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# SMOOTHED PROLONGATION MULTIGRID WITH RAPID COARSENING AND MASSIVE SMOOTHING* 

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## Dedicated to Soňa Krausová

Abstract. We prove that within the frame of smoothed prolongations, rapid coarsening between first two levels can be compensated by massive prolongation smoothing and preand post-smoothing derived from the prolongator smoother.

Keywords: smoothed prolongations, rapid coarsening, massive smoothing
MSC 2010: 35J25, 65M55

## 1. Introduction

In multigrid context, assuming no regularity it is impossible to improve convergence by adding more smoothing steps and therefore rapid coarsening cannot be compensated by massive smoothing. In this paper we show that this is possible if, alongside with adding more smoothing steps, also prolongator smoothing is performed. We prove that within the frame of smoothed prolongations ([5], [4], [6]), rapid coarsening between first two levels can be compensated by massive prolongation smoothing and pre- and post-smoothing derived from the prolongator smoother while preserving coarse-level matrices reasonably sparse. We prove an abstract convergence result and apply it to the simplest regular multigrid for the twodimensional model problem with $H_{0}^{1}$-equivalent form on a unit square. We prove a uniform

[^0]convergence result for the case that finest level prolongator smoother, pre- and postsmoothers are based on transformed Chebyshev polynomials in matrix $A$ of degree about $\frac{1}{2} h_{2} / h_{1}$, where $h_{1}$ and $h_{2}$ are resolutions on first and second level. By uniform convergence result we mean rate of convergence independent of $h_{1}, h_{2} / h_{1}$ and dependent linearly on number of levels as in [1]. In [3], we presented such result for variational two-level method. Here, we extend it to multigrid V-cycle with rapid coarsening between first two levels. Our theory is based on interpretation of a complex key result in [3] and is simpler and more general. Restriction to V-cycle is only for the sake of brevity and extension to W-cycle is trivial. Paper presupposes basic expertise in multigrid.

## 2. Algorithm

We are interested in solving the system of linear algebraic equations

$$
\begin{equation*}
A x=f \tag{2.1}
\end{equation*}
$$

where $A$ is an $n \times n$ symmetric positive definite matrix and $f \in \mathbb{R}^{n}$. Set $n_{1}=n$. We consider a standard variational multigrid V-cycle with prolongators

$$
\begin{equation*}
I_{l+1}^{l}: \mathbb{R}^{n_{l+1}} \rightarrow \mathbb{R}^{n_{l}}, \quad l=1, \ldots, L-1, n_{l+1}<n_{l} \tag{2.2}
\end{equation*}
$$

that is, the multigrid algorithm with coarse level matrices

$$
A_{l}=\left(I_{l}^{1}\right)^{\top} A I_{l}^{1}, \quad I_{l}^{1}=I_{2}^{1} \ldots I_{l}^{l-1} \quad \text { for } l>2 \text { and } I_{1}^{1}=I
$$

and restrictions given by the transpose of prolongators. With abstract convergence theory [1] in mind we define coarse spaces $U_{l}$, associated norms $\|\cdot\|_{l}$ and inner products $(\cdot, \cdot)_{l}$ by

$$
\begin{equation*}
U_{l}=\operatorname{Rng}\left(I_{l}^{1}\right), \quad(\cdot, \cdot)_{l}: I_{l}^{1} x, I_{l}^{1} y \mapsto \sum_{i=1}^{n_{l}} x_{i} y_{i} \quad \text { and } \quad\|\cdot\|_{l}=(\cdot, \cdot)_{l}^{1 / 2} \tag{2.3}
\end{equation*}
$$

In this paper we are interested in rapid coarsening between the first two levels compensated by massive prolongator smoothing and massive pre- and post-smoothing derived from the prolongator smoother. More specifically, we will investigate the multigrid V-cycle with the prolongator $I_{2}^{1}$ in the form

$$
I_{2}^{1}=S \tilde{I}_{2}^{1}, \quad \tilde{I_{2}^{1}}: \mathbb{R}^{n_{2}} \rightarrow \mathbb{R}^{n_{1}}, \quad n_{2} \ll n_{1}
$$

where the prolongator smoother $S$ is the tranformed Chebyshev polynomial in $A$ such that

$$
\begin{equation*}
\varrho\left(S^{2} A\right) \ll \varrho(A) . \tag{2.4}
\end{equation*}
$$

In what follows we assume that $S$ is a polynomial in A satisfying

$$
\begin{equation*}
\varrho(S) \leqslant 1 \tag{2.5}
\end{equation*}
$$

With (2.4) in mind a specific choice of the operator $S$ will be given in Section 4. On finest level we choose pre-smoother with error propagation operator $S$ and postsmoother with error propagation operator

$$
\begin{equation*}
S^{\prime}=I-\frac{\omega}{\varrho\left(A_{S}\right)} A_{S}, \quad A_{S}=S^{2} A, \omega \in(0,1) \tag{2.6}
\end{equation*}
$$

Note that resulting iteration can be implemented by formula

$$
x \leftarrow\left(I-\frac{\omega}{\varrho\left(A_{S}\right)} A_{S}\right) x+\frac{\omega}{\varrho\left(A_{S}\right)} S^{2} f .
$$

On other levels we choose both pre- and post-smoothers to be simple Jacobi iterations with error propagation operator

$$
\begin{equation*}
I-\frac{\omega}{\varrho\left(A_{l}\right)} A_{l} \tag{2.7}
\end{equation*}
$$

The choice of smoothers will be justified in next section. In Section 4 we propose operator $S$ in the form $S=\left(I-\alpha_{1} A\right) \ldots\left(I-\alpha_{d} A\right)$. Finest level pre-smoother can be then implemented as sequence of Jacobi sweeps $x \leftarrow\left(I-\alpha_{i} A\right) x+\alpha_{i} f, i=1, \ldots, d$. Note that smoothers (2.7) satisfy smoothing condition of [1].

## 3. Analysis

The error propagation operator of our algorithm is

$$
\begin{equation*}
E=S^{\prime}\left(I-I_{2}^{1} V_{2}\left(I_{2}^{1}\right)^{\top} A\right) S=S^{\prime}\left(I-S \tilde{I}_{2}^{1} V_{2}\left(S \tilde{I}_{2}^{1}\right)^{\top} A\right) S \tag{3.1}
\end{equation*}
$$

where $V_{2}$ is a single iteration of V-cycle on level 2 started from the zero approximation. By direct calculation,

$$
\begin{equation*}
E=S^{\prime} S\left(I-\tilde{I}_{2}^{1} V_{2}\left(\tilde{I}_{2}^{1}\right)^{\top} A_{S}\right)=S S^{\prime}\left(I-\tilde{I}_{2}^{1} V_{2}\left(\tilde{I}_{2}^{1}\right)^{\top} A_{S}\right) \tag{3.2}
\end{equation*}
$$

Let $u \in U_{1}$. It is well known that since both the pre- and post-smoothers on all coarse levels are simple Jacobi smoothers, the coarse-grid correction part of the error propagation operator of the variational multigrid V-cycle is A-symmetric and satisfies

$$
\left\|I-I_{2}^{1} V_{2}\left(I_{2}^{1}\right)^{\top} A\right\|_{A} \leqslant 1
$$

where $\|\cdot\|_{A}=(A \cdot, \cdot)_{1}^{1 / 2}$. Moreover, $\left\|S^{\prime}\right\|_{A} \leqslant 1$ and therefore by (3.1),

$$
\begin{equation*}
\|E u\|_{A} \leqslant\left\|S^{\prime}\right\|_{A}\left\|I-I_{2}^{1} V_{2}\left(I_{2}^{1}\right)^{\top} A\right\|_{A}\|S u\|_{A} \leqslant\|S u\|_{A} . \tag{3.3}
\end{equation*}
$$

Further, setting

$$
R=I-\tilde{I}_{2}^{1} V_{2}\left(\tilde{I}_{2}^{1}\right)^{\top} A_{S}
$$

and using (3.2) and (2.5), we get

$$
\begin{align*}
\frac{\|E u\|_{A}}{\|u\|_{A}}=\frac{\left\|S S^{\prime} R u\right\|_{A}}{\|u\|_{A_{S}}} \cdot \frac{\|u\|_{A_{S}}}{\|u\|_{A}} & =\frac{\left\|S^{\prime} R u\right\|_{A_{S}}}{\|u\|_{A_{S}}} \cdot \frac{\|S u\|_{A}}{\|u\|_{A}}  \tag{3.4}\\
& \leqslant \frac{\left\|S^{\prime}\left(I-\tilde{I}_{2}^{1} V_{2}\left(\tilde{I}_{2}^{1}\right)^{\top} A_{S}\right) u\right\|_{A_{S}}}{\|u\|_{A_{S}}}
\end{align*}
$$

where $\|\cdot\|_{A_{S}}=\left(A_{S} \cdot, \cdot\right)_{1}^{1 / 2}$. Let $t \in(0,1)$ be a given parameter. We set

$$
W=\left\{u \in U: \frac{\|S u\|_{A}}{\|u\|_{A}} \geqslant t\right\} .
$$

Note that

$$
\begin{equation*}
t\|u\|_{A} \leqslant\|u\|_{A_{S}}=\|S u\|_{A} \leqslant\|u\|_{A} \quad \text { for all } u \in W \tag{3.5}
\end{equation*}
$$

In view of (3.3) and (3.4) it becomes clear that to establish a convergence estimate for our method it is sufficient to estimate the term on the right-hand side of (3.4) for all $u \in W$. We will do so using the equivalence (3.5) as a key argument. Note that the term $S^{\prime}\left(I-\tilde{I}_{2}^{1} V_{2}\left(\tilde{I}_{2}^{1}\right)^{\top} A_{S}\right)$ on the right-hand side of (3.4) is an error propagation operator of the multigrid V-cycle for solving the problem with the smoothed matrix $A_{s}$, prolongators $\tilde{I}_{2}^{1}, I_{3}^{2}, \ldots, I_{L}^{L-1}$, Jacobi post-smoother $S^{\prime}$ on the finest level and simple Jacobi pre and post smoothers (2.7) on the other levels.

Theorem 3.1 ([1]). Let $E$ be the error propagation operator of the variational multigrid V-cycle algorithm for solving problem (2.1) with prolongators (2.2) and simple Jacobi pre- and/or post-smoothers (2.7) on all levels $l=1, \ldots, L-1$. Let $V \subset U_{1}$ be a subset. We assume that there are constants $C_{1}, C_{2}>0$ and linear mappings $Q_{l}: U_{1} \rightarrow U_{l}, l=2, \ldots, L, Q_{1}=I$ such that for every $u \in V$

$$
\begin{equation*}
\left\|\left(Q_{l}-Q_{l+1}\right) u\right\|_{l} \leqslant \frac{C_{1}}{\sqrt{\varrho\left(A_{l}\right)}}\|u\|_{A}, \quad l=1, \ldots, L-1 \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|Q_{l} u\right\|_{A} \leqslant C_{2}\|u\|_{A}, \quad l=1, \ldots, L . \tag{3.7}
\end{equation*}
$$

Then for every $u \in V$

$$
\|E u\|_{A} \leqslant 1-\frac{1}{C L}\|u\|_{A}, \quad \text { where } C=\left(1+C_{2}^{1 / 2}+\left(\frac{C_{1}}{\omega}\right)^{1 / 2}\right)^{2} .
$$

Proof. Proof follows by the original proof of [1].
We apply the above theorem, choosing $V=W$, to estimate the right-hand side of (3.4). Recall that the term

$$
S^{\prime}\left(I-\tilde{I}_{2}^{1} V_{2}\left(\tilde{I}_{2}^{1}\right)^{\top} A_{S}\right)
$$

is the variational multigrid V -cycle for solving the problem with the matrix $A_{S}$, prolongators $\tilde{I}_{2}^{1}, I_{3}^{2}, \ldots, I_{L}^{L-1}$ and Jacobi post-smoother (2.6) on the finest level and Jacobi pre- and post-smoothers (2.7) on the other levels. The coarse level matrices are given by

$$
\tilde{A}_{l}=\left(\tilde{I}_{l}^{1}\right)^{\top} A_{S} \tilde{I}_{l}^{1}, \quad l=1, \ldots, L
$$

where $\tilde{I}_{l}^{1}=\tilde{I}_{2}^{1} I_{3}^{2} \ldots I_{l}^{l-1}$ for $l>2, \tilde{I}_{1}^{1}=I$. Note that $\tilde{A}_{1}=A_{S}$ and $\tilde{A}_{l}=A_{l}$ for $l>1$. We define coarse spaces and associated norms by

$$
\tilde{U}_{l}=\operatorname{Rng}\left(\tilde{I}_{l}^{1}\right), \quad\|\cdot\|_{\tilde{U}_{l}}: \tilde{I}_{l}^{1} x \mapsto\left(\sum_{i=1}^{n_{l}} x_{i}^{2}\right)^{1 / 2}, \quad x \in \mathbb{R}^{n_{l}} .
$$

Note that $\tilde{U}_{1}=U_{1}=\mathbb{R}^{n_{1}}$.

Theorem 3.2. Assume there are constants $C_{1}, C_{2}>0$ and linear mappings $\tilde{Q}_{l}: \tilde{U}_{1} \rightarrow \tilde{U}_{l}, l=2, \ldots, L, \tilde{Q}_{1}=I$ such that for every $u \in \tilde{U}_{1}$

$$
\begin{equation*}
\left\|\left(\tilde{Q}_{l}-\tilde{Q}_{l+1}\right) u\right\|_{\tilde{U}_{l}} \leqslant \frac{C_{1}}{\sqrt{\varrho\left(\tilde{A}_{l}\right)}}\|u\|_{A}, \quad l=1, \ldots, L-1 \tag{3.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\tilde{Q}_{l}\right\|_{A} \leqslant C_{2}, \quad l=1, \ldots, L \tag{3.9}
\end{equation*}
$$

Then the error propagation operator $E$ of our method satisfies

$$
\begin{equation*}
\|E u\|_{A} \leqslant q\|u\|_{A} \quad \forall u \in \tilde{U}_{1} \tag{3.10}
\end{equation*}
$$

with a positive constant $q<1$ dependent only on $C_{1}, C_{2}$ and a parameter $\omega$ in (2.6) and (2.7).

Proof. Assume $u \notin W$. Then (3.10) follows by (3.3) with $q=t$. Let $u \in W$. We use Theorem 3.1 choosing $V=W$ to estimate the right-hand side of (3.4). We need to verify

$$
\begin{equation*}
\left\|\left(\tilde{Q}_{l}-\tilde{Q}_{l+1}\right) u\right\|_{\tilde{U}_{l}} \leqslant \frac{C_{a}}{\sqrt{\varrho\left(\tilde{A}_{l}\right)}}\|u\|_{A_{S}}, \quad l=1, \ldots, L-1 \tag{3.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\tilde{Q}_{l} u\right\|_{A_{S}} \leqslant C_{s}\|u\|_{A_{s}}, \quad l=1, \ldots, L \tag{3.12}
\end{equation*}
$$

for every $u \in W$. Using the equivalence (3.5), (3.11) follows from (3.8) with $C_{a}=$ $C_{1} / t$. Further, $\left\|\tilde{Q}_{l} u\right\|_{A_{s}}=\left\|S \tilde{Q}_{l} u\right\|_{A} \leqslant\left\|\tilde{Q}_{l} u\right\|_{A}$ and $\|u\|_{A_{S}} \geqslant t\|u\|_{A}$ from (3.5). Therefore,

$$
\frac{\left\|\tilde{Q}_{l} u\right\|_{A_{S}}}{\|u\|_{A_{S}}} \leqslant \frac{1}{t} \cdot \frac{\|\tilde{Q} u\|_{A}}{\|u\|_{A}}
$$

and (3.12) follows from (3.9) with $C_{s}=C_{2} / t$. Hence, by Theorem 3.1 we have the estimate (3.10) with

$$
q=1-\frac{1}{\left(1+\left(\frac{C_{2}}{t}\right)^{1 / 2}+\left(\frac{C_{1}}{\omega t}\right)^{1 / 2}\right)^{2} L}, \quad u \in W
$$

and for $u \notin W$ we have (3.10) with $q=t$, where $t$ is a paremeter we choose. Minimizing

$$
\min _{t \in(0,1)} \max \left\{t, q\left(C_{1}, C_{2}, \omega, t\right)\right\}
$$

eliminates the dependence of the estimate $q$ on $t$.

When proving convergence of the multigrid in case of rapid coarsening between levels 1 and 2 by means of Theorem 3.1, the critical issue is to verify the approximation condition (3.6) for $l=1$. If $\varrho\left(S^{2} A\right) \ll \varrho(A)$, the condition (3.8) is much easier to satisfy than (3.6).

## 4. Prolongator smoother

Lemma 4.1 ([2]). For any $\varrho>0$ and the integer $d>0$ there is a unique polynomial $p$ of degree $d$ such that

$$
\max \left\{p^{2}(\lambda) \lambda: 0 \leqslant \lambda \leqslant \varrho\right\}
$$

is minimal under the constraint $p(0)=1$. The polynomial $p$ is given by

$$
\begin{equation*}
p(\lambda)=\left(1-\frac{\lambda}{r_{1}}\right) \ldots\left(1-\frac{\lambda}{r_{d}}\right), \quad r_{k}=\frac{\varrho}{2}\left(1-\cos \frac{2 k \pi}{2 d+1}\right), \tag{4.1}
\end{equation*}
$$

$k=1, \ldots, d$. The polynomial $p$ satisfies

$$
\begin{equation*}
\max _{0 \leqslant \lambda \leqslant \varrho} p^{2}(\lambda) \lambda=\frac{\varrho}{(2 d+1)^{2}} \tag{4.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\max _{0 \leqslant \lambda \leqslant \varrho}|p(\lambda)|=1 \tag{4.3}
\end{equation*}
$$

We choose $S$ to be the polynomial (4.1) in $A$ with $\varrho=\varrho(A)$. For simplicity we assume that the spectral bound $\varrho(A)$ is available. To use the upper bound $\varrho=\bar{\varrho}$ satisfying

$$
\varrho(A) \leqslant \varrho \bar{\varrho} \leqslant C \varrho(A)
$$

represents a minimal technical problem.
Using the spectral mapping theorem and (4.3), we get (2.5). By the spectral mapping theorem and (4.2) we get

$$
\begin{equation*}
\varrho\left(A_{S}\right) \leqslant \frac{1}{(2 \operatorname{deg}(S)+1)^{2}} \varrho(A) . \tag{4.4}
\end{equation*}
$$

## 5. Application to Regular multigrid for Problem with $H_{0}^{1}$-EQUIVALENT FORM

The purpose of this section is to demonstrate the abstract result on the simplest possible nontrivial case. A more natural application to smoothed aggregation spaces will be published elsewhere.

Let $\Omega$ be unit square. We consider the second order elliptic problem

$$
\text { find } u \in H_{0}^{1}(\Omega) \text { such that } a(u, v)=(f, v)_{L^{2}(\Omega)} \quad \forall v \in H_{0}^{1}(\Omega)
$$

where $f \in L^{2}(\Omega)$ and the bilinear form $a(\cdot, \cdot)$ satisfies

$$
c\|u\|_{H^{1}(\Omega)}^{2} \leqslant a(u, u) \leqslant C\|u\|_{H^{1}(\Omega)}^{2} \quad \forall u \in H_{0}^{1}(\Omega)
$$

We assume a system of nested regular triangulations $\tau_{h_{l}}$ with meshsizes $h_{l}$, where

$$
h_{2}=N h_{1}, \quad h_{l+1}=2 h_{l}, \quad l=2, \ldots, L
$$

and $N, L$ are integers $N>2, L \geqslant 2$. Let $n_{l}$ be the number of interior vertices of $\tau_{h_{l}}$. On each level we consider the standard P1 finite element basis $\left\{\varphi_{i}^{l}\right\}_{i=1}^{n_{l}}$ and denote the corresponding finite element space by $V_{h_{l}}$. We assume the standard scaling $\left\|\varphi_{i}^{l}\right\|_{L^{\infty}(\Omega)}=1$. It is well known that the corresponding stiffness matrices satisfy

$$
\begin{equation*}
\varrho\left\{a\left(\varphi_{l}^{l}, \varphi_{j}^{l}\right), i, j=1, \ldots, n_{l}\right\} \leqslant C \tag{5.1}
\end{equation*}
$$

Here and in what follows $c, C$ are positive constants independent of the meshsize on any level and the number of levels. We assume that the prolongators $\tilde{I}_{2}^{1}, I_{3}^{2}, \ldots, I_{L}^{L-1}$ are constructed so that

$$
\Pi_{h} \tilde{I}_{l}^{1} e_{i}=\varphi_{i}^{l}, \quad i=1, \ldots, n_{l}, \quad \Pi_{h}: x \in \mathbb{R}^{n_{1}} \mapsto \sum_{i=1}^{n_{l}} x_{i} \varphi_{i}^{1}
$$

Here, $e_{i}$ denotes the $i$ th canonical basis vector. Note that

$$
V_{h_{l}}=\left\{\Pi_{h} u, u \in \tilde{U}_{l}\right\} \quad \text { and } \quad\left(\tilde{I}_{l}^{1}\right)^{\top} A\left(\tilde{I}_{l}^{1}\right)=\left\{a\left(\varphi_{l}^{l}, \varphi_{j}^{l}\right), i, j=1, \ldots, n_{l}\right\}
$$

In finite element stiffness matrices, $a_{i j} \neq 0$ if the vertex $j$ belongs to an element adjacent to the vertex $i$. Ussage of the prolongator smoother of degree 1 causes that the fill-in of all coarse level matrices $A_{l}$ increases; an entry $a_{i j}$ of $A_{l}, l=2, \ldots, L$ becomes nonzero if the vertex $j$ of $\tau_{h_{l}}$ belongs to two layers of elements adjacent to the vertex $i$. We choose the prolongator smoother $S$, of the largest degree such that
coarse-level matrices $A_{l}, l>1$, have such pattern. It is routine to verify that such degree is the nearest integer that is smaller or equal to $\frac{1}{2} h_{2} / h_{1}$. Then (4.4) and (5.1) give

$$
\begin{equation*}
\varrho\left(\tilde{A}_{1}\right)=\varrho\left(A_{s}\right) \leqslant C\left(\frac{h_{1}}{h_{2}}\right)^{2} . \tag{5.2}
\end{equation*}
$$

In what follows we will verify assumptions (3.8) and (3.9). We choose $\tilde{Q}_{l}, l=$ $2, \ldots, L$ so that $\Pi_{h} \tilde{Q}_{l}$ is the $L^{2}(\Omega)$-orthogonal projection onto $V_{h_{l}}$. The following are well-known properties of finite element functions:

$$
\begin{gather*}
c h_{l}\|u\|_{\tilde{U}_{l}} \leqslant\left\|\Pi_{h} u\right\|_{L^{2}(\Omega)} \leqslant C h_{l}\|u\|_{\tilde{U}_{l}}, \quad u \in \tilde{U}_{l},  \tag{5.3}\\
\left\|\Pi_{h}\left(I-\tilde{Q}_{l}\right) u\right\|_{L^{2}(\Omega)} \leqslant C h_{l}\left|\Pi_{h} u\right|_{H^{1}(\Omega)}, \quad u \in \tilde{U}_{1},  \tag{5.4}\\
\left|\Pi_{h} \tilde{Q}_{l} u\right|_{H^{1}(\Omega)} \leqslant C\left|\Pi_{h} u\right|_{H^{1}(\Omega)}, \quad u \in \tilde{U}_{1} . \tag{5.5}
\end{gather*}
$$

Clearly,

$$
\begin{equation*}
c\left|\Pi_{h} u\right|_{H^{1}(\Omega)} \leqslant a\left(\Pi_{h} u, \Pi_{h} u\right)=\|u\|_{A}^{2} \leqslant C\left|\Pi_{h} u\right|_{H^{1}(\Omega)}, \quad u \in \tilde{U}_{1} \tag{5.6}
\end{equation*}
$$

and (3.9) follows from (5.5).
Using (5.4) and the well-known properties of the orthogonal projections we get

$$
\left\|\Pi_{h}\left(\tilde{Q}_{l}-\tilde{Q}_{l+1}\right) u\right\|_{L^{2}(\Omega)} \leqslant\left\|\Pi_{h}\left(I-\tilde{Q}_{l+1}\right) u\right\|_{L^{2}(\Omega)} \leqslant C h_{l+1}\left|\Pi_{h} u\right|_{H^{1}(\Omega)}
$$

Hence by (5.3) and (5.6),

$$
\begin{equation*}
\left\|\left(\tilde{Q}_{l}-\tilde{Q}_{l+1}\right) u\right\|_{\tilde{U}_{l}} \leqslant C \frac{h_{l+1}}{h_{l}}\|u\|_{A} \tag{5.7}
\end{equation*}
$$

This together with (5.2) gives (3.8) for $l=1$. For $l>1$ we first estimate

$$
\varrho\left(\tilde{A}_{l}\right)=\sup \frac{\left(\tilde{I}_{l}^{1} x\right)^{\top} S^{2} A\left(\tilde{I}_{l}^{1} x\right)}{x^{\top} x} \leqslant \varrho\left(\left(I_{l}^{1}\right)^{\top} A I_{l}^{1}\right) .
$$

Since $\left(I_{l}^{1}\right)^{\top} A I_{l}^{1}$ is a stiffness matrix corresponding to the basis $\left\{\varphi_{i}^{l}\right\}$, the last inequality together with (5.1) gives

$$
\varrho\left(\tilde{A}_{l}\right) \leqslant \varrho\left(\left(I_{l}^{1}\right)^{\top} A I_{l}^{1}\right) \leqslant C \quad \text { for } l=2, \ldots, L
$$

This estimate, $h_{l+1}=2 h_{l}$ and (5.7) give (3.8) for $l>2$.

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