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OSCILLATION THEOREMS OF COMPARISON TYPE OF DELAY DIFFERENTIAL EQUATIONS WITH A NONLINEAR DAMPING TERM

S. R. GRACE

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ABSTRACT. In this paper, we study the oscillatory behaviour of the solutions of delay differential equations of the form

$$\frac{d}{dt} \frac{1}{a_{n-1}(t)} \frac{d}{dt} \cdots \frac{d}{dt} \frac{1}{a_1(t)} \frac{d}{dt} x(t) + f(t, x(t-g), \frac{d}{dt} x(t-h)) = 0, \quad n \text{ is even}$$

by comparing with certain differential equations of the same or lower order whose oscillatory character is known. The obtained results can be applied to the delay differential equation

$$\begin{aligned} & \frac{d}{dt} \frac{1}{a_{n-1}(t)} \cdots \frac{d}{dt} \frac{1}{a_1(t)} \frac{d}{dt} x(t) \\ & + q(t) (|x(t-g)|^{m_1}) \left(\left| \frac{d}{dt} x(t-h) \right|^{m_2} \right) \operatorname{sgn} x(t-g) = 0, \end{aligned}$$

where m_1 and m_2 are positive constants.

1. Introduction

We consider the functional differential equation

$$L_n x(t) + f(t, x(t-g), \dot{x}(t-h)) = 0, \quad n \text{ is even, } \left(' = \frac{d}{dt} \right), \quad (\text{E})$$

where $L_0 x(t) = x(t)$, $L_k x(t) = \frac{1}{a_k(t)} (L_{k-1} x(t))'$, $k = 1, 2, \dots, n$, $a_n = 1$, $a_i: [t_0, \infty) \rightarrow (0, \infty)$, $i = 1, 2, \dots, n-1$, $f: [t_0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R} = (-\infty, \infty)$ are continuous, g and h are positive constants and $h \geq g$. We assume that:

$$(1) \quad \int_{t_0}^{\infty} a_i(s) ds = \infty, \quad i = 1, 2, \dots, n-1,$$

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- (2) there exist a continuous function $q: [t_0, \infty) \rightarrow (0, \infty)$ and real constants m_1 and m_2 , $m_1 > 0$ and $m_2 \geq 0$ such that

$$f(t, x_1, x_2) \operatorname{sgn} x_1 \geq q(t)(|x_1|^{m_1})(|x_2|^{m_2}) \quad \text{for } x_1 \neq 0.$$

The oscillatory behaviour of functional differential equations has been intensively studied in recent years. Most of the literature on this subject has been concerned with equations of type (E) and/or related equations, specially when f satisfies condition (2) with $m_2 = 0$, see [1], [5], [7] and [8], and the references cited therein. It seems that very little is known regarding the oscillation of equation (E) when f satisfies condition (2) with $m_2 \neq 0$, see [2]; [4], [10] and [12], and the references cited therein. In this paper, we proceed further in this direction to establish some new oscillation results for equation (E). Theorems 1 and 2 are concerned with the oscillation of equation (E) via comparison with the oscillatory behaviour of two equations of order n and $n - 1$, and in Theorem 3, we reduce the problem of the oscillation of equation (E) to the problem of the oscillation of a certain set of first order equations and the oscillation of all bounded solutions of certain retarded equation of order $n - 1$.

The *domain* of $L_n D(L_n)$ is defined to be the set of functions $x: [T_x, \infty) \rightarrow \mathbb{R}$ such that $L_j x(t)$, $j = 0, 1, \dots, n$, exist and are continuous on $[T_x, \infty)$, $T_x \geq t_0$. In what follows, we consider only the "nonconstant" solutions in $D(L_n)$, of equation (E). A *solution* of equation (E) is called *oscillatory* if it has arbitrary large zeros, otherwise, it is called *nonoscillatory*. Equation (E) is said to be *oscillatory* if all its solutions are oscillatory.

2. Main results

We begin by formulating preparatory results which are needed in proving our main results.

For functions $p_i: [t_0, \infty) \rightarrow \mathbb{R}$, $i = 1, 2, \dots$, we define

$$I_0 = 1,$$

$$I_i(t, s; p_i, \dots, p_1) = \int_s^t p_i(u) I_{i-1}(u, s; p_{i-1}, \dots, p_1) du, \quad i = 1, 2, \dots$$

It is easy to verify that for $i = 1, 2, \dots, n - 1$

$$I_i(t, s; p_1, \dots, p_i) = (-1)^i I_i(s, t; p_i, \dots, p_1)$$

and

$$I_i(t, s; p_1, \dots, p_i) = \int_s^t p_i(u) I_{i-1}(t, u; p_1, \dots, p_{i-1}) du.$$

The following two lemmas will be needed in the proofs of the main results.

LEMMA 1. *If $x \in D(L_n)$, then for $t, s \in [t_0, \infty)$ and $0 \leq i < k \leq n$*

$$\begin{aligned}
 \text{(i)} \quad L_i x(t) &= \sum_{j=i}^{k-1} I_{j-i}(t, s; a_{i+1}, \dots, a_j) L_j(s) \\
 &\quad + \int_s^t I_{k-i-1}(t, u; a_{i+1}, \dots, a_{k-1}) a_k(u) L_k x(u) \, du. \\
 \text{(ii)} \quad L_i x(t) &= \sum_{j=i}^{k-1} (-i)^{j-i} I_{j-i}(s, t; a_j, \dots, a_{i+1}) L_j x(s) \\
 &\quad + (-1)^{k-i} \int_t^s I_{k-i-1}(u, t; a_{k-1}, \dots, a_{i+1}) a_k(u) L_k(u) \, du.
 \end{aligned}$$

This lemma is a generalization of Taylor's formula with remainder encountered in calculus. The proof is immediate.

LEMMA 2. *Suppose conditions (1) and (2) hold. If $x \in D(L_n)$ is of constant sign and is not identically zero for all large t , then there exist a $t_x \geq t_0$ and an integer m , $0 \leq m \leq n$, with $n+m$ even for $x(t)L_n x(t)$ nonnegative, or $n+m$ odd for $x(t)L_n x(t)$ nonpositive, and such for every $t \geq t_x$*

$$m > 0 \quad \text{implies} \quad x(t)L_k x(t) > 0 \quad (k = 1, 2, \dots, m),$$

and

$$m \leq n-1 \quad \text{implies} \quad (-1)^{m-k} x(t)L_k x(t) > 0 \quad (k = m, m+1, \dots, n).$$

This lemma generalizes a well-known lemma of Kiguradze (see [6]) and can be proved similarly.

Next, for $t \geq T \geq t_0$, we put

$$\begin{aligned}
 A_{j,i}[t, T] &= \int_T^t I_{i-j}(t, s; a_j, \dots, a_{i-1}) a_i(s) I_{n-i-1}(t, s; a_{n-1}, \dots, a_{i+1}) \, ds \\
 &\quad \text{for } i \geq j, \quad c = 1, 2 \quad \text{and } i = 1, 2, \dots, n-1,
 \end{aligned}$$

and

$$R[t, T] = \int_T^t a_1(s) \, ds.$$

In the following theorem, we give a sufficient condition for the oscillation of the damped equation (E) via comparison with undamped equations of the form

$$L_n x(t) + c_1 (a_1(t-h))^{m_2} q(t) (|x(t-g)|^{m_1}) \operatorname{sgn} x(t-g) = 0 \quad (\text{E}_1)$$

and

$$M_m y(t) + c_2 (a_1(t-h))^{m_2} q(t) (|y(t-h)|^{m_2}) \operatorname{sgn} y(t-h) = 0, \quad (\text{E}_2)$$

where $M_0 = y(t)$, $M_k y(t) = \frac{1}{b_k(t)} (M_{k-1} y(t))'$, $k = 1, 2, \dots, m$; $m = n - 1$. $b_k(t) = a_{k+1}(t)$, $k = 1, 2, \dots, n - 1$ and c_1 and c_2 are positive constants.

THEOREM 1. *Let conditions (1) and (2) hold. If for every $c_1 > 0$, equation (E₁) is oscillatory, and for every $c_2 > 0$, every bounded solution of equation (E₂) is oscillatory, then equation (E) is oscillatory.*

Proof. Let $x(t)$ be a nonoscillatory solution of equation (E). Assume $x(t) > 0$ and $x(t-g) > 0$ for $t \geq t_0$.

By Lemma 2, there exist a $t_1 \geq t_0$ and an integer $N \in \{1, 3, \dots, n-1\}$ such that

$$\begin{aligned} L_k x(t) &> 0 && \text{for } t \geq t_1, \quad (k = 1, 2, \dots, N), \\ (-1)^{N-k} L_k x(t) &> 0 && \text{for } t \geq t_1, \quad (k = N, N+1, \dots, n). \end{aligned} \quad (3)$$

Suppose that $N > 1$. From (3), we see that $L_1 x(t)$ is positive and increasing for $t \geq t_1$. There exist a $t_2 \geq t_1$ and a constant $A > 0$ such that

$$\dot{x}(t-h) \geq A a_1(t-h) \quad \text{for } t \geq t_2. \quad (4)$$

Using (2) and (4) in equation (E), we get

$$L_n x(t) + A^{m_2} (a_1(t-h))^{m_2} q(t) (|x(t-g)|)^{m_1} \operatorname{sgn} x(t-g) \leq 0 \quad \text{for } t \geq t_2.$$

But, in view of [3] and [8], it follows that the equation

$$L_n x(t) + A^{m_2} (a_1(t-h))^{m_2} q(t) (|x(t-g)|)^{m_1} \operatorname{sgn} x(t-g) = 0 \quad \text{for } t \geq t_2$$

has a positive nonoscillatory solution, a contradiction.

Next, let $N = 1$. Since $x(t)$ is an increasing function for $t \geq t_1$, there exist a $t_3 \geq t_1$ and a constant $B > 0$ so that

$$x(t-g) \geq B \quad \text{for } t \geq t_3. \quad (5)$$

Using (2) and (5) in equation (E) we get

$$L_n x(t) + B^{m_1} q(t) (x'(t-h))^{m_2} \leq 0 \quad \text{for } t \geq t_3,$$

or

$$L_n x(t) + B^{m_1} q(t) (a_1(t-h))^{m_2} (L_1 x(t-h))^{m_2} \leq 0 \quad \text{for } t \geq t_3.$$

Setting $y(t) = L_1 x(t)$, $t \geq t_3$, we have

$$M_m y(t) + B^{m_1} q(t) (a_1(t-h))^{m_2} (y(t-h))^{m_2} \leq 0.$$

Clearly, $y(t)$ is a positive and decreasing function for $t \geq t_3$. Applying [11; Corollary 1'], we see that the equation

$$M_m y(t) + B^{m_1} q(t) (a_1(t-h))^{m_2} (y(t-h))^{m_2} \leq 0, \quad \text{for } t \geq t_3$$

has a bounded, eventually positive and decreasing solution, a contradiction. This completes the proof.

In the following result, we replace equation (E₂) in Theorem 1 by the equation

$$M_m w(t) + (a_1(t-h))^{m_2} (R[t-g, T])^{m_1} q(t) (|w(t-g)|^{m_1+m_2}) \operatorname{sgn} w(t-g) = 0, \tag{E_3}$$

where M_m is defined as in equation (E₃).

THEOREM 2. *Let conditions (1) and (2) hold. If, for all $c_1 > 0$, the equation (E₁) is oscillatory and for all large T with $t > T + g$ all bounded solution of equation (E₃) are oscillatory, then equation (E) is oscillatory.*

Proof. Let $x(t)$ be a nonoscillatory solution of equation (E), say $x(t) > 0$ and $x(t-g) > 0$ for $t \geq t_0$. As in the proof of Theorem 1, there exist a $t_1 \geq t_0$ and an integer $N \in \{1, 3, \dots, n-1\}$ such that (3) holds. Next, we consider the two cases: $N > 1$ and $N = 1$. The proof of the first case is similar to that of Theorem 1 and hence is omitted. Now, we consider the case $N = 1$. From (3) we see that the function $L_1 x$ is decreasing on $[t_1, \infty)$. Next, for $t \geq t_1$ we have

$$\begin{aligned} x(t) - x(t_1) &= \int_{t_1}^t \frac{a_1(s)}{a_1(s)} x'(s) \, ds \\ &= \left(\int_{t_1}^t a_1(s) \, ds \right) L_1 x(t) - \int_{t_1}^t \left(a_2(s) \int_{t_1}^s a_1(u) \, du \right) L_2 x(s) \, ds \\ &\geq R[t, t_1] L_1 x(t) \quad \text{for } t \geq t_1. \end{aligned}$$

There exists a $t_2 \geq t_1$ so that

$$x(t - g) \geq R[t - g, t_1]L_1x(t - g) \quad \text{for } t \geq t_2. \tag{6}$$

Using (6) in equation (E) and the fact that $L_1x(t)$ is a decreasing function on $[t_1, \infty)$ and $h > g$, we obtain

$$L_nx(t) + (R[t - g, t_1])^{m_1}(a_1(t - h))^{m_2}(L_1x(t - g))^{m_1+m_2} \leq 0 \quad \text{for } t \geq t_2.$$

Next, we set $v(t) = L_1x(t)$, $t \geq t_2$; we get

$$M_mv(t) + (R[t - g, t_1])^{m_1}(a_1(t - h))^{m_2}(v(t - g))^{m_1+m_2} \leq 0.$$

The rest of the proof is similar to that of Theorem 1 (the case $N = 1$) and hence is omitted.

In the following theorem, we replace equation (E₁) by a set of first order equations

$$\dot{y}(t) + Q_i[t, T](|y(t - g)|^{m_1+m_2}) \operatorname{sgn} y(t - g) = 0, \quad T \text{ is large,} \quad (\text{E}_4; i)$$

where $Q_i[t, T] = (a_1(t - h))^{m_2}(A_{1,i}[t - g, T])^{m_1}(A_{2,i}[t - h, T])^{m_2}$, $i = 3, 5, \dots, \dots, n - 1$, and obtain the following oscillation criterion for equation (E).

THEOREM 3. *Let conditions (1) and (2) hold. If for all large T with $t \geq T + g$, the equations (E₄; i), $i = 3, 5, \dots, n - 1$ are oscillatory and all bounded solutions of equation (E₃) (or equation (E₂), $c_2 > 0$) are oscillatory, then equation (E) is oscillatory.*

PROOF. Let $x(t)$ be a nonoscillatory solution of equation (E), say $x(t) > 0$ and $x(t - g) > 0$ for $t \geq t_0$. As in the proof of Theorem 1, there exist a $t_1 \geq t_0$ and an integer $N \in \{1, 3, \dots, n - 1\}$ so that (3) holds. We consider the two cases: $N = 1$ and $N > 1$. The proof of the case $N = 1$ is similar to that of Theorem 1 (or Theorem 2) and hence is omitted. Next, we consider the case $N > 1$. From Lemma 1 (ii), we get

$$L_Nx(s) = \sum_{j=N}^{n-2} (-1)^{j-N} I_{j-N}(t, s; a_j, \dots, a_{N+1}) L_jx(t) \cdot (-1)^{n-N-1} \int_s^t I_{n-N-2}(u, s; a_{n-2}, \dots, a_{N+1}) a_{n-1}(u) L_{n-1}x(u) \, du$$

for $t \geq s \geq t_1$.

Using (3) and the fact that $L_{n-1}x$ is decreasing function on $[t_1, \infty)$, we obtain

$$L_N x(s) \geq \left(\int_s^t T_{n-N-2}(u, s; a_{n-2}, \dots, a_{N+1}) a_{n-1}(u) \, du \right) L_{n-1} x(t)$$

or

$$L_N x(s) \geq I_{n-N-1}(t, s; a_{n-1}, \dots, a_{N+1}) L_{n-1} x(t), \quad t \geq s \geq t_1. \quad (7)$$

On the other hand, from Lemma 1 (i), we have

$$\begin{aligned} x(t) &= \sum_{j=0}^{N-1} I_j(t, t_1; a_1, \dots, a_j) L_j x(t_1) \\ &\quad + \int_{t_1}^t I_{N-1}(t, s; a_1, \dots, a_{N-1}) a_N(s) L_N x(s) \, ds \end{aligned}$$

or

$$x(t) \geq \int_{t_1}^t I_{N-1}(t, s; a_1, \dots, a_{N-1}) a_N(s) L_N x(s) \, ds, \quad t \geq t_1. \quad (8)$$

Combining (7) and (8) we get

$$x(t) \geq A_{1,N}[t, t_1] L_{n-1} x(t) \quad \text{for } t \geq t_1.$$

Also, from Lemma 1 (i), we have

$$\begin{aligned} \dot{x}(t) &= \left[\sum_{j=1}^{N-1} I_{j-1}(t, t_1; a_2, \dots, a_j) L_j x(t_1) \right. \\ &\quad \left. + \int_{t_1}^t I_{N-2}(t, s; a_2, \dots, a_{N-1}) a_N(s) L_N x(s) \, ds \right] a_1(t) \end{aligned}$$

or

$$\dot{x}(t) \geq a_1(t) \int_{t_1}^t I_{N-2}(t, s; a_2, \dots, a_{N-1}) a_N(s) L_N x(s) \, ds. \quad (9)$$

Combining (7) and (9) we obtain

$$\dot{x}(t) \geq a_1(t)A_{2,N}[t, t_1]L_{n-1}x(t) \quad \text{for } t \geq t_1.$$

There exists a $t_2 \geq t_1$ so that

$$x(t-g) \geq A_{1,N}[t-g, t_1]L_{n-1}x(t-g) \quad \text{for } t \geq t_2 \tag{10}$$

and

$$\dot{x}(t-h) \geq a_1(t-h)A_{2,N}[t-h, t_1]L_{n-1}x(t-h) \quad \text{for } t \geq t_2.$$

Using the fact that $L_{n-1}x$ is a decreasing function on $[t_1, \infty)$ and $h > g$, we have

$$\dot{x}(t-h) \geq a_1(t-h)A_{2,N}[t-h, t_1]L_{n-1}x(t-g) \quad \text{for } t \geq t_2. \tag{11}$$

Now, using (10) and (11) in equation (E), we get

$$\begin{aligned} L_n x(t) &= -f(t, x(t-g), \dot{x}(t-h)) \\ &\leq -q(t)(x(t-g))^{m_1}(\dot{x}(t-h))^{m_2} \\ &\leq -q(t)(A_{1,N}[t-g, t_1])^{m_1}(a_1(t-h))^{m_2} \\ &\quad \cdot (A_{2,N}[t-h, t_1])^{m_2}(L_{n-1}x(t-g))^{m_1+m_2} \quad \text{for } t \geq t_2. \end{aligned}$$

Setting $y(t) = L_{n-1}x(t)$ yields

$$\begin{aligned} \dot{y}(t) + q(t)(a_1(t-h))^{m_2}(A_{1,N}[t-g, t_1])^{m_1}(A_{2,N}[t-h, t_1])^{m_2} \\ \cdot (y(t-g))^{m_1+m_2} \leq 0 \quad \text{for } t \geq t_2. \end{aligned}$$

But in view of [11; Corollary 1], each of the equations $(E_4; N)$, $N = 3, 5, \dots, n-1$, has an eventually positive and decreasing solution, which is a contradiction. This completes the proof.

The following results are immediate consequences of Theorem 3. The Corollaries below follow readily from results in [1], [7] and [9].

For all large $T \geq t_0$ with $t \geq T + g$, we put

$$Q_1[t, T] = (a_1(t-h))^{m_2}(R[t-g, T])^{m_1}q(t).$$

COROLLARY 1. *Let conditions (1) and (2) hold and $m_1 + m_2 < 1$. Moreover, suppose that for all large T with $t > T + g$*

$$\int Q_N[s, T] ds = \infty, \quad \text{for } N = 3, 5, \dots, n - 1, \quad (12; N)$$

and

$$\liminf_{t \rightarrow \infty} \int_{t-g}^t I_{n-2}(s, s - g; a_{n-1}, \dots, a_2) Q_1[s, T] ds > 0. \quad (13)$$

Then equation (E) is oscillatory.

COROLLARY 2. *Let conditions (1) and (2) hold and $m_1 + m_2 = 1$. In addition, we assume that for all large T with $t > T + g$*

$$\liminf_{t \rightarrow \infty} \int_{t-g}^t Q_N[s, T] ds > \frac{1}{e} \quad \text{for } N = 3, 5, \dots, n - 1, \quad (14; N)$$

and for some $i = 0, 1, \dots, n - 2$

$$\limsup_{t \rightarrow \infty} \int_{t-g}^t I_{n-i-2}(s, t - g; a_{n-1}, \dots, a_{i+2}) I_i(t - g, s - g; a_{i+1}, \dots, a_2) \cdot Q_1[s, T] ds > 1. \quad (15)$$

Then equation (E) is oscillatory.

Remark 1. From the known oscillation criteria for undamped equations of type (E) (i.e., equation (E) with $m_2 = 0$) in [1] and [7] and the references cited therein, we see that Theorem 1 applies to equation (E) with $m_1 > 0$ and $0 \leq m_2 \leq 1$ while Theorems 2 and 3 are applicable to (E) with $0 < m_1 + m_2 \leq 1$.

The following example is illustrative:

Example 1. Consider the fourth order differential equation

$$\left(\frac{1}{t} \left(\frac{1}{t} \left(\frac{1}{t} x'(t) \right)' \right)' \right)' + \frac{231}{16} t^{-13/2} (2(t - h)^{1/2})^{m_4} (t - g)^{-m_3/2} \cdot (|x(t - g)|^{m_1}) (|x'(t - h)|^{m_2}) \operatorname{sgn} x(t - h) = 0, \quad t > g, \quad (E_5)$$

where $g, h, m_j, j = 1, 2, 3, 4$ are real constants, $m_1 > 0, m_2 \geq 0$ and $g \geq h \geq 0$. It is easy to check the following:

- (i) when $m_2 = 0, m_4 - m_3 > 3$ and $m_1 \geq 1$, equation (E₅) is oscillatory by [1; Theorems 2 and 4] and [7; Theorems 3.2 and 5.1];
- (ii) when $m_2 > 0$ and $\frac{1}{4}(13 - m_4 + m_3 + 2m_2) \leq m_1 + m_2 \leq 1$, equation (E₅) is oscillatory by Theorems 2 and 3;
- (iii) when $m_2 = m_4 \geq 0$ and $m_1 = m_3 > 0$, equation (E₅) has a nonoscillatory solution $x(t) = t^{1/2}$.

Thus, we conclude that the damping term which appeared in equation (E₅) (i.e., equation (E₅) with $m_2 \neq 0$) plays important role in preserving or disrupting the oscillatory character of undamped equation (E₅) (i.e., equation (E₅) with $m_2 = 0$).

Theorems 1-3 applied to the special equation

$$\left(\frac{1}{a_1(t)} x'(t)\right)' + f(t, x(t-g), x'(t-h)) = 0 \tag{E_6}$$

(i.e., equation (E) with $n = 2$) yields the following corollary.

COROLLARY 3. *Let conditions (1) and (2) hold. If for all large T every bounded solution of the equation*

$$y'(t) + Q_1[t, T](|y(t-g)|^{m_1+m_2}) \operatorname{sgn} y(t-g) = 0 \tag{E_7}$$

is oscillatory, or for all large T and every $c > 0$, all bounded solutions of the equation

$$v'(t) + c(a_1(t-h))^{m_2} q(t)(|v(t-h)|^{m_2}) \operatorname{sgn} v(t-h) = 0. \tag{E_8}$$

are oscillatory, then equation (E₆) is oscillatory.

Remark 2. In view of Corollaries 1 and 2, one can easily see that Corollary 3 is an extension of our results in [4] and some of the results in [12].

Remark 3. From the proof of Theorem 3, we see that Theorem 3 remains valid when the constant m_2 in condition (2) is identically zero, i.e., f satisfies

$$f(t, x_1, x_2) \operatorname{sgn} x_1 \geq q(t)|x_1|^{m_1}, \quad m_1 > 0 \quad \text{and} \quad x_1 \neq 0, \tag{16}$$

where q is defined as in condition (2).

In this case, we establish a criterion for the oscillation of equation (E₆) which improves our earlier result in [5].

Now, we state this result by noting that for $t > T$

$$C_1(t, T) = (A_{1,2}(t-g, T))^{m_1} q(t-g), \quad t \in [T, \infty),$$

THEOREM 4. *Let conditions (1) and (16) hold. If for all large T and $N = 1, 3, \dots, n-1$, the equations*

$$y'(t) + C_i[t, T](|y(t-g)|^{m_1}) \operatorname{sgn} y(t-g) = 0 \quad (17; N)$$

are oscillatory, then equation (E) is oscillatory.

PROOF. It follows from the proof of Theorem 3, and hence is omitted.

Theorems 1-3 seems to be new even when specialized to the equation

$$x^{(n)}(t) + f(t, x(t-g), x'(t-h)) = 0, \quad n \text{ is even,} \quad (E_9)$$

for which condition (2) is satisfied. So, we state them below as corollaries by noting that in this case for $t \geq s$

$$I_{n-1}(t, s; a_1, \dots, a_{n-1}) = I_{n-1}(t, s; a_{n-1}, \dots, a_1) = \frac{(t-s)^{n-1}}{(n-1)!}.$$

Next, for all large T , p_i , $0 < p_i < 1$, $i = 1, 3, \dots, n-1$ such that

$$\begin{aligned} Q_1[t, p_1] &= p_1 t^{m_1} q(t), \\ Q_i[t, p_i] &= p_i K_i t^B q(t), \end{aligned}$$

where

$$B = (n-1)m_1 + (n-2)m_2,$$

and

$$K_i = \frac{1}{(n-1)^{m_1} (n-2)^{m_2} ((i-1)!)^{m_1} ((i-2)!)^{m_2} ((n-i-1)!)^{m_1+m_2}}.$$

COROLLARY 4. *Suppose that condition (2) holds. If for every p_i , $0 < p_i < 1$, $i = 1, 3, \dots, n-1$, the equations*

$$y'(t) + Q_i[t, p_i](|y(t-g)|^{m_1+m_2}) \operatorname{sgn} y(t-g) = 0, \quad \text{for } i = 3, 5, \dots, n-1, \quad (18; N)$$

are oscillatory and every bounded solution of either

$$w^{(n-1)} + Q_1[t, p_1](|w(t-g)|^{m_1+m_2}) \operatorname{sgn} w(t-g) = 0 \quad (19)$$

or

$$v^{(n-1)}(t) + cq(t)(|v(t-h)|^{m_2}) \operatorname{sgn} v(t-h) = 0, \quad \text{for every } c > 0. \quad (20)$$

is oscillatory, then equation (E₉) is oscillatory.

REMARK 1. One can draw more corollaries from Theorems 1-4, similar to those given above. Here we omit the details.

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