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## Michel Eleuteri

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# REGULARITY RESULTS FOR A CLASS OF OBSTACLE PROBLEMS* 

Michela Eleuteri, Berlin

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Abstract. We prove some optimal regularity results for minimizers of the integral functional $\int f(x, u, D u) \mathrm{d} x$ belonging to the class $K:=\left\{u \in W^{1, p}(\Omega): u \geqslant \psi\right\}$, where $\psi$ is a fixed function, under standard growth conditions of $p$-type, i.e.

$$
L^{-1}|z|^{p} \leqslant f(x, s, z) \leqslant L\left(1+|z|^{p}\right)
$$

Keywords: regularity results, local minimizers, integral functionals, obstacle problems, standard growth conditions

MSC 2000: 49N60, 35J85, 49J40

## 1. Introduction

The aim of this paper is the study of regularity properties of local minimizers of integral functionals of the type

$$
\begin{equation*}
\mathcal{F}(u, \Omega):=\int_{\Omega} f(x, u(x), D u(x)) \mathrm{d} x \tag{1.1}
\end{equation*}
$$

in the class $K:=\left\{u \in W^{1, p}(\Omega, \mathbb{R}): u \geqslant \psi\right\}$, where $\psi$ is a fixed obstacle function, $\Omega$ is a bounded open set of $\mathbb{R}^{n}, f: \Omega \times \mathbb{R} \times \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a Carathéodory function and $u \in W_{\text {loc }}^{1,1}(\Omega, \mathbb{R})$. The assumptions we are going to consider here are weaker than those usually employed in literature in that we are not assuming that the functional considered in (1.1) admits an Euler equation, in particular we shall assume that the Lagrangian $f$ is convex in the gradient variable in a suitably strong way, see (H2),

[^0]and not necessarily twice differentiable. Such assumptions have been considered since the innovative paper of Fonseca and Fusco [11], where Lipschitz regularity results have been achieved for unconstrained local minimizers. Subsequently these results have been extended in [4], [5], [12] as far as standard functionals are considered and in [1], [8], [9] as far as the vectorial case and non-standard growth conditions are considered.

In this paper we extend the treatment of such functionals to the case of onesided obstacle problems, providing sharp regularity results in the setting of Hölder and Morrey spaces. In particular, our results seem to be new in the standard case; indeed, they extend in a sharp way those obtained by Choe [2], where regularity in Morrey spaces is considered. This is made possible via a more careful estimation using a suitable freezing techniques. The lack of smoothness of the energy density is overcome by the use of Ekeland's variational principle, a tool that revealed to be crucial in regularity since the paper [13].

The results of this paper can be used to prove regularity theorems for obstacle problems under non standard growth conditions, see e.g. [3].

## 2. Notation and statements

In the sequel $\Omega$ will denote a bounded open set in $\mathbb{R}^{n}$ and $B(x, R)$ the open ball $\left\{y \in \mathbb{R}^{n}:|x-y|<R\right\}$. As we are analysing the regularity properties of minimizers inside $\Omega$, it is not restrictive to assume $\Omega$ to be smooth.

If $u$ is an integrable function defined on $B(x, R)$, we will set

$$
(u)_{x, R}=f_{B(x, R)} u(x) d x=\frac{1}{\omega_{n} R^{n}} \int_{B(x, R)} u(x) \mathrm{d} x
$$

where $\omega_{n}$ is the Lebesgue measure of $B(0,1)$. We shall also adopt the convention of writing $B_{R}$ and $(u)_{R}$ instead of $B(x, R)$ and $(u)_{x, R}$ respectively, provided the center is not relevant or is clear from the context; moreover, unless otherwise stated, all balls considered will have the same center. Finally, the letter $c$ will freely denote a constant, not necessarily the same in any two occurrences, while only the relevant dependences will be highlighted.

The Carathéodory function $f: \Omega \times \mathbb{R} \times \mathbb{R}^{n} \rightarrow \mathbb{R}$ is supposed to satisfy a growth condition of the type

$$
L^{-1}|z|^{p} \leqslant f(x, u, z) \leqslant L\left(1+|z|^{p}\right)
$$

for all $x \in \Omega, u \in \mathbb{R}, z \in \mathbb{R}^{n}$, where $p>1$ and $L \geqslant 1$. Next, we set

$$
\begin{gather*}
\varsigma(x):=|D \psi(x)|^{p}  \tag{2.1}\\
\mathcal{F}(u, \mathcal{A}):=\int_{\mathcal{A}} f(x, u(x), D u(x)) \mathrm{d} x
\end{gather*}
$$

$$
\begin{align*}
\mathcal{F}_{\psi}(u, \mathcal{A}) & :=\int_{\mathcal{A}} h_{\psi}(x, u(x), D u(x)) \mathrm{d} x  \tag{2.2}\\
& :=\int_{\mathcal{A}}[f(x, u(x), D u(x))+\varsigma(x)] \mathrm{d} x
\end{align*}
$$

for all $u \in W_{\text {loc }}^{1,1}(\Omega)$ and for all $\mathcal{A} \subset \Omega$, where $\psi \in W^{1, p}(\Omega)$ is a fixed function.
With this type of standard growth, we adopt the following notion of local minimizer and local $Q$-minimizer.

Definition 2.1. We say that a function $u \in W_{\mathrm{loc}}^{1,1}(\Omega)$ is a local minimizer of the functional $\mathcal{F}$ if $|D u(x)|^{p} \in L_{\mathrm{loc}}^{1}(\Omega)$ and

$$
\int_{\operatorname{supp} \varphi} f(x, u(x), D u(x)) \mathrm{d} x \leqslant \int_{\operatorname{supp} \varphi} f(x, u(x)+\varphi(x), D u(x)+D \varphi(x)) \mathrm{d} x
$$

for all $\varphi \in W_{0}^{1,1}(\Omega)$ with compact support in $\Omega$.
Definition 2.2. We say that a function $u \in W_{\text {loc }}^{1,1}(\Omega)$ is a local $Q$-minimizer of the functional $\mathcal{F}$ with $Q \geqslant 1$ if for all $v \in W_{\text {loc }}^{1,1}(\Omega)$ such that $H:=\operatorname{supp}(u-v) \subset \subset \Omega$, we have

$$
\mathcal{F}(u, H) \leqslant Q \mathcal{F}(v, H)
$$

We shall consider the following growth, ellipticity and continuity conditions:

$$
\begin{equation*}
L^{-1}\left(\mu^{2}+|z|^{2}\right)^{p / 2} \leqslant f(x, u, z) \leqslant L\left(\mu^{2}+|z|^{2}\right)^{p / 2} \tag{H1}
\end{equation*}
$$

$$
\begin{align*}
& \int_{Q_{1}}\left[f\left(x_{0}, u_{0}, z_{0}+D \varphi(x)\right)-f\left(x_{0}, u_{0}, z_{0}\right)\right] \mathrm{d} x  \tag{H2}\\
& \quad \geqslant L^{-1} \int_{Q_{1}}\left(\mu^{2}+\left|z_{0}\right|^{2}+|D \varphi(x)|^{2}\right)^{(p-2) / 2}|D \varphi(x)|^{2} \mathrm{~d} x
\end{align*}
$$

for some $0 \leqslant \mu \leqslant 1$, for all $z_{0} \in \mathbb{R}^{n}, u_{0} \in \mathbb{R}, x_{0} \in \Omega, \varphi \in \mathcal{C}_{0}^{\infty}\left(Q_{1}\right)$, where $Q_{1}=(0,1)^{n}$,

$$
\begin{equation*}
\left|f(x, u, z)-f\left(x_{0}, u_{0}, z\right)\right| \leqslant L \omega\left(\left|x-x_{0}\right|+\left|u-u_{0}\right|\right)\left(\mu^{2}+|z|^{2}\right)^{p / 2} \tag{H3}
\end{equation*}
$$

for all $z \in \mathbb{R}^{n}, u, u_{0} \in \mathbb{R}, x, x_{0} \in \Omega$, where $L \geqslant 1$. Here $\omega: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is a continuous, nondecreasing function, vanishing at zero; we also suppose, without loss of generality, that $\omega$ is a concave, bounded and, hence, subadditive function. Let us set

$$
K:=\left\{u \in W^{1, p}(\Omega): u \geqslant \psi\right\} .
$$

Now we recall the definition of Morrey and Campanato spaces (see for example [16]).

Definition 2.3 (Morrey spaces). Let $\Omega$ be an open and bounded subset of $\mathbb{R}^{n}$, let $1 \leqslant p<+\infty$ and $\lambda \geqslant 0$. By $L^{p, \lambda}(\Omega)$ we denote the linear space of functions $u \in L^{p}(\Omega)$ such that, if we set $\Omega\left(x_{0}, \varrho\right):=\Omega \cap B\left(x_{0}, \varrho\right)$, we get

$$
\|u\|_{L^{p, \lambda}(\Omega)}:=\left\{\sup _{x_{0} \in \Omega, 0<\varrho<\operatorname{diam}(\Omega)} \varrho^{-\lambda} \int_{\Omega\left(x_{0}, \varrho\right)}|u(x)|^{p} \mathrm{~d} x\right\}^{1 / p}<+\infty .
$$

It is easy to see that $\|u\|_{L^{p, \lambda}(\Omega)}$ is a norm with respect to which $L^{p, \lambda}(\Omega)$ is a Banach space.

Definition 2.4 (Campanato spaces). Let $\Omega$ be an open and bounded subset of $\mathbb{R}^{n}$, let $p \geqslant 1$ and $\lambda \geqslant 0$. By $\mathcal{L}^{p, \lambda}(\Omega)$ we denote the linear space of functions $u \in L^{p}(\Omega)$ such that, if we set $\Omega\left(x_{0}, \varrho\right):=\Omega \cap B\left(x_{0}, \varrho\right)$, we get

$$
[u]_{p, \lambda}=\left\{\sup _{x_{0} \in \Omega, 0<\varrho<\operatorname{diam}(\Omega)} \varrho^{-\lambda} \int_{\Omega\left(x_{0}, \varrho\right)}\left|u(x)-(u)_{x_{0}, \varrho}\right|^{p} \mathrm{~d} x\right\}^{1 / p}<+\infty,
$$

where

$$
(u)_{x_{0}, \varrho}:=\frac{1}{\left|\Omega\left(x_{0}, \varrho\right)\right|} \int_{\Omega\left(x_{0}, \varrho\right)} u(x) \mathrm{d} x
$$

is the average of $u$ in $\Omega\left(x_{0}, \varrho\right)$.
Also in this case it is not difficult to show that $\mathcal{L}^{p, \lambda}(\Omega)$ is a Banach space equipped with the norm

$$
\|u\|_{\mathcal{L}^{p, \lambda}(\Omega)}=\|u\|_{L^{p}(\Omega)}+[u]_{p, \lambda} .
$$

Remark 2.5. The local variants $L_{\text {loc }}^{p, \lambda}(\Omega)$ and $\mathcal{L}_{\text {loc }}^{p, \lambda}(\Omega)$ are defined in a standard way:

$$
\begin{array}{ll}
u \in L_{\operatorname{loc}}^{p, \lambda}(\Omega) \Leftrightarrow u \in L^{p, \lambda}\left(\Omega^{\prime}\right) & \forall \Omega^{\prime} \subset \subset \Omega \\
u \in \mathcal{L}_{\operatorname{loc}}^{p, \lambda}(\Omega) \Leftrightarrow u \in \mathcal{L}^{p, \lambda}\left(\Omega^{\prime}\right) & \forall \Omega^{\prime} \subset \subset \Omega
\end{array}
$$

The interest of Campanato spaces lies mainly in the following result which will be used in the next sections. It can be found in [16, Section 2.3].

Theorem 2.6. Let $\Omega$ be a bounded open set without internal cusps, and let $n<$ $\lambda<n+p$. Then the space $\mathcal{L}^{p, \lambda}(\Omega)$ is isomorphic to $\mathcal{C}^{0, \alpha}(\bar{\Omega})$ with $\alpha=(\lambda-n) / p$. We also remark that, using Poincaré inequality, we have that, for a weakly differentiable function $v$, if $D v \in L^{p, \lambda}(\Omega)$, then $v \in \mathcal{L}^{p, p+\lambda}(\Omega)$.

The first result we are able to obtain is for local minimizers in $K$ of the functional

$$
\begin{equation*}
\mathcal{G}_{0}\left(w, B_{R}\right)=\int_{B_{R}} g(D w(x)) \mathrm{d} x \tag{2.3}
\end{equation*}
$$

where $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a continuous function fulfilling the following growth and ellipticity conditions:

$$
\begin{equation*}
L^{-1}\left(\mu^{2}+|z|^{2}\right)^{p / 2} \leqslant g(z) \leqslant L\left(\mu^{2}+|z|^{2}\right)^{p / 2} \tag{H4}
\end{equation*}
$$

$$
\begin{align*}
& \int_{Q_{1}}\left[g\left(z_{0}+D \varphi(x)\right)-g\left(z_{0}\right)\right] \mathrm{d} x  \tag{H5}\\
& \quad \geqslant L^{-1} \int_{Q_{1}}\left(\mu^{2}+\left|z_{0}\right|^{2}+|D \varphi(x)|^{2}\right)^{(p-2) / 2}|D \varphi(x)|^{2} \mathrm{~d} x
\end{align*}
$$

for some $0 \leqslant \mu \leqslant 1$, for all $z_{0} \in \mathbb{R}^{n}, \varphi \in \mathcal{C}_{0}^{\infty}\left(Q_{1}\right)$, where $Q_{1}=(0,1)^{n}, L \geqslant 1, p>1$. More precisely, we have

Theorem 2.7. Let $v \in W_{\text {loc }}^{1,1}(\Omega)$ be a local minimizer of the functional (2.3) in $K$, where $g$ is a continuous function satisfying (H4) and (H5) and the function $\psi$ fulfils the assumption

$$
\begin{equation*}
D \psi \in L_{\mathrm{loc}}^{p, \lambda}(\Omega) \tag{2.4}
\end{equation*}
$$

for some $0<\lambda<n$. Then also $D v \in L_{\mathrm{loc}}^{p, \lambda}(\Omega)$ for the same $\lambda$.
As an immediate consequence of this result we deduce the following theorem.

Theorem 2.8. If the assumptions of Theorem 2.7 hold with $\lambda>n-p$, then $v \in \mathcal{C}_{\text {loc }}^{0, \alpha}(\Omega)$ with $\alpha=1-(n-\lambda) / p$.

Now if we assume that the obstacle $\psi$ is a little more integrable, we are able to deduce the following theorem which holds for the local minimizers in $K$ of the functional (1.1).

Theorem 2.9. Let $u \in W_{\text {loc }}^{1,1}(\Omega)$ be a local minimizer of the functional (1.1) in $K$, where $f$ is a continuous function satisfying (H1), (H2) and (H3) and the function $\psi$ fulfils the assumption

$$
\begin{equation*}
D \psi \in L_{\mathrm{loc}}^{q, \lambda}(\Omega) \tag{2.5}
\end{equation*}
$$

where $q=p r$ for some $r>1$ and $n-p<\lambda<n$. Then $D u \in L_{\text {loc }}^{p, \lambda}(\Omega)$.
Further improvements are still possible, see Remark 5.3.
Also in this case the following result can be obtained immediately from the previous one.

Theorem 2.10. Under the assumptions of Theorem 2.9, $u \in \mathcal{C}_{\text {loc }}^{0, \alpha}(\Omega)$ with $\alpha=$ $1-(n-\lambda) / p$.

Finally, if the Lagrangian $f$ is more regular and the obstacle stays in a Campanato space, we have

Theorem 2.11. Let $u \in W_{\text {loc }}^{1,1}(\Omega)$ be a local minimizer of the functional (1.1) in $K$, where $f$ is a function of class $\mathcal{C}^{2}$ satisfying (H1), (H2) and (H3) and the function $\psi$ fulfils the assumption

$$
\begin{equation*}
D \psi \in \mathcal{L}_{\mathrm{loc}}^{p, \lambda}(\Omega) \tag{2.6}
\end{equation*}
$$

for some $n<\lambda<n+p$. If we assume that

$$
\begin{equation*}
\omega(R) \leqslant L R^{\xi} \tag{2.7}
\end{equation*}
$$

for some $0<\xi \leqslant 1$ and all $R \leqslant 1$, then $D u \in \mathcal{L}_{\text {loc }}^{p, \tilde{\lambda}}(\Omega)$ for some $\tilde{\lambda} \equiv \tilde{\lambda}(\lambda, \xi, p, n)$ such that $n<\tilde{\lambda}<n+p$.

In this case we have the following consequence.
Theorem 2.12. Under the assumptions of Theorem 2.11, $u \in \mathcal{C}_{\text {loc }}^{1, \alpha}(\Omega)$ for some $0<\alpha<1$.

## 3. Preliminary results

## - A classical result

The following result is taken from [11], see also [9].

Theorem 3.1. Let $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a continuous function satisfying ( H 4 ) and (H5). Let $w \in W^{1, p}(\Omega)$ be a local minimizer of the functional (2.3) with $B_{R} \subset \subset \Omega$. Then $D w$ is locally bounded and, moreover, if $0<\varrho<R / 2$, then

$$
\int_{B_{\varrho}}\left(\mu^{2}+|D w(x)|^{2}\right)^{p / 2} \mathrm{~d} x \leqslant c\left(\frac{\varrho}{R}\right)^{n} \int_{B_{R}}\left(\mu^{2}+|D w(x)|^{2}\right)^{p / 2} \mathrm{~d} x
$$

with $c$ depending only on $p, L$.

## - A remark about local minimizers with obstacles

If $v$ is a local minimizer of the functional (2.3) in $K$ with the Lagrangian $g$ of class $\mathcal{C}^{2}$, then it is easy to see that

$$
\begin{equation*}
\int_{\Omega} A(D v(x)) \cdot D \varphi(x) \mathrm{d} x \geqslant 0 \quad \forall \varphi \in \mathcal{C}_{0}^{\infty}(\Omega) \text { such that } \varphi \geqslant 0 \tag{3.1}
\end{equation*}
$$

where $A(z):=D g(z)$ and $A(z)$ satisfies the monotonicity and growth conditions

$$
\begin{equation*}
A(z) \cdot z \geqslant \nu|z|^{p}-c \tag{3.2}
\end{equation*}
$$

for some $\nu>0$ and

$$
\begin{equation*}
|A(z)| \leqslant L\left(1+|z|^{p-1}\right) \tag{3.3}
\end{equation*}
$$

Moreover we have that

$$
\begin{equation*}
\int_{\Omega} A(D v(x)) \cdot(D v(x)-D w(x)) \mathrm{d} x \leqslant 0 \quad \forall w \in K, w-v \in W_{0}^{1, p}(\Omega) \tag{3.4}
\end{equation*}
$$

## - A higher integrability result

If $u$ is a local minimizer of the functional (1.1) in $K$, then it is possible to deduce for $u$ a higher integrability result.

Theorem 3.2. Let $u$ be a local minimizer of the functional (1.1) in $K$, where the Lagrangian $f$ satisfies (H1) and the function $\psi$ fulfils (2.5). Then there exist two positive constants $c, \delta$ depending on $p, L$ such that, if $B_{R} \subset \subset \Omega$, then

$$
\begin{equation*}
\left(f_{B_{R / 2}}|D u(x)|^{p(1+\delta)} \mathrm{d} x\right)^{1 /(1+\delta)} \leqslant c f_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c R^{(\lambda-n) /(1+\delta)} \tag{3.5}
\end{equation*}
$$

Moreover, if the function $\psi$ fulfils (2.6), then (3.5) holds with $\lambda$ replaced by $n$.

Proof. Working as in [8] we can easily find the Caccioppoli inequality for local minimizers of the functional (1.1) in $K$

$$
\begin{equation*}
\int_{B_{R / 2}}|D u(x)|^{p} \mathrm{~d} x \leqslant c \int_{B_{R}}\left|\frac{u(x)-(u)_{R}}{R}\right|^{p} \mathrm{~d} x+c \int_{B_{R}}\left(|D \psi(x)|^{p}+1\right) \mathrm{d} x \tag{3.6}
\end{equation*}
$$

from what we deduce

$$
f_{B_{R / 2}}|D u(x)|^{p} \mathrm{~d} x \leqslant c\left(f_{B_{R}}|D u(x)|^{p / \theta} \mathrm{d} x\right)^{\theta}+c f_{B_{R}}\left(|D \psi(x)|^{p}+1\right) \mathrm{d} x
$$

for a suitable $\theta \geqslant 1$. Now the assumption (2.5) allows us to use a classical result (see [16, Theorem 6.6]) based on Gehring's lemma and deduce that there exists $\delta \in(0,(q-p) / p)$ such that

$$
\begin{aligned}
& \left(f_{B_{R / 2}}|D u(x)|^{p(1+\delta)} \mathrm{d} x\right)^{1 /(1+\delta)} \\
& \quad \leqslant c f_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c\left(f_{B_{R}}\left(|D \psi(x)|^{p(1+\delta)}+1\right) \mathrm{d} x\right)^{1 /(1+\delta)}
\end{aligned}
$$

Using again assumption (2.5), we have

$$
\begin{aligned}
& \left(f_{B_{R / 2}}|D u(x)|^{p(1+\delta)} \mathrm{d} x\right)^{1 /(1+\delta)} \\
& \quad \leqslant c f_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c\left(f_{B_{R}}\left(|D \psi(x)|^{q}+1\right) \mathrm{d} x\right)^{1 /(1+\delta)} \\
& \quad \leqslant c f_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c R^{(\lambda-n) /(1+\delta)}
\end{aligned}
$$

This completes the proof. The other case is obtained in a similar way.

## - An up-to-the-boundary higher integrability result

If $u$ is a local minimizer of the functional (2.3) in $K$, then the following up-to-theboundary higher integrability result can be easily deduced:

Proposition 3.3. Let $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a continuous function fulfilling (H4). Let $v$ be a local minimizer of the functional (2.3) in the Dirichlet class $\left\{v \in u+W_{0}^{1, p}\left(B_{R}\right)\right.$ : $v \in K\}$ for some $u \in W^{1, p}\left(B_{R}\right)$, where the function $\psi$ fulfils the assumption (2.5). If, moreover, $u \in W^{1, \bar{q}}\left(B_{R}\right)$ for a certain $p<\bar{q}<q$, then there exist $p<\bar{r}<\bar{q}$ and $c$ depending on $p, L$ but not on $u$ or $R$ such that $v \in W^{1, \bar{r}}\left(B_{R / 2}\right)$ and

$$
\begin{align*}
\left(f_{B_{R / 2}}|D v(x)|^{\bar{r}} \mathrm{~d} x\right)^{p / \bar{r}} \leqslant & c\left[f_{B_{R}}\left(1+|D u(x)|^{\bar{q}}\right) \mathrm{d} x\right]^{p / \bar{q}}  \tag{3.7}\\
& +c\left[f_{B_{R}}\left(1+|D \psi(x)|^{\bar{q}}\right) \mathrm{d} x\right]^{p / \bar{q}} .
\end{align*}
$$

The same holds if the function $\psi$ fulfils assumption (2.6) instead.
Proof. The proof follows as in [4], the only difference is that now we have to take into consideration the presence of the obstacle function; so for example, for the Caccioppoli inequality, we have that, for any $B_{2 \varrho} \subset B_{R / 2}$ (not necessarily having the same center)

$$
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c \int_{B_{2 \varrho}}\left|\frac{v(x)-(v)_{2 \varrho}}{\varrho}\right|^{p} \mathrm{~d} x+c \int_{B_{2 \varrho}}\left(1+|D \psi(x)|^{p}\right) \mathrm{d} x
$$

and so on. The rest of the proof follows as in the standard case, with the obvious modifications.

## - A classical iteration lemma

The following classical iteration lemma can be found for example in [16]. Here we state this lemma with formulas showing the precise dependence on the constants we will need later.

Lemma 3.4. Let $\varphi(t)$ be a nonnegative and nondecreasing function. Suppose that

$$
\varphi(\varrho) \leqslant A\left[\left(\frac{\varrho}{R}\right)^{\alpha}+\varepsilon\right] \varphi(R)+B R^{\beta}
$$

for all $\varrho \leqslant R \leqslant R_{0}$, with $A, B, \alpha, \beta$ nonnegative constants, $\beta<\alpha$. Then there exists a constant $\varepsilon_{0}=\varepsilon_{0}(A, \alpha, \beta)$ such that if $\varepsilon<\varepsilon_{0}$, we have

$$
\varphi(\varrho) \leqslant c\left[\left(\frac{\varrho}{R}\right)^{\beta} \varphi(R)+B \varrho^{\beta}\right]
$$

for all $\varrho \leqslant R \leqslant R_{0}$, where $c$ is a constant depending on $\alpha$, $\beta$, $A$ but independent of $B$.

## - An auxiliary decay estimate

This estimate, which will be useful later, is established by following an idea from [10].

Proposition 3.5. Let $u \in W^{1, p}(\Omega)$ be a local minimizer of the functional (1.1) in $K$; assume that $\varsigma \in L^{r}(\Omega)$ where the function $\varsigma$ is introduced in (2.1) and $1<r<$ $n / p$, with $p<n$. Then for any $\varepsilon>0$ and for any $B_{\varrho} \subset B_{R} \subset \Omega$ with $R \leqslant 1$,

$$
\begin{aligned}
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}+\varepsilon\right] \\
& \times \int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c_{\varepsilon} R^{n(1-1 / r)}\left[\int_{B_{R}}\left(|\varsigma(x)|^{r}+1\right) \mathrm{d} x\right]^{1 / r}
\end{aligned}
$$

for some $0<\sigma_{1} \leqslant 1$, where $c$ is a constant depending on $L$, $n$, $p$ while $c_{\varepsilon}$ depends also on $\varepsilon$.

Proof. Let us fix any $B_{R} \subset \Omega$ with $R \leqslant 1$ and consider the functional

$$
\mathcal{F}_{\psi}\left(w, B_{R}\right):=\int_{B_{R}}[f(x, w(x), D w(x))+\varsigma(x)] \mathrm{d} x
$$

with $w \in V$ where $V:=\left\{v \in u+W_{0}^{1,1}\left(B_{R}\right)\right\}$.
First of all we notice that

$$
\inf _{w \in V} \mathcal{F}_{\psi}\left(w, B_{R}\right)
$$

is finite. So let us fix any $\delta>0$ and choose $u_{\delta} \in V$ such that

$$
\begin{equation*}
\mathcal{F}_{\psi}\left(u_{\delta}, B_{R}\right) \leqslant \inf _{w \in V} \mathcal{F}_{\psi}\left(w, B_{R}\right)+\delta R^{n} . \tag{3.8}
\end{equation*}
$$

We want to use the minimality of $u$. Since $u_{\delta}$ does not generally stay in $K$ we set $w_{\delta}:=\max \left\{\psi, u_{\delta}\right\}$ and $\Sigma:=\left\{x \in \mathbb{R}^{n}: u_{\delta} \geqslant \psi\right\}$. In this way we ensure that $w_{\delta} \in K$ and, by the minimality of $u$, we have

$$
\begin{equation*}
\mathcal{F}\left(u, B_{R}\right) \leqslant \mathcal{F}\left(w_{\delta}, B_{R}\right) \tag{3.9}
\end{equation*}
$$

Therefore we have

$$
\begin{aligned}
\mathcal{F}_{\psi}\left(u, B_{R}\right) & =\mathcal{F}\left(u, B_{R}\right)+\int_{B_{R}} \varsigma(x) \mathrm{d} x \\
& \stackrel{(3.9)}{\leqslant} \mathcal{F}\left(w_{\delta}, B_{R}\right)+\int_{B_{R}} \varsigma(x) \mathrm{d} x \\
& =\mathcal{F}\left(w_{\delta}, B_{R} \cap \Sigma\right)+\mathcal{F}\left(w_{\delta}, B_{R} \backslash \Sigma\right)+\int_{B_{R}} \varsigma(x) \mathrm{d} x \\
& \leqslant \mathcal{F}\left(u_{\delta}, B_{R}\right)+\mathcal{F}\left(\psi, B_{R}\right)+\int_{B_{R}} \varsigma(x) \mathrm{d} x \\
& =\mathcal{F}_{\psi}\left(u_{\delta}, B_{R}\right)+\mathcal{F}\left(\psi, B_{R}\right) \\
& \stackrel{(3.8)}{\leqslant} \inf _{w \in V} \mathcal{F}_{\psi}\left(w, B_{R}\right)+\delta R^{n}+L\left(\int_{B_{R}} \varsigma(x) \mathrm{d} x+R^{n}\right)
\end{aligned}
$$

we set

$$
H(R):=L\left(\int_{B_{R}} \varsigma(x) \mathrm{d} x+R^{n}\right) .
$$

Then letting $\delta \rightarrow 0$ we have

$$
\mathcal{F}_{\psi}\left(u, B_{R}\right) \leqslant \inf _{w \in V} \mathcal{F}_{\psi}\left(w, B_{R}\right)+H(R)
$$

At this point, the functional $\mathcal{F}_{\psi}\left(w, B_{R}\right)$ is lower semicontinuous with respect to the topology induced on $V$ by the distance

$$
d\left(u_{1}, u_{2}\right):=(H(R))^{-1 / p} R^{-n(1-1 / p)} \int_{B_{R}}\left|D u_{1}(x)-D u_{2}(x)\right| \mathrm{d} x
$$

then Ekeland's Lemma (see Theorem 1 in [7]) implies that there exists $v \in V$ such that
(i) $\int_{B_{R}}|D v(x)-D u(x)| \mathrm{d} x \leqslant(H(R))^{1 / p} R^{n(1-1 / p)}$,
(ii) $\mathcal{F}_{\psi}\left(v, B_{R}\right) \leqslant \mathcal{F}_{\psi}\left(u, B_{R}\right)$,
(iii) $v$ minimizes the functional

$$
\mathcal{F}_{\psi}\left(w, B_{R}\right)+\left(\frac{H(R)}{R^{n}}\right)^{(p-1) / p} \int_{B_{R}}|D w(x)-D v(x)| \mathrm{d} x .
$$

Actually it is not difficult to show that $v \in u+W_{0}^{1, p}\left(B_{R}\right)$ and it is a local $Q$-minimizer (with $Q$ depending only on $L$ ) of the functional

$$
w \mapsto \int_{B_{R}}\left(|D w(x)|^{p}+\frac{H(R)}{R^{n}}+1\right) \mathrm{d} x .
$$

Then using a classical result (see for example [16, Theorem 6.7], in which formula (6.60) holds even without the term $|u|^{p^{*}}$ on both sides of the inequality) we obtain, for some $p<q_{1}<n$,

$$
\begin{equation*}
\left(f_{B_{R / 2}}|D v(x)|^{q_{1}} \mathrm{~d} x\right)^{1 / q_{1}} \leqslant c\left[\left(f_{B_{R}}|D v(x)|^{p}\right)^{1 / p}+\left(1+\frac{H(R)}{R^{n}}\right)^{1 / p}\right] \tag{3.10}
\end{equation*}
$$

we can choose $q_{1}=p(1+\delta)$ where $\delta$ is the higher integrability exponent for $u$ given by Theorem 3.2, so that the following inequality holds:

$$
\begin{align*}
& \left(f_{B_{R / 2}}|D u(x)|^{p(1+\delta)} \mathrm{d} x\right)^{1 /(1+\delta)}  \tag{3.11}\\
& \quad \leqslant c f_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c\left(f_{B_{R}}\left(|D \psi(x)|^{p(1+\delta)}+1\right) \mathrm{d} x\right)^{1 /(1+\delta)}
\end{align*}
$$

We can choose $\delta$ so small that $\delta<r-1$.
At this point another classical result (see [10, Theorem 3.5], where also in this case formula (3.6) still holds even without the term $|u|^{p}$ on both sides of the inequality) entails that there exists $\sigma_{1}>0$ such that, for any $0<\varrho<R$,

$$
\begin{equation*}
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}\left[\int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x+H(R)+R^{n}\right] . \tag{3.12}
\end{equation*}
$$

Now, choosing $0<\theta<1$ such that $\theta / q_{1}+1-\theta=1 / p$, we obtain

$$
\left(f_{B_{R / 2}}|D u-D v|^{p} \mathrm{~d} x\right)^{1 / p} \leqslant\left(f_{B_{R / 2}}|D u-D v|^{q_{1}} \mathrm{~d} x\right)^{\theta / q_{1}}\left(f_{B_{R / 2}}|D u-D v| \mathrm{d} x\right)^{1-\theta}
$$

and this implies, with $\varepsilon \in(0,1)$,

$$
\begin{align*}
& \left(f_{B_{R / 2}}|D u(x)-D v(x)|^{p} \mathrm{~d} x\right)^{1 / p}  \tag{3.13}\\
& \quad \leqslant \varepsilon\left[\left(f_{B_{R / 2}}|D u(x)|^{q_{1}} \mathrm{~d} x\right)^{1 / q_{1}}+\left(f_{B_{R / 2}}|D v(x)|^{q_{1}} \mathrm{~d} x\right)^{1 / q_{1}}\right] \\
& \quad+c_{\varepsilon} f_{B_{R / 2}}|D u(x)-D v(x)| \mathrm{d} x
\end{align*}
$$

$$
\begin{aligned}
& \stackrel{(3.11)}{\leqslant} \varepsilon c\left[\left(f_{B_{R}}|D u(x)|^{p} \mathrm{~d} x\right)^{1 / p}+c\left(f_{B_{R}}\left(|\varsigma(x)|^{q_{1} / p}+1\right) \mathrm{d} x\right)^{1 / q_{1}}\right. \\
& \left.\stackrel{(3.10)}{+}\left(f_{B_{R}}|D v(x)|^{p}\right)^{1 / p}+\left(1+\frac{H(R)}{R^{n}}\right)^{1 / p}\right] \stackrel{(\mathrm{i})}{+} c_{\varepsilon}\left(\frac{H(R)}{R^{n}}\right)^{1 / p}
\end{aligned}
$$

On the other hand,

$$
\begin{align*}
\int_{B_{R}} & |D v(x)|^{p} \mathrm{~d} x  \tag{3.14}\\
& \leqslant L \int_{B_{R}} f(x, v(x), D v(x)) \mathrm{d} x+L \int_{B_{R}} \varsigma(x) \mathrm{d} x-L \int_{B_{R}} \varsigma(x) \mathrm{d} x \\
& =L \mathcal{F}_{\psi}\left(v, B_{R}\right)-L \int_{B_{R}} \varsigma(x) \mathrm{d} x \stackrel{(i i)}{\leqslant} L \mathcal{F}_{\psi}\left(u, B_{R}\right)-L \int_{B_{R}} \varsigma(x) \mathrm{d} x \\
& =L \mathcal{F}\left(u, B_{R}\right) \leqslant c(L) \int_{B_{R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x .
\end{align*}
$$

At this point, (3.13) becomes

$$
\begin{aligned}
& \left(f_{B_{R / 2}}|D u(x)-D v(x)|^{p} \mathrm{~d} x\right)^{1 / p} \\
& \leqslant \\
& \qquad \begin{aligned}
& \varepsilon c(L)\left[\left(f_{B_{R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x\right)^{1 / p}+\left(f_{B_{R}}\left(|\varsigma(x)|^{q_{1} / p}+1\right) \mathrm{d} x\right)^{1 / q_{1}}\right. \\
& \left.+\left(1+\frac{H(R)}{R^{n}}\right)^{1 / p}\right]+c_{\varepsilon}\left(\frac{H(R)}{R^{n}}\right)^{1 / p}
\end{aligned} .
\end{aligned}
$$

Hence, raising both sides of the previous inequality to the power $p$ and getting rid of the averages, we get

$$
\begin{align*}
& \int_{B_{R / 2}}|D u(x)-D v(x)|^{p} \mathrm{~d} x  \tag{3.15}\\
& \leqslant \\
& \quad \varepsilon c(p, L)\left[\int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+R^{n}+R^{n\left(1-p / q_{1}\right)}\right. \\
& \left.\quad \times\left(\int_{B_{R}}\left(|\varsigma(x)|^{q_{1} / p}+1\right) \mathrm{d} x\right)^{p / q_{1}}\right] \\
& \\
& \quad+c_{\varepsilon}(p) H(R)
\end{align*}
$$

This allows us to conclude (using the fact that $\delta<r-1$ ) that

$$
\begin{aligned}
& \int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \\
& \leqslant 2^{p-1} \int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x+2^{p-1} \int_{B_{R / 2}}|D u(x)-D v(x)|^{p} \mathrm{~d} x
\end{aligned}
$$

$$
\begin{aligned}
& \stackrel{(3.12)}{\leqslant} c(p, L)\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}\left[\int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x+H(R)+R^{n}\right] \\
& \stackrel{(3.15)}{+} \varepsilon c(p, L)\left[\int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+R^{n}+R^{n(1-1 / r)}\left(\int_{B_{R}}|\varsigma(x)|^{r} \mathrm{~d} x\right)^{1 / r}\right] \\
& +c_{\varepsilon}(p) H(R) \\
& \leqslant c(p, L)\left[\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}+\varepsilon\right] \int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x \\
& +c_{\varepsilon} R^{n(1-1 / r)}\left(\int_{B_{R}}\left(|\varsigma(x)|^{r}+1\right) \mathrm{d} x\right)^{1 / r}
\end{aligned}
$$

and this completes the proof.

## - A Hölder regularity result

Theorem 3.6. Let $u \in W^{1, p}(\Omega)$ be a local minimizer of the functional (1.1) in $K$, with $p<n$; assume that $\varsigma \in L_{\mathrm{loc}}^{r, \lambda}(\Omega)$ where $\varsigma$ is the function introduced in (2.1), $1<r<n / p$ and $0<\lambda<n$. If, moreover, $n-p r<\lambda<n$, then $u$ is locally Hölder continuous in $\Omega$. On the other hand, if $p \geqslant n$ then $u$ is trivially locally Hölder continuous too.

Proof. We immediately remark that, if $p>n$ then $u$ is trivially locally Hölder continuous in $\Omega$ due to the Sobolev embedding. On the other hand, if $p=n$ the same conclusion can be obtained using the higher integrability result (3.5) and the previous assertion. So we concentrate our discussion on the case $p<n$.

From Proposition 3.5 we have that, for any $\varepsilon>0$ and for any $B_{\varrho} \subset B_{R} \subset \Omega$ with $R \leqslant 1$,

$$
\begin{aligned}
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}+\varepsilon\right] \int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x \\
& +c_{\varepsilon} R^{n(1-1 / r)}\left[\int_{B_{R}}\left(|\varsigma(x)|^{r}+1\right) \mathrm{d} x\right]^{1 / r}
\end{aligned}
$$

for some $0<\sigma_{1} \leqslant 1$, where $c$ is a constant depending on $L, n, p$ while $c_{\varepsilon}$ depends also on $\varepsilon$. Now, with our assumptions on the function $\varsigma$, we can immediately deduce that

$$
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}+\varepsilon\right] \int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c_{\varepsilon} R^{n-(n-\lambda) / r}\|\varsigma\|_{L^{r, \lambda}\left(B_{R}\right)} .
$$

As, moreover, $\lambda>n-p r$, there exists $\sigma_{2}>0$ such that

$$
\frac{\lambda}{r}-\frac{n}{r}=p \sigma_{2}-p
$$

and therefore

$$
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n-p+p \sigma_{1}}+\varepsilon\right] \int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c_{\varepsilon} R^{n-p+p \sigma_{2}}
$$

Choosing for example $\gamma:=\frac{1}{2} \min \left\{\sigma_{1}, \sigma_{2}\right\}$ and using the classical iteration Lemma 3.4, we deduce that

$$
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant c\left(\frac{\varrho}{R}\right)^{n-p+p \gamma}\left[\int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x+c_{\varepsilon} R^{n-p+p \gamma}\right]
$$

At this point, Theorem 2.6 allows us to conclude that $u \in \mathcal{C}_{\text {loc }}^{0, \gamma}(\Omega)$. This completes the proof.

From now on, since we are going to prove local regularity results, we shall assume that any local minimizer $u$ of the functional (1.1) in $K$ is globally Hölder continuous, that is for all $x, y \in \Omega$

$$
\begin{equation*}
|u(x)-u(y)| \leqslant[u]_{\gamma}|x-y|^{\gamma} \leqslant c|x-y|^{\gamma} . \tag{3.16}
\end{equation*}
$$

## 4. Proof of Theorem 2.7

The proof of this theorem is carried out in three steps: first we establish a decay estimate for local minimizers of the functional (2.3) in $K$, with $g \in \mathcal{C}^{2}$; then we remove the smoothness of the function $g$ by means of a standard approximation argument and finally we conclude using a classical iteration lemma.

Step 1. We start by proving the first result:
Proposition 4.1. Let $v \in W_{\mathrm{loc}}^{1,1}(\Omega)$ be a local minimizer of the functional (2.3) in $K$, where $g \in \mathcal{C}^{2}$ satisfies (H4) and (H5). If the function $\psi$ fulfils (2.4) for some $0<\lambda<n$, then for all $0<\varrho<R / 2$ and any $\varepsilon>0$

$$
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D v(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda}
$$

where $c \equiv c(p, L, \nu)$ and $\bar{c} \equiv \bar{c}(p, L, \varepsilon, \nu)$ (the coefficient $\nu$ was introduced in (3.2)).
Proof. We fix $R>0$; then let $w \in v+W_{0}^{1, p}\left(B_{R}\right)$ be the solution of the equation

$$
\begin{equation*}
\int_{B_{R}} A(D w(x)) \cdot D \varphi(x) \mathrm{d} x=\int_{B_{R}} A(D \psi(x)) \cdot D \varphi(x) \mathrm{d} x \quad \forall \varphi \in W_{0}^{1, p}\left(B_{R}\right) . \tag{4.1}
\end{equation*}
$$

Then by the maximum principle (for more details see for example [15]) we get that $w \geqslant \psi$ in $B_{R}$ since $v \geqslant \psi$ on $\partial B_{R}$. We also have

$$
\begin{equation*}
\int_{B_{R}} A(D v(x)) \cdot(D v(x)-D w(x)) \mathrm{d} x \leqslant 0 \tag{4.2}
\end{equation*}
$$

since $v-w \in W_{0}^{1, p}\left(B_{R}\right)$ and $w \geqslant \psi$ in $B_{R}$.
Now let $z$ be the solution of the minimum problem

$$
\begin{equation*}
\min \left\{\mathcal{G}_{0}\left(z, B_{R}\right): z \in v+W_{0}^{1, p}\left(B_{R}\right)\right\}, \tag{4.3}
\end{equation*}
$$

where $\mathcal{G}_{0}$ was introduced in (2.3). It is evident that $z$ satisfies

$$
\begin{equation*}
\int_{B_{R}} A(D z(x)) \cdot D \varphi(x) \mathrm{d} x=0 \quad \forall \varphi \in W_{0}^{1, p}\left(B_{R}\right) ; \tag{4.4}
\end{equation*}
$$

moreover, $z=w$ on $\partial B_{R}$, so for example

$$
\begin{equation*}
\int_{B_{R}} A(D z(x)) \cdot(D w(x)-D z(x)) \mathrm{d} x=0 \tag{4.5}
\end{equation*}
$$

First of all, from Theorem 3.1 we get for any $0<\varrho<R / 2$

$$
\int_{B_{\varrho}}\left(\mu^{2}+|D z(x)|^{2}\right)^{p / 2} \mathrm{~d} x \leqslant c\left(\frac{\varrho}{R}\right)^{n} \int_{B_{R}}\left(\mu^{2}+|D z(x)|^{2}\right)^{p / 2} \mathrm{~d} x
$$

where the constant $c$ depends only on $p, L$. Moreover, using the minimality of $z$ we get

$$
\begin{aligned}
\int_{B_{R}}|D z(x)|^{p} \mathrm{~d} x \leqslant L \int_{B_{R}} g(D z(x)) \mathrm{d} x & \leqslant L \int_{B_{R}} g(D w(x)) \mathrm{d} x \\
& \leqslant c(L) \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

as $w-z \in W_{0}^{1, p}\left(B_{R}\right)$.
Now, we would like to compare $z$ and $w$. If $p \geqslant 2$, we readily have

$$
\begin{aligned}
\int_{B_{R}} & |D w(x)-D z(x)|^{p} \mathrm{~d} x \\
& \leqslant c \int_{B_{R}}\left(1+|D w(x)|^{2}+|D z(x)|^{2}\right)^{(p-2) / 2}|D w(x)-D z(x)|^{2} \mathrm{~d} x \\
& \leqslant c \int_{B_{R}}\langle A(D w(x))-A(D z(x)), D w(x)-D z(x)\rangle \mathrm{d} x
\end{aligned}
$$

$$
\begin{aligned}
& \stackrel{(4.5)}{=} c \int_{B_{R}}\langle A(D w(x)), D w(x)-D z(x)\rangle \mathrm{d} x \\
& \stackrel{(4.1)}{=} c \int_{B_{R}}\langle A(D \psi(x)), D w(x)-D z(x)\rangle \mathrm{d} x \\
& \stackrel{(3.3)}{\leqslant} c \int_{B_{R}}\left(|D \psi(x)|^{p-1}+1\right) \cdot|D w(x)-D z(x)| \mathrm{d} x \\
& \leqslant \\
& \leqslant \\
& \leqslant \int_{B_{R}}|D \psi(x)|^{p-1} \cdot|D w(x)-D z(x)| \mathrm{d} x+c \int_{B_{R}}|D w(x)-D z(x)| \mathrm{d} x \\
& \leqslant \\
& \quad c \int_{B_{R}}|D \psi(x)|^{p} \mathrm{~d} x+\frac{1}{4} \int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \\
& \\
& \quad+c R^{n(p-1) / p}\left(\int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x\right)^{1 / p} \\
& \leqslant \\
& \\
& \quad c \int_{B_{R}}|D \psi(x)|^{p} \mathrm{~d} x+\frac{1}{2} \int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x+c R^{n}
\end{aligned}
$$

where (4.1) was used with the choice $\varphi=w-z$, Young's inequality was used twice and the constants $c$ depend only on $p, L$. So, using assumption (2.4), we get

$$
\int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \leqslant c R^{\lambda}
$$

In a rather similar way, if $1<p<2$, using again Young's inequality

$$
\begin{aligned}
\int_{B_{R}} \mid D w(x) & -\left.D z(x)\right|^{p} \mathrm{~d} x \\
\leqslant & \left(\int_{B_{R}}\left(1+|D w(x)|^{2}+|D z(x)|^{2}\right)^{(p-2) / 2}|D w(x)-D z(x)|^{2} \mathrm{~d} x\right)^{1 / 2} \\
& \times\left(\int_{B_{R}}\left(1+|D w(x)|^{2}+|D z(x)|^{2}\right)^{(2-p) / 2}|D w(x)-D z(x)|^{2 p-2} \mathrm{~d} x\right)^{1 / 2} \\
\leqslant & c(L)\left[\int_{B_{R}}\left(|D \psi(x)|^{p-1}+1\right) \cdot|D w(x)-D z(x)| \mathrm{d} x\right]^{1 / 2} \\
& \times\left(\int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x\right)^{1 / 2} \\
\leqslant & c(\varepsilon, L)\left[\int_{B_{R}}\left(|D \psi(x)|^{p-1}+1\right) \cdot|D w(x)-D z(x)| \mathrm{d} x\right] \\
& +\varepsilon \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

$$
\begin{aligned}
\leqslant & c(\varepsilon, L, p) \int_{B_{R}}\left(|D \psi(x)|^{p}+1\right) \mathrm{d} x+\frac{1}{2} \int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \\
& +\varepsilon \int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x
\end{aligned}
$$

gives us

$$
\begin{equation*}
\int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \leqslant c(\varepsilon, L, p) R^{\lambda}+\varepsilon \int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x . \tag{4.6}
\end{equation*}
$$

Summarizing, for any $p>1$ we have (4.6). So we get

$$
\begin{aligned}
\int_{B_{\varrho}}|D w(x)|^{p} \mathrm{~d} x \leqslant & 2^{p-1} \int_{B_{\varrho}}|D z(x)|^{p} \mathrm{~d} x+2^{p-1} \int_{B_{\varrho}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \\
\leqslant & c(p) \int_{B_{\varrho}}\left(\mu^{2}+|D z(x)|^{2}\right)^{p / 2} \mathrm{~d} x+c(\varepsilon, L, p) R^{\lambda} \\
& +2^{p-1} \varepsilon \int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x \\
\leqslant & c\left(\frac{\varrho}{R}\right)^{n} \int_{B_{R}}\left(\mu^{2}+|D z(x)|^{2}\right)^{p / 2} \mathrm{~d} x+\bar{c} R^{\lambda} \\
& +2^{p-1} \varepsilon \int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x \\
\leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda}
\end{aligned}
$$

where the constant $c$ depends only on $p, L$ and the constant $\bar{c}$ depends on $p, L, \varepsilon$. Now, we would like to compare $w$ and $v$. We get

$$
\begin{aligned}
\int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x \stackrel{(3.2)}{\leqslant} & \frac{1}{\nu} \int_{B_{R}}\langle A(D w(x)), D w(x)\rangle \mathrm{d} x+c R^{n} \\
\stackrel{(4.1)}{=} & \frac{1}{\nu} \int_{B_{R}}\langle A(D w(x)), D v(x)\rangle \mathrm{d} x \\
& +\frac{1}{\nu} \int_{B_{R}}\langle A(D \psi(x)), D w(x)-D v(x)\rangle \mathrm{d} x+c R^{n} \\
\leqslant & \frac{L}{\nu} \int_{B_{R}}\left(|D w(x)|^{p-1}+1\right)|D v(x)| \mathrm{d} x \\
& +\frac{L}{\nu} \int_{B_{R}}\left(|D \psi(x)|^{p-1}+1\right)|D w(x)| \mathrm{d} x \\
& +\frac{L}{\nu} \int_{B_{R}}\left(|D \psi(x)|^{p-1}+1\right)|D v(x)| \mathrm{d} x+c R^{n}
\end{aligned}
$$

$$
\begin{aligned}
\leqslant & \frac{1}{2} \int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x+c \int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x \\
& +c \int_{B_{R}}|D \psi(x)|^{p} \mathrm{~d} x+c R^{n},
\end{aligned}
$$

where (4.1) is applied with the choice $\varphi=w-v$ and the constants $c$ depend only on $p, L, \nu$. So, using assumption (2.4), we have

$$
\begin{equation*}
\int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x \leqslant c \int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x+c R^{\lambda} . \tag{4.7}
\end{equation*}
$$

On the other hand, working as for (4.6), it is not hard to get

$$
\int_{B_{R}}|D v(x)-D w(x)|^{p} \mathrm{~d} x \leqslant c(\varepsilon, L, p, \nu) R^{\lambda}+\varepsilon \int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x
$$

which is valid for all $p>1$ and for any $\varepsilon>0$. Indeed, when developing the analogue of (4.6) with $v(x)$ replacing $z(x)$, it is sufficient to write

$$
\begin{aligned}
& \int_{B_{R}}\langle A(D w(x))-A(D v(x)), D w(x)-D v(x)\rangle \mathrm{d} x \\
& \leqslant \int_{B_{R}}\langle A(D(w(x)), D w(x)-D v(x)\rangle \mathrm{d} x
\end{aligned}
$$

which comes from (4.2). Now for any $0<\varrho<R / 2$ and any $\varepsilon>0$

$$
\begin{aligned}
& \int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant 2^{p-1} \int_{B_{\varrho}}|D w(x)|^{p} \mathrm{~d} x+2^{p-1} \int_{B_{e}}|D v(x)-D w(x)|^{p} \mathrm{~d} x \\
& \leqslant c(p)\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x+c(\varepsilon, L, p) R^{\lambda} \\
&+\varepsilon 2^{p-1} \int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x \\
& \stackrel{(4.7)}{\leqslant} c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D v(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda}
\end{aligned}
$$

where $c$ depends only on $p, L, \nu$ while $\bar{c}$ depends on $\varepsilon, p, L, \nu$. This completes the proof.

Step 2. We remove the $\mathcal{C}^{2}$-regularity of the function $g$.

Proposition 4.2. Let $v \in W_{\mathrm{loc}}^{1,1}(\Omega)$ be a local minimizer of the functional (2.3) in $K$, where $g$ is a continuous function satisfying (H4) and (H5). If the function $\psi$ fulfils (2.4) for some $0<\lambda<n$, then for all $0<\varrho<R / 2$ and any $\varepsilon>0$

$$
\begin{equation*}
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D v(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda} \tag{4.8}
\end{equation*}
$$

where $c \equiv c(p, L, \nu)$ and $\bar{c} \equiv \bar{c}(p, L, \varepsilon, \nu)$.
Proof. The proof relies on a standard approximation argument, see [11], [4]. Here we confine ourselves only to a sketch of this proof. Let us consider $\left(G_{m}\right)_{m \in \mathbb{N}}$ to be a sequence of continuous functions defined by

$$
G_{m}(z):=\int_{B(0,1)} \varphi(y) g\left(z+\frac{y}{m}\right) \mathrm{d} y
$$

where $\varphi: B(0,1) \rightarrow[0,1]$ is a positive and symmetric mollifier. Then for any $m \in \mathbb{N}$ it is not hard to prove, following [11], that $G_{m}$ satisfies (H4) and (H5) with $L$ replaced by a suitable constant $c$ dependent only on $L$ and $p$ and independent of $m$ and with $\mu^{2}$ replaced by $\mu^{2}+1 / m^{2}$. At this point we define $v_{m} \in v+W_{0}^{1, p}\left(B_{R}\right)$ as the unique minimizer in $K$ of the functional

$$
\mathcal{G}_{m}\left(w, B_{R}\right):=\int_{B_{R}} G_{m}(D w(x)) \mathrm{d} x
$$

in the Dirichlet class $v+W_{0}^{1, p}\left(B_{R}\right)$. Using a standard coercivity argument and the strict convexity of the functional (2.3) (see for example [1]), it turns out that, up to subsequences, $v_{m}$ weakly converges to $v$ in $W^{1, p}\left(B_{R}\right)$ and the estimate (4.8) follows by passing to the limit of the corresponding estimates valid uniformly for each $v_{m}$.

Step 3. Now we have that the following estimate holds for all $0<\varrho<R / 2$ and any $\varepsilon>0$ :

$$
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D v(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda}
$$

where $c \equiv c(p, L, \nu)$ and $\bar{c} \equiv \bar{c}(p, L, \varepsilon, \nu)$. Using Lemma 3.4, we can choose a radius $R_{1} \equiv R_{1}(p, L, \nu)$ and a constant $\varepsilon_{0}>0$ such that, if $\varepsilon \leqslant \varepsilon_{0}$, we may deduce

$$
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant \bar{c} \varrho^{\lambda}
$$

with $\bar{c} \equiv \bar{c}(p, L, \nu, \varepsilon)$ whenever $0<\varrho<R_{1}$, a fact which we may assume without loss of generality. This allows us to conclude that $D v \in L_{\mathrm{loc}}^{p, \lambda}(\Omega)$.

## 5. Proof of Theorem 2.9

Also the proof of this result is divided into three parts: in the first step we establish a technical estimate which will be used in the last part of the proof. This estimate can be only obtained provided the function $g$ is of class $\mathcal{C}^{2}$; therefore in the second step we must remove this further regularity assumption by means of another approximation argument similar to the one used in Proposition 4.2.

Step 1. We first prove the following proposition.

Proposition 5.1. Let $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a function of class $\mathcal{C}^{2}$ satisfying (H4) and (H5) with $L$ replaced by $8^{p} L$ and $\mu>0$. Let $u \in K, B_{R} \subset \Omega$ and let $v_{0} \in W^{1, p}(\Omega)$ be a minimizer of the functional

$$
\begin{aligned}
\mathcal{H}\left(w, B_{R}\right) & :=\int_{B_{R}} g(D w(x)) \mathrm{d} x+\theta_{0} \int_{B_{R}}\left|D w-D v_{0}\right| \mathrm{d} x \\
& :=\mathcal{G}_{0}\left(w, B_{R}\right)+\theta_{0} \int_{B_{R}}\left|D w-D v_{0}\right| \mathrm{d} x
\end{aligned}
$$

in the Dirichlet class

$$
\begin{equation*}
\bar{D}:=\left\{w \in K: w=u \text { on } \partial B_{R}\right\} \tag{5.1}
\end{equation*}
$$

where $\theta_{0} \geqslant 0$. Then, for all $\beta>0$, for all $A_{0}>0$ and for any $\varepsilon>0$ we have

$$
\begin{aligned}
\int_{B_{\varrho}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x \leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+\left|D v_{0}(x)\right|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda} \\
& +c \theta_{0} \int_{B_{R}}\left|D u(x)-D v_{0}(x)\right| \mathrm{d} x+c R^{n} \theta_{0}^{p /(p-1)}\left[\frac{1}{A_{0}}\right]^{p \beta /(p-1)} \\
& +c\left[A_{0}\right]^{p \beta} \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

for any $0<\varrho<R / 2$, where the constants $c$ depend only on $L$, $p, \nu$ while the constant $\bar{c}$ depends also on $\varepsilon$.

Proof. Let $v \in W^{1, p}\left(B_{R}\right)$ be a local minimizer of the functional (2.3) in the Dirichlet class (5.1), where $g$ is the function introduced in the statement of Proposition 5.1. So by Proposition 4.1 we have for any $0<\varrho<R / 2$ and any $\varepsilon>0$

$$
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+|D v(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda}
$$

with constants $c \equiv c(L, p, \nu)$ and $\bar{c} \equiv \bar{c}(L, p, \nu, \varepsilon)$; thus comparing $v$ and $v_{0}$ and using the minimality of $v$ in $\bar{D}$, we obtain for any $0<\varrho<R / 2$ and any $\varepsilon>0$

$$
\begin{equation*}
\int_{B_{\varrho}}|D v(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+\left|D v_{0}(x)\right|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda} \tag{5.2}
\end{equation*}
$$

where $c \equiv c(p, L, \nu)$ and $\bar{c} \equiv \bar{c}(p, L, \varepsilon, \nu)$. We remark that for obtaining this first result it is not necessary to assume $g \in \mathcal{C}^{2}$ as we could use directly Proposition 4.2.

Moreover, arguing in a standard way and using (5.2), it is possible to obtain the inequality

$$
\begin{aligned}
& \int_{B_{\varrho}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \\
&+c \int_{B_{R}}\left(1+\left|D v_{0}(x)\right|^{p}\right) \mathrm{d} x \\
&\left(\mu^{2}\right.\left.+\left|D v_{0}(x)\right|^{2}+|D v(x)|^{2}\right)^{(p-2) / 2} \\
& \times\left|D v_{0}(x)-D v(x)\right|^{2} \mathrm{~d} x+\bar{c} R^{\lambda}
\end{aligned}
$$

and the estimate (since in our case we are assuming $\mu>0$ )

$$
\mathcal{G}_{0}\left(v_{0}\right)-\mathcal{G}_{0}(v) \geqslant c^{-1} \int_{B_{R}}\left(\mu^{2}+\left|D v_{0}(x)\right|^{2}+|D v(x)|^{2}\right)^{(p-2) / 2}\left|D v_{0}(x)-D v(x)\right|^{2} \mathrm{~d} x
$$

It is here that we specifically need the $\mathcal{C}^{2}$-regularity of the function $g$. On the other hand, using the minimality of $v_{0}$ and the triangular inequality, we deduce

$$
\begin{aligned}
\mathcal{G}_{0}\left(v_{0}\right)-\mathcal{G}_{0}(v) \leqslant & \mathcal{H}\left(v_{0}\right)-\mathcal{H}(v)+\theta_{0} \int_{B_{R}}\left|D v_{0}(x)-D v(x)\right| \mathrm{d} x \\
& +\theta_{0} \int_{B_{R}}|D v(x)-D u(x)| \mathrm{d} x-\theta_{0} \int_{B_{R}}|D v(x)-D u(x)| \mathrm{d} x \\
\leqslant & \theta_{0} \int_{B_{R}}\left|D u(x)-D v_{0}(x)\right| \mathrm{d} x \\
& +\int_{B_{R}}\left\{\theta_{0}\left[\frac{1}{A_{0}}\right]^{\beta}\right\}\left\{|D v(x)-D u(x)|\left[A_{0}\right]^{\beta}\right\} \mathrm{d} x \\
\leqslant & \theta_{0} \int_{B_{R}}\left|D u(x)-D v_{0}(x)\right| \mathrm{d} x+c R^{n} \theta_{0}{ }^{p /(p-1)}\left[\frac{1}{A_{0}}\right]^{p \beta /(p-1)} \\
& +c\left[A_{0}\right]^{p \beta} \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

for all $\beta>0$ and all $A_{0}>0$. Combining all the estimates we have just obtained, we get the assertion.

Step 2. We now remove the assumption of smoothness of the function $g$.

Proposition 5.2. Let $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a continuous function satisfying (H4) and (H5). Let $u \in K, B_{R} \subset \Omega$ and let $v_{0} \in W^{1, p}(\Omega)$ be a minimizer of the functional

$$
\begin{aligned}
\mathcal{H}\left(w, B_{R}\right) & :=\int_{B_{R}} g(D w(x)) \mathrm{d} x+\theta_{0} \int_{B_{R}}\left|D w-D v_{0}\right| \mathrm{d} x \\
& :=\mathcal{G}_{0}\left(w, B_{R}\right)+\theta_{0} \int_{B_{R}}\left|D w-D v_{0}\right| \mathrm{d} x
\end{aligned}
$$

in the Dirichlet class (5.1) where $\theta_{0} \geqslant 0$. Then for all $\beta>0$, for all $A_{0}>0$ and for any $\varepsilon>0$ we have

$$
\begin{aligned}
\int_{B_{\varrho}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x \leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+\left|D v_{0}(x)\right|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda} \\
& +c \theta_{0} \int_{B_{R}}\left|D u(x)-D v_{0}(x)\right| \mathrm{d} x+c R^{n} \theta_{0}^{p /(p-1)}\left[\frac{1}{A_{0}}\right]^{p \beta /(p-1)} \\
& +c\left[A_{0}\right]^{p \beta} \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

for any $0<\varrho<R / 2$, where the constants $c$ depend only on $L$, $p, \nu$ while the constant $\bar{c}$ depends also on $\varepsilon$.

Proof. Also this result is based on a standard approximation argument similar to the one employed in Proposition 4.2; it easily follows from [11] and Proposition 5.1. See also [8].

Step 3. We are ready to deal with the main part of the proof of Theorem 2.9.

## - Freezing

In the previous sections we remarked that if $u$ is a local minimizer of (1.1) in $K$, then it is possible to apply Theorem 3.2 and get that $D u \in L^{p+\delta}(\Omega)$ for some $\delta \equiv \delta(p, L)>0$.

Now let us fix any $R>0$ and any $x_{0} \in B_{4 R}$, where $B_{4 R} \subset \subset \Omega$. For any $z \in \mathbb{R}^{n}$ we set

$$
\begin{gather*}
h(z):=f\left(x_{0},(u)_{R}, z\right), \\
\mathcal{H}_{0}\left(w, B_{R}\right):=\int_{B_{R}} h(D w(x)) \mathrm{d} x=\int_{B_{R}} f\left(x_{0},(u)_{R}, D w(x)\right) \mathrm{d} x . \tag{5.3}
\end{gather*}
$$

Let $\bar{v}$ be a local minimizer of the functional (5.3) in the Dirichlet class $\{v \in K: v \in$ $\left.u+W_{0}^{1, p}\left(B_{R}\right)\right\}$. We immediately notice that the function $h(z):=f\left(x_{0},(u)_{R}, z\right)$ satisfies the assumption of Proposition 3.3, so it follows that there exist two constants $c$,
$\bar{r}$ both depending on $p, L$ and independent of $R$ and $u$, such that $p<\bar{r}<p(1+\delta)$ and

$$
\begin{align*}
\left(f_{B_{R}}|D \bar{v}(x)|^{\bar{r}} \mathrm{~d} x\right)^{p / \bar{r}} & \leqslant c\left[f_{B_{2 R}}\left(1+|D u(x)|^{p(1+\delta)}\right) \mathrm{d} x\right]^{1 /(1+\delta)}  \tag{5.4}\\
& +c\left[f_{B_{2 R}}\left(1+|D \psi(x)|^{p(1+\delta)}\right) \mathrm{d} x\right]^{1 /(1+\delta)}
\end{align*}
$$

Since $u$ is a local minimizer of the functional (1.1) in $K$, we obtain

$$
\begin{align*}
\mathcal{H}_{0}(u) \leqslant & \mathcal{H}_{0}(\bar{v})+\int_{B_{R}} f(x, \bar{v}(x), D \bar{v}(x)) \mathrm{d} x-\int_{B_{R}} f(x, u(x), D \bar{v}(x)) \mathrm{d} x  \tag{5.5}\\
& +\int_{B_{R}} f(x, u(x), D \bar{v}(x)) \mathrm{d} x-\int_{B_{R}} f\left(x_{0}, u(x), D \bar{v}(x)\right) \mathrm{d} x \\
& +\int_{B_{R}} f\left(x_{0}, u(x), D \bar{v}(x)\right) \mathrm{d} x-\int_{B_{R}} f\left(x_{0},(u)_{R}, D \bar{v}(x)\right) \mathrm{d} x \\
& +\int_{B_{R}} f\left(x_{0},(u)_{R}, D u(x)\right) \mathrm{d} x-\int_{B_{R}} f\left(x_{0}, u(x), D u(x)\right) \mathrm{d} x \\
& +\int_{B_{R}} f\left(x_{0}, u(x), D u(x)\right) \mathrm{d} x-\int_{B_{R}} f(x, u(x), D u(x)) \mathrm{d} x \\
= & \mathcal{H}_{0}(\bar{v})+I+I I+I I I+I V+V .
\end{align*}
$$

- Bounds for the quantities $I, I I, \ldots, V$

We now estimate the quantities $I, I I, \ldots, V$.

$$
\begin{aligned}
& I \leqslant L \int_{B_{R}} \omega(|\bar{v}(x)-u(x)|)\left(\mu^{2}+|D \bar{v}(x)|^{2}\right)^{p / 2} \mathrm{~d} x \\
& \leqslant c\left[\int_{B_{R}}\left(\mu^{2}+|D \bar{v}(x)|^{2}\right)^{\bar{r} / 2} \mathrm{~d} x\right]^{p / \bar{r}}\left[\int_{B_{R}} \omega^{\bar{r} /(\bar{r}-p)}(|\bar{v}(x)-u(x)|) \mathrm{d} x\right]^{(\bar{r}-p) / \bar{r}} \\
& \leqslant c R^{n}\left[f_{B_{R}}\left(1+|D \bar{v}(x)|^{\bar{r}}\right) \mathrm{d} x\right]^{p / \bar{r}}\left[f_{B_{R}} \omega^{\bar{r} /(\bar{r}-p)}(|\bar{v}(x)-u(x)|) \mathrm{d} x\right]^{(\bar{r}-p) / \bar{r}} \\
& \stackrel{(5.4)}{\leqslant} c R^{n}\left[\left(f_{B_{2 R}}\left(1+|D u(x)|^{p(1+\delta)}\right) \mathrm{d} x\right)^{1 /(1+\delta)}+R^{(\lambda-n) /(1+\delta)}\right] \\
& \times\left[f_{B_{R}} \omega(|\bar{v}(x)-u(x)|) \mathrm{d} x\right]^{(\bar{r}-p) / \bar{r}}
\end{aligned}
$$

$$
\begin{aligned}
& \stackrel{(3.5)}{\leqslant} c R^{n}\left[f_{B_{4 R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x+R^{(\lambda-n) /(1+\delta)}\right] \\
& \\
& \times\left[f_{B_{R}} \omega(|\bar{v}(x)-u(x)|) \mathrm{d} x\right]^{(\bar{r}-p) / \bar{r}} \\
& \leqslant \\
& \leqslant \\
&
\end{aligned}
$$

where $\sigma:=(\bar{r}-p) / \bar{r}$. We set

$$
\lambda_{1}:=\frac{\lambda+n \delta}{1+\delta}
$$

and notice that $\lambda_{1} \geqslant \lambda$ so that $R^{\lambda_{1}} \leqslant R^{\lambda}$. Now, using the Poincaré inequality and the Caccioppoli inequality for local minimizers with obstacle (3.6), we have

$$
\begin{aligned}
& \omega^{\sigma}\left(f_{B_{R}}|\bar{v}(x)-u(x)| \mathrm{d} x\right) \\
& \quad \leqslant \omega^{\sigma}\left(R f_{B_{R}}|D \bar{v}(x)-D u(x)| \mathrm{d} x\right) \\
& \quad \leqslant \omega^{\sigma}\left[\left(R^{p} f_{B_{R}}|D \bar{v}(x)-D u(x)|^{p} \mathrm{~d} x\right)^{1 / p}\right] \\
& \quad \leqslant \omega^{\sigma}\left[\left(R^{p} f_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x\right)^{1 / p}\right] \\
& \quad \begin{array}{l}
(3.6) \\
\leqslant \\
\\
\quad \omega^{\sigma}\left\{\left[c R^{p}\left(f_{B_{2 R}}\left|\frac{u(x)-(u)_{2 R}}{R}\right|^{p} \mathrm{~d} x+f_{B_{2 R}}\left(1+|D \psi(x)|^{p}\right) \mathrm{d} x\right)\right]^{1 / p}\right\} \\
\quad \leqslant \omega^{\sigma}\left\{\left[c R^{p} f_{B_{2 R}}\left|\frac{u(x)-(u)_{2 R}}{R}\right|^{p} \mathrm{~d} x\right]^{1 / p}+c R\left[f_{B_{2 R}}(1+|D \psi(x)|)^{q} \mathrm{~d} x\right]^{1 / q}\right\} \\
\quad(3.16) \\
\quad \leqslant \omega^{\sigma}\left\{\left[R^{p}\left(\frac{[u]_{\gamma}^{p} R^{p \gamma}}{R^{p}}\right)\right]^{1 / p}+R\left(R^{\lambda-n}\right)^{1 / q}\right\} \\
\quad \leqslant c(p) \omega^{\sigma}\left[[u]_{\gamma} R^{\gamma}+R^{(q+\lambda-n) / q}\right] \leqslant c(p, \gamma) \omega^{\sigma}\left(R^{\tilde{m}}\right)
\end{array}
\end{aligned}
$$

where $\tilde{m}:=\min \{\gamma,(q+\lambda-n) / q\}$; we notice that, as we choose $\lambda>n-p$, we have $\tilde{m}>0$. So, finally

$$
I \leqslant c(p, \gamma) \omega^{\sigma}\left(R^{\tilde{m}}\right)\left[\int_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+R^{\lambda_{1}}\right]
$$

Now, using the minimality of $\bar{v}$, we get
$I I I \leqslant L \int_{B_{R}} \omega\left(\left|u(x)-(u)_{R}\right|\right)\left(\mu^{2}+|D \bar{v}(x)|^{2}\right)^{p / 2} \mathrm{~d} x \leqslant c(L) \omega\left(R^{\gamma}\right) \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x$.

In a similar way we estimate $I V$ :

$$
I V \leqslant L \int_{B_{R}} \omega\left(\left|u(x)-(u)_{R}\right|\right)\left(\mu^{2}+|D u(x)|^{2}\right)^{p / 2} \mathrm{~d} x \leqslant c(L) \omega\left(R^{\gamma}\right) \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x
$$

On the other hand,

$$
I I \leqslant L \int_{B_{R}} \omega\left(\left|x-x_{0}\right|\right)\left(\mu^{2}+|D \bar{v}(x)|^{2}\right)^{p / 2} \mathrm{~d} x \leqslant c(L) \omega(R) \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x
$$

also the estimate of $V$ is immediate:

$$
V \leqslant L \int_{B_{R}} \omega\left(\left|x-x_{0}\right|\right)\left(\mu^{2}+|D u(x)|^{2}\right)^{p / 2} \mathrm{~d} x \leqslant c(L) \omega(R) \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x
$$

Collecting the previous bounds and summing them up we get

$$
\begin{equation*}
I+I I+I I I+I V+V \leqslant c(L) \omega^{\sigma}\left(R^{\tilde{m}}\right)\left[\int_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+R^{\lambda_{1}}\right] \tag{5.6}
\end{equation*}
$$

## - Applying Ekeland's variational principle

At this point, by the minimality of $\bar{v}$, we obtain from (5.5) and (5.6)

$$
\mathcal{H}_{0}(u) \leqslant \inf _{V} \mathcal{H}_{0}+H(R)
$$

where we set

$$
H(R):=c(L) \omega^{\sigma}\left(R^{\tilde{m}}\right)\left[\int_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+R^{\lambda_{1}}\right]
$$

and

$$
V:=\left\{v \in u+W_{0}^{1,1}\left(B_{R}\right): v \in K\right\} .
$$

Now we are in the position to apply Theorem 1 in [7]. Let us consider $V$ equipped with the distance

$$
d\left(w_{1}, w_{2}\right):=H(R)^{-1 / p} R^{-n(p-1) / p} \int_{B_{R}}\left|D w_{1}(x)-D w_{2}(x)\right| \mathrm{d} x
$$

It is easy to see that the functional $\mathcal{H}_{0}$ is lower semicontinuous with respect to the topology induced by the distance $d$. Then by Theorem 1 in [7], it follows that there exists $v_{0} \in V$ such that
(i) $\int_{B_{R}}\left|D u(x)-D v_{0}(x)\right| \mathrm{d} x \leqslant[H(R)]^{1 / p} R^{n(p-1) / p}$,
(ii) $\mathcal{H}_{0}\left(v_{0}\right) \leqslant \mathcal{H}_{0}(u)$,
(iii) $v_{0}$ is a local minimizer in $V$ of the functional

$$
w \mapsto \mathcal{H}(w):=\mathcal{H}_{0}(w)+\left[\frac{H(R)}{R^{n}}\right]^{(p-1) / p} \int_{B_{R}}\left|D w-D v_{0}\right| \mathrm{d} x
$$

Working exactly as in [8], we get for $v_{0}$ the estimates

$$
\begin{gather*}
L^{-1} \int_{B_{R}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x \leqslant \mathcal{H}_{0}\left(v_{0}\right) \leqslant \mathcal{H}_{0}(u) \leqslant L \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x  \tag{5.7}\\
\quad\left(f_{B_{R / 2}}\left|D v_{0}(x)\right|^{s} \mathrm{~d} x\right)^{p / s} \leqslant c f_{B_{R}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x+c\left(1+\frac{H(R)}{R^{n}}\right) \tag{5.8}
\end{gather*}
$$

where $s \in(p, p(1+\delta))$; the latter estimate is a higher integrability result for $v_{0}$ : in fact, from (i), (ii) and (iii) of Ekeland's variational principle we can prove that $v_{0}$ is also a local quasi-minimizer of a suitable functional with standard growth.

## - Comparison and conclusion

Now we are ready to apply Proposition 5.2 to the function $h(z):=f\left(x_{0},(u)_{R}, z\right)$ and to the functional

$$
\mathcal{H}\left(w, B_{R}\right):=\mathcal{H}_{0}\left(w, B_{R}\right)+\left[\frac{H(R)}{R^{n}}\right]^{(p-1) / p} \int_{B_{R}}\left|D w(x)-D v_{0}(x)\right| \mathrm{d} x .
$$

We choose $A_{0}=F(R):=\omega^{\sigma}\left(R^{\tilde{m}}\right)$ in Proposition 5.2 , so, using the property (i) given by Ekeland's variational principle, we have for every $\beta>0$ and any $\varepsilon>0$

$$
\begin{aligned}
\int_{B_{\varrho}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x \leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n}+\varepsilon\right] \int_{B_{R}}\left(1+\left|D v_{0}(x)\right|^{p}\right) \mathrm{d} x \\
& +c[F(R)]^{p \beta} \int_{B_{R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x \\
& +c H(R)+c H(R)[F(R)]^{p \beta /(1-p)}+\bar{c} R^{\lambda}
\end{aligned}
$$

where the constants $c$ depend only on $L, p, \nu$ while the constant $\bar{c}$ depends also on $\varepsilon$. Now, for a suitable choice of $\beta$ and using (5.7), we can say that

$$
\int_{B_{\varrho}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+[F(R)]^{p \beta}+\varepsilon\right] \int_{B_{4 R}}\left(1+|D u(x)|^{p}\right) \mathrm{d} x+\bar{c} R^{\lambda}
$$

So summing up, we have for any $\varepsilon>0$

$$
\begin{aligned}
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant & c \int_{B_{\varrho}}\left|D v_{0}(x)\right|^{p} \mathrm{~d} x+c \int_{B_{\varrho}}\left|D u(x)-D v_{0}(x)\right|^{p} \mathrm{~d} x \\
\leqslant & c\left[\left(\frac{\varrho}{R}\right)^{n}+[F(R)]^{p \beta}+\varepsilon\right] \int_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x \\
& +\bar{c} R^{\lambda}+c \int_{B_{R / 2}}\left|D u(x)-D v_{0}(x)\right|^{p} \mathrm{~d} x
\end{aligned}
$$

where $c \equiv c(L, p, \nu)$ and $\bar{c} \equiv \bar{c}(L, p, \nu, \varepsilon)$.
In order to complete the proof we have to estimate the last term of the previous formula. We choose $\theta \in(0,1)$ such that $\theta / s+1-\theta=1 / p$ where $s$ is the higher integrability exponent of $v_{0}$. As $s \in(p, p(1+\delta))$, we get

$$
\begin{aligned}
& \int_{B_{R / 2}}\left|D u(x)-D v_{0}(x)\right|^{p} \mathrm{~d} x \\
& \leqslant c R^{n}\left(f_{B_{R / 2}}\left|D u(x)-D v_{0}(x)\right|^{s} \mathrm{~d} x\right)^{\theta p / s} \\
& \times\left(f_{B_{R / 2}}\left|D u(x)-D v_{0}(x)\right| \mathrm{d} x\right)^{(1-\theta) p} \\
&(\mathrm{i}) \\
& \leqslant c R^{n}\left[H(R)^{1 / p} R^{-n / p}\right]^{(1-\theta) p} \\
& \times\left[\left(f_{B_{R / 2}}|D u(x)|^{s} \mathrm{~d} x\right)^{\theta p / s}+\left(f_{B_{R / 2}}\left|D v_{0}(x)\right|^{s} \mathrm{~d} x\right)^{\theta p / s}\right] \\
&(5.7),(5.8) \\
& \leqslant c R^{n \theta}[H(R)]^{(1-\theta)} \\
& \times\left[\left(f_{B_{R / 2}}|D u(x)|^{p(1+\delta)} \mathrm{d} x\right)^{\theta /(1+\delta)}+\left(f_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+R^{\lambda_{1}-n}\right)^{\theta}\right] \\
&(3.5) c R^{n \theta}[H(R)]^{(1-\theta)}\left(f_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+R^{\lambda_{1}-n}\right)^{\theta} \\
& \leqslant c F(R)^{(1-\theta)}\left[\int_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+R^{\lambda_{1}}\right] .
\end{aligned}
$$

Now we can insert this estimate into the previous one and get for any $0<\varrho<R / 8$ and for any $\varepsilon>0$

$$
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant c\left[\left(\frac{\varrho}{R}\right)^{n}+[F(R)]^{p \beta}+[F(R)]^{(1-\theta)}+\varepsilon\right] \int_{B_{4 R}}|D u(x)|^{p} \mathrm{~d} x+\bar{c} R^{\lambda}
$$

where the constant $c$ depends only on $p, L, \nu$ while the constant $\bar{c}$ depends also on $\varepsilon$. Using Lemma 3.4 and the fact that $\lim _{R \rightarrow 0}[F(R)]^{p \beta}+[F(R)]^{(1-\theta)}=0$, we can choose a
radius $R_{1} \equiv R_{1}(p, L, \nu)>0$ and a constant $\varepsilon_{0}>0$ such that $[F(R)]^{p \beta}+[F(R)]^{(1-\theta)} \leqslant$ $\varepsilon_{0} / 2$ whenever $0<R<16 R_{1}$; so if also $\varepsilon \leqslant \varepsilon_{0} / 2$, we may conclude that

$$
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant \bar{c} \varrho^{\lambda}
$$

with $\bar{c} \equiv \bar{c}(p, L, \nu, \varepsilon)$ whenever $0<\varrho<R_{1}$, a fact which we may assume without loss of generality. This allows us to conclude that $D u \in L_{\mathrm{loc}}^{p, \lambda}(\Omega)$.

Remark 5.3. If one takes $\tilde{q}$ sufficiently small such that $p<\tilde{q}<p(1+\delta)$, where $\delta$ is the higher integrability exponent obtained for $D u$ in the proof of Theorem 2.9, then a higher integrability result

$$
f_{B_{\varrho}}|D u(x)|^{\tilde{q}} \mathrm{~d} x \leqslant c\left(f_{B_{2 \varrho}}|D u(x)|^{p} \mathrm{~d} x\right)^{\tilde{q} / p}+c f_{B_{2 \varrho}}\left(|D \psi(x)|^{\tilde{q}}+1\right) \mathrm{d} x
$$

can be obtained (in the same way as in the proof of Theorem 3.2). This inequality implies

$$
\begin{aligned}
& \varrho^{-\lambda} f_{B_{\varrho}}|D u(x)|^{\tilde{q}} \mathrm{~d} x \\
& \quad \leqslant c \varrho^{-\lambda}\left(f_{B_{2 \varrho}}|D u(x)|^{p} \mathrm{~d} x\right)^{\tilde{q} / p}+c \varrho^{-\lambda} f_{B_{2 \varrho}}\left(|D \psi(x)|^{\tilde{q}}+1\right) \mathrm{d} x \\
& \quad \leqslant c\left[\varrho^{-\lambda(p / \tilde{q})} f_{B_{2 \varrho}}|D u(x)|^{p} \mathrm{~d} x\right]^{\tilde{q} / p}+c \varrho^{-\lambda} f_{B_{2 \varrho}}\left(|D \psi(x)|^{\tilde{q}}+1\right) \mathrm{d} x \\
& \quad \leqslant c\left[\varrho^{\lambda(1-p / \tilde{q})} \varrho^{-\lambda} f_{B_{2 \varrho}}|D u(x)|^{p} \mathrm{~d} x\right]^{\tilde{q} / p}+c \varrho^{-\lambda} f_{B_{2 \varrho}}\left(|D \psi(x)|^{\tilde{q}}+1\right) \mathrm{d} x \\
& \quad \leqslant c \varrho^{\lambda(\tilde{q}-p) / p}\left[\varrho^{-\lambda} f_{B_{2 \varrho}}|D u(x)|^{p} \mathrm{~d} x\right]^{\tilde{q} / p}+c \varrho^{-\lambda} f_{B_{2 \varrho}}\left(|D \psi(x)|^{\tilde{q}}+1\right) \mathrm{d} x
\end{aligned}
$$

at this point, if $D \psi$ satisfies (2.5), i.e. if $D \psi \in L_{\mathrm{loc}}^{q, \lambda}(\Omega)$, then certainly $D \psi \in L_{\mathrm{loc}}^{\tilde{q}, \lambda}(\Omega)$ and therefore, by virtue of the estimates just obtained, also $D u \in L_{\text {loc }}^{\tilde{q}, \lambda}(\Omega)$ as $\tilde{q} / p>1$.

## 6. Proof of Theorem 2.11

Let $u$ be a local minimizer of the functional (1.1) in $K$; we fix a radius $R>0$ and any $x_{0} \in B_{4 R}$; let $v \in u+W_{0}^{1, p}\left(B_{R}\right)$ be a local minimizer in $K$ of the functional $\mathcal{H}_{0}$ introduced in (5.3). Moreover, let $z$ be the solution of the minimum problem

$$
\begin{equation*}
\min \left\{\mathcal{H}_{0}\left(z, B_{R}\right): z \in u+W_{0}^{1, p}\left(B_{R}\right)\right\} . \tag{6.1}
\end{equation*}
$$

Then, using estimates (2.4) and (2.5) in [17], we can easily obtain for all $0<\varrho<R / 2$

$$
\begin{aligned}
f_{B_{\varrho}}\left|D z(x)-(D z)_{\varrho}\right|^{p} \mathrm{~d} x & =f_{B_{\varrho}}\left|f_{B_{\varrho}}(D z(x)-D z(y)) \mathrm{d} y\right|^{p} \mathrm{~d} x \\
& \leqslant\left[\sup _{x, y \in B_{\varrho}}|D z(x)-D z(y)|\right]^{p} \leqslant\left[c\left(\frac{\varrho}{R}\right)^{\bar{\beta}} \sup _{B_{R / 2}}|D z|\right]^{p} \\
& \leqslant c\left(\frac{\varrho}{R}\right)^{\bar{\beta} p} f_{B_{R}}\left(1+|D z(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

where $c>0,0<\bar{\beta}<1$ and both $c$ and $\bar{\beta}$ depend only on $p, L$.
Our aim now is to compare $z$ and $w$. First of all, using the minimality of $z$, we have

$$
\int_{B_{R}}|D z(x)|^{p} \mathrm{~d} x \leqslant c(L) \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x
$$

On the other hand, Theorem 2.6 implies

$$
D \psi \in \mathcal{L}^{p, \lambda}(\Omega) \Rightarrow D \psi \in \mathcal{C}^{0, \alpha}(\Omega)
$$

where $\alpha=(\lambda-n) / p$. At this point, if $p \geqslant 2$ then it is not difficult to see that

$$
|A(D \psi(x))-A(D \psi(y))| \leqslant c|x-y|^{\alpha}, \quad \forall x, y \in \Omega
$$

Therefore we can estimate

$$
\begin{aligned}
& \int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \\
& \leqslant \int_{B_{R}}\left(1+|D w(x)|^{2}+|D z(x)|^{2}\right)^{(p-2) / 2}|D w(x)-D z(x)|^{2} \mathrm{~d} x \\
& \leqslant \int_{B_{R}}\langle A(D w(x))-A(D z(x)), D w(x)-D z(x)\rangle \mathrm{d} x \\
& \stackrel{(4.4)}{=} \int_{B_{R}}\langle A(D w(x)), D w(x)-D z(x)\rangle \mathrm{d} x
\end{aligned}
$$

$$
\begin{aligned}
& \stackrel{(4.1)}{=} \int_{B_{R}}\langle A(D \psi(x)), D w(x)-D z(x)\rangle \mathrm{d} x \\
& =\int_{B_{R}}\left\langle A(D \psi(x))-(A(D \psi))_{R}, D w(x)-D z(x)\right\rangle \mathrm{d} x \\
& \leqslant \int_{B_{R}}\left|A(D \psi(x))-(A(D \psi))_{R}\right| \cdot|D w(x)-D z(x)| \mathrm{d} x \\
& \leqslant c(L) R^{\alpha} \int_{B_{R}}\left(|D w(x)|^{p}+1\right) \mathrm{d} x .
\end{aligned}
$$

On the other hand, if $1<p<2$ we can easily prove that

$$
\begin{equation*}
|A(D \psi(x))-A(D \psi(y))| \leqslant c|x-y|^{\alpha(p-1)}, \quad \forall x, y \in \Omega \tag{6.2}
\end{equation*}
$$

where again $\alpha=(\lambda-n) / p$. This allows us to conclude that

$$
\begin{aligned}
\int_{B_{R}} & |D w(x)-D z(x)|^{p} \mathrm{~d} x \\
\leqslant & \left(\int_{B_{R}}\left(1+|D w(x)|^{2}+|D z(x)|^{2}\right)^{(p-2) / 2}|D w(x)-D z(x)|^{2} \mathrm{~d} x\right)^{1 / 2} \\
& \times\left(\int_{B_{R}}\left(1+|D w(x)|^{2}+|D z(x)|^{2}\right)^{(2-p) / 2}|D w(x)-D z(x)|^{2 p-2} \mathrm{~d} x\right)^{1 / 2} \\
\leqslant & c(L)\left[\int_{B_{R}}\left\langle A(D \psi(x))-(A(D \psi))_{R}, D w(x)-D z(x)\right\rangle \mathrm{d} x\right]^{1 / 2} \\
& \times\left(\int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x\right)^{1 / 2} \\
\leqslant & c(L) R^{\frac{1}{2} \alpha(p-1)} \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x
\end{aligned}
$$

So in both cases we deduce

$$
\int_{B_{R}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \leqslant c(L) R^{\frac{1}{2} \alpha(p-1)} \int_{B_{R}}\left(1+|D w(x)|^{p}\right) \mathrm{d} x .
$$

Moreover, using (3.2), (3.3) and (4.1) we are able to deduce

$$
\begin{aligned}
\int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x \stackrel{(3.2)}{\leqslant} & \frac{1}{\nu} \int_{B_{R}}\langle A(D w(x)), D w(x)\rangle \mathrm{d} x+c R^{n} \\
\stackrel{(4.1)}{\leqslant} & \frac{1}{\nu} \int_{B_{R}}\langle A(D w(x)), D v(x)\rangle \mathrm{d} x \\
& +\frac{1}{\nu} \int_{B_{R}}\langle A(D \psi(x)), D w(x)-D v(x)\rangle \mathrm{d} x+c R^{n}
\end{aligned}
$$

$$
\begin{aligned}
\stackrel{(3.3)}{\leqslant} & \frac{L}{\nu} \int_{B_{R}}\left(|D w(x)|^{p-1}+1\right)|D v(x)| \mathrm{d} x \\
& +\frac{1}{\nu} \int_{B_{R}}\langle A(D \psi(x)), D w(x)\rangle \mathrm{d} x \\
& -\frac{1}{\nu} \int_{B_{R}}\langle A(D \psi(x)), D v(x)\rangle \mathrm{d} x+c R^{n} \\
\leqslant & \frac{1}{4} \int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x+c \int_{B_{R}}|D v(x)|^{p} \mathrm{~d} x \\
& +\frac{1}{\nu} \int_{B_{R}}\left\langle A(D \psi(x))-(A(D \psi))_{R}, D w(x)\right\rangle \mathrm{d} x \\
& -\frac{1}{\nu} \int_{B_{R}}\left\langle A(D \psi(x))-(A(D \psi))_{R}, D v(x)\right\rangle \mathrm{d} x+c R^{n} \\
\leqslant & \frac{1}{4} \int_{B_{R}}\left(|D w(x)|^{p}+1\right) \mathrm{d} x+c \int_{B_{R}}\left(|D v(x)|^{p}+1\right) \mathrm{d} x+c R^{n}
\end{aligned}
$$

where we have used (6.2) which is valid for all $p>1$ and where the constants $c$ may depend on $L, p, \alpha, \nu$. Thus we obtain

$$
\int_{B_{R}}|D w(x)|^{p} \mathrm{~d} x \leqslant c(L, p, \alpha, \nu) \int_{B_{R}}\left(|D v(x)|^{p}+1\right) \mathrm{d} x
$$

Moreover, working as in the previous case, it is not difficult to deduce for all $p>1$

$$
\begin{equation*}
\int_{B_{R}}|D v(x)-D w(x)|^{p} \mathrm{~d} x \leqslant c(L, p, \alpha, \nu) R^{\frac{1}{2} \alpha(p-1)} \int_{B_{R}}\left(|D v(x)|^{p}+1\right) \mathrm{d} x \tag{6.3}
\end{equation*}
$$

Now it is time to compare $u$ and $v$. Proceeding as in the proof of Theorem 2.9 and using the assumption (2.7), we obtain
$\mathcal{H}_{0}(u)-\mathcal{H}_{0}(v) \leqslant c(L) \omega^{\sigma}\left(R^{\tilde{m}}\right) \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x \leqslant c(L) R^{\zeta} \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x$
where $\zeta \equiv \zeta(\gamma, \sigma, \xi, \lambda, p)$ and $\gamma, \sigma$ were introduced in the previous section. Arguing in a standard way, we immediately have

$$
\begin{equation*}
\int_{B_{R}}|D u(x)-D v(x)|^{p} \mathrm{~d} x \leqslant c(L) R^{\zeta / 2} \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x \tag{6.4}
\end{equation*}
$$

which holds for all $p>1$. Thus, summing up and setting

$$
M:=\min \left\{\frac{1}{2} \alpha(p-1), \frac{1}{2} \zeta\right\}
$$

we have for any $0<\varrho<R / 2$

$$
\begin{aligned}
& \int_{B_{\varrho}}\left|D u(x)-(D u)_{\varrho}\right|^{p} \mathrm{~d} x \leqslant \int_{B_{\varrho}}\left|D v(x)-(D v)_{\varrho}\right|^{p} \mathrm{~d} x+\int_{B_{\varrho}}|D u(x)-D v(x)|^{p} \mathrm{~d} x \\
& \leqslant \int_{B_{\varrho}}\left|D w(x)-(D w)_{\varrho}\right|^{p} \mathrm{~d} x+\int_{B_{R}}|D v(x)-D w(x)|^{p} \mathrm{~d} x \\
&+\int_{B_{R}}|D u(x)-D v(x)|^{p} \mathrm{~d} x \\
& \leqslant \int_{B_{\varrho}}\left|D z(x)-(D z)_{\varrho}\right|^{p} \mathrm{~d} x+\int_{B_{\varrho}}|D w(x)-D z(x)|^{p} \mathrm{~d} x \\
& \quad \begin{array}{l}
(6.3),(6.4) \\
+ \\
\\
\leqslant
\end{array} \\
& \leqslant \varrho^{n} f_{B_{\varrho}} \left\lvert\, D z(x, p, \alpha, \nu)\left(R^{\frac{1}{2} \alpha(p-1)}+R^{\frac{1}{2} \zeta}\right) \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x\right. \\
& \leqslant c(p, L)\left(\frac{\varrho}{R}\right)^{\bar{\beta} p}\left(\frac{\varrho}{R}\right)^{n} \int_{B_{R}}\left(1+|D z(x)|^{p}\right) \mathrm{d} x+c(L, p, \alpha, \nu) R^{M} \\
& \times \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x+c(L, p, \alpha, \nu) R^{M} \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x \\
& \leqslant c(L, p, \alpha, \nu)\left[\left(\frac{\varrho}{R}\right)^{\bar{\beta} p+n} \int_{B_{R}}\left(1+|D v(x)|^{p}\right) \mathrm{d} x+R^{M} \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x\right] \\
& \leqslant c(L, p, \alpha, \nu)\left[\left(\frac{\varrho}{R}\right)^{\bar{\beta} p+n}+R^{M}\right] \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x .
\end{aligned}
$$

On the other hand, using Theorem 3.1 we immediately get

$$
\int_{B_{\varrho}}|D u(x)|^{p} \mathrm{~d} x \leqslant c(L, p)\left[\left(\frac{\varrho}{R}\right)^{n}+R^{M}\right] \int_{B_{4 R}}\left(|D u(x)|^{p}+1\right) \mathrm{d} x
$$

then, by a standard iteration lemma, we are able to infer the existence of a radius $R_{0}$ such that for all $R \leqslant R_{0}$

$$
\int_{B_{R}}|D u(x)|^{p} \mathrm{~d} x \leqslant c R^{n-\tau}
$$

for all $0<\tau<1$. For our purposes, we can choose any $\tau<p \bar{\beta} M /(n+p \bar{\beta})$, for example $\tau:=\frac{1}{2} p \bar{\beta} M /(n+p \bar{\beta})$. At this point we choose $\varrho$ such that $\varrho=\frac{1}{2} R^{1+\theta}$ where $\theta:=M /(n+\bar{\beta} p)$. With such a choice of $\varrho, \theta$ and $\tau$, we have

$$
\begin{equation*}
\int_{B_{\varrho}}\left|D u(x)-(D u)_{\varrho}\right|^{p} \mathrm{~d} x \leqslant c(L, p, \alpha, \nu) \varrho^{\tilde{\lambda}} \tag{6.5}
\end{equation*}
$$

where

$$
\tilde{\lambda}:=n+\frac{p \bar{\beta} M}{2(n+p \bar{\beta}+M)} .
$$

However, the choice of $R$ was arbitrary, so without loss of generality we may assume that (6.5) holds for all $0<\varrho \leqslant R_{0}$. This yields the result.

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Author's address: M. Eleuteri, WIAS-Weierstrass Institute for Applied Analysis and Stochastics, Mohrenstrasse 39, 10117 Berlin, Germany, e-mail: eleuteri@wias-berlin.de; on leave from: Dipartimento di Matematica, Universitá di Trento, via Sommarive 14, 38050 Povo (Trento), Italy, e-mail: eleuteri@science.unitn.it.


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