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## Kami Niedziałomski

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# ON THE GEOMETRY OF FRAME BUNDLES 

Kamil NiedZiaŁomski


#### Abstract

Let $(M, g)$ be a Riemannian manifold, $L(M)$ its frame bundle. We construct new examples of Riemannian metrics, which are obtained from Riemannian metrics on the tangent bundle TM. We compute the Levi-Civita connection and curvatures of these metrics.


## 1. Introduction

Let $(M, g)$ be a Riemannian manifold, $L(M)$ its frame bundle. The first example of a Riemannian metric on $L(M)$ was considered by Mok [12]. This metric, called the Sasaki-Mok metric or the diagonal lift $g^{d}$ of $g$, was also investigated in [5] and [6]. It is very rigid, for example, $\left(L(M), g^{d}\right)$ is never locally symmetric unless $(M, g)$ is locally Euclidean. Moreover, with respect to the Sasaki-Mok metric vertical and horizontal distributions are orthogonal. A wider and less rigid class of metrics $\bar{g}$, in which vertical and horizontal distributions are no longer orthogonal, has been recently considered by Kowalski and Sekizawa in the series of papers [9, 10, 11. These metrics are defined with respect to the decomposition of the vertical distribution $\mathcal{V}$ into $n=\operatorname{dim} M$ subdistributions $\mathcal{V}^{1}, \ldots, \mathcal{V}^{n}$.

In this short paper we introduce a new class of Riemannian metrics on the frame bundle. We identify distributions $\mathcal{V}^{i}$ with the vertical distribution in the second tangent bundle TTM. Namely, each map $R_{i}: L(M) \rightarrow T M, R_{i}\left(u_{1}, \ldots, u_{n}\right)=u_{i}$ induces a linear isomorphism $R_{i *}: \mathcal{H} \oplus \mathcal{V}^{i} \rightarrow T T M$, where $\mathcal{H}$ is a horizontal distribution defined by the Levi-Civita connection $\nabla$ on $M$. By this identification we pull-back the Riemannian metric from $T M$. We pull-back natural metrics, in the sense of Kowalski and Sekizawa [8], from TM and study the geometry of such Riemannian manifolds. We compute the Levi-Civita connection, the curvature tensor, sectional and scalar curvature.

## 2. Riemannian metrics on frame bundles

Let $(M, g)$ be a Riemannian manifold. Its frame bundle $L(M)$ consists of pairs $(x, u)$ where $x=\pi_{L(M)}(u) \in M$ and $u=\left(u_{1}, \ldots, u_{n}\right)$ is a basis of a tangent space

[^0]$T_{x} M$. We will write $u$ instead of $(x, u)$. Let $\left(x_{1}, \ldots, x_{n}\right)$ be a local coordinate system on $M$. Then, for every $i=1, \ldots, n$, we have
$$
u_{i}=\sum_{j} u_{i}^{j} \frac{\partial}{\partial x_{j}}
$$
for some smooth functions $u_{i}^{j}$ on $L(M)$. Putting $\alpha_{i}=x_{i} \circ \pi_{L(M)},\left(\alpha_{i}, u_{k}^{j}\right)$ is a local coordinate system on $L(M)$. Let $\omega$ be a connection form of $L(M)$ corresponding to Levi-Civita connection $\nabla$ on $M$. We have a decomposition of the tangent bundle $T L(M)$ into the horizontal and vertical distribution:
$$
T_{u} L(M)=\mathcal{H}_{u}^{L(M)} \oplus \mathcal{V}_{u}^{L(M)},
$$
where $\mathcal{H}^{L(M)}=\operatorname{ker} \omega$ and $\mathcal{V}^{L(M)}=\operatorname{ker} \pi_{L(M) *}$. Let $X_{u}^{h}$ denotes the horizontal lift of a vector $X \in T_{x} M, \pi_{L(M)}(u)=x$, to $\mathcal{H}_{u}^{L(M)}$.

Let $L_{u}: G L(n) \rightarrow L(M), L_{u}(a)=u a$, be a left multiplication of $a \in G L(n)$ by a basis $u \in L(M)$. Let $A_{u}^{*}=L_{u *}(A)$ be a fundamental vertical vector corresponding to a matrix $A \in \operatorname{gl}(n)$.

Denote by $\mathcal{V}^{i}$ a linear subspace of $\mathcal{V}^{L(M)}$ spanned by fundamental vertical vectors $A^{*}$, where the matrix $A \in \operatorname{gl}(n)$ has only nonzero $i$-th column.

For an index $i=1, \ldots, n$ define a map $R_{i}: L(M) \rightarrow T M$ as follows

$$
R_{i}(u)=u_{i}, \quad u=\left(u_{1}, \ldots, u_{n}\right) \in L(M) .
$$

$R_{i}$ is the right multiplication by a $i$-th vector of a canonical basis in $\mathbb{R}^{n}$.
We will need some basic facts about the second tangent bundle TTM. There is a decomposition of $T T M$ into horizontal and vertical part, $T_{\zeta} T M=\mathcal{H}_{\zeta}^{T M} \oplus \mathcal{V}_{\zeta}^{T M}$, with respect to the connection map $K: T T M \rightarrow T M$ and the projection in the tangent bundle $\pi_{T M}: T M \rightarrow M$, see for example [7]. Let $X_{\zeta}^{h, T M}$ and $X_{\zeta}^{v, T M}$ denote the horizontal and vertical lifts to $T_{\zeta} T M, \zeta \in T_{x} M$, of a vector $X \in T_{x} M$, respectively.

Proposition 2.1. The operator $R_{i}$ has the following properties.
(1) $R_{i *}$ is a linear isomorphism of $\mathcal{H}^{L(M)}$ onto $\mathcal{H}^{T M}$. Moreover,

$$
R_{\xi *} X^{h}=X^{h, T M}
$$

(2) $R_{i *}$ is a linear isomorphism of $\mathcal{V}^{i}$ onto $\mathcal{V}^{T M}$ and $R_{i *}$ is identically equal zero on $\mathcal{V}^{j}$ for $j \neq i$.
(3) There is a decomposition

$$
\mathcal{V}^{L(M)}=\mathcal{V}^{1} \oplus \ldots \oplus \mathcal{V}^{n}
$$

Proof. Easy computations left to the reader.
By Proposition 2.1, we have natural identifications

$$
\begin{equation*}
 \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
X \tag{2.2}
\end{equation*}
$$

Hence, we have defined the vertical lift $X_{u}^{v, i} \in \mathcal{V}_{u}^{i}, u \in L(M)$, of the vector $X \in T_{x} M, \pi_{L(M)}(u)=x$, satisfying the property

$$
R_{i *} X_{u}^{v, i}=X_{u_{i}}^{v, T M}
$$

Let $c=\left(c_{1}, \ldots, c_{n}\right) \in \mathbb{R}^{n}$ and $C=\left(c_{i j}\right)$ be $n \times n$ matrix. We assume that the $(n+1) \times(n+1)$ matrix

$$
\bar{C}=\left(\begin{array}{cc}
1 & c \\
c^{\top} & C
\end{array}\right)
$$

is symmetric and positive definite. Let $g_{T M}$ be a Riemannian metric on $T M$.
Now, we are able to define a new class of Riemannian metrics $\bar{g}=\bar{g}_{\bar{C}}$ on $L(M)$. Let $F: L(M) \rightarrow T M$ be any smooth function. Put

$$
\begin{aligned}
\bar{g}\left(X^{h}, Y^{h}\right)_{u} & =g_{T M}\left(X^{h, T M}, Y^{h, T M}\right)_{F(u)} \\
\bar{g}\left(X^{h}, Y^{v, i}\right)_{u} & =c_{i} g_{T M}\left(X^{h, T M}, Y^{v, T M}\right)_{F(u)} \\
\bar{g}\left(X^{v, i}, Y^{v, j}\right)_{u} & =c_{i j} g_{T M}\left(X^{v, T M}, Y^{v, T M}\right)_{F(u)}
\end{aligned}
$$

Fix $u \in L(M)$. Let $e_{1}, \ldots, e_{n}$ be a basis in $T_{x} M, \pi_{L(M)}(u)=x$, such that $\left(e_{1}\right)_{F(u)}^{h, T M}, \ldots,\left(e_{1}\right)_{F(u)}^{h, T M}$ is an orthonormal basis in $\mathcal{H}_{F(u)}^{T M}$. Then

$$
\begin{equation*}
e_{1}^{h}, \ldots, e_{n}^{h}, e_{1}^{v, 1}, \ldots, e_{n}^{v, 1}, \ldots, e_{1}^{v, n}, \ldots, e_{n}^{v, n} \tag{2.3}
\end{equation*}
$$

is a basis in $T_{u} L(M)$. Let $G$ be a matrix of the Riemannian metric $g_{T M}$ with respect to the basis $e_{1}^{h, T M}, \ldots, e_{n}^{h, T M}, e_{1}^{v, T M}, \ldots, e_{n}^{v, T M}$. The fact that $\bar{g}$ is positive definite follows from the following lemma.

Lemma 2.2. Let

$$
G=\left(\begin{array}{cc}
I & g^{h v} \\
g^{v h} & \hat{g}
\end{array}\right)
$$

be a positive definite symmetric $2 n \times 2 n$ block matrix. Then the matrix

$$
\bar{G}=\left(\begin{array}{cc}
I & c \otimes g^{v h} \\
c^{\top} \otimes g^{h v} & C \otimes \hat{g}
\end{array}\right)
$$

is positive definite.
Proof. It suffices to show that each principal minor $\bar{G}_{k}, k=1, \ldots, n+n^{2}$, of $\bar{G}$ is positive. Obviously $\operatorname{det} \bar{G}_{k}=1>0$ for $k=1, \ldots, n$. Hence we assume $k>n$. Then each minor $\bar{G}_{k}$ is of the same form as the whole matrix $\bar{G}$, thus we will make calculations using matrix $\bar{G}$. Computing the determinant of the block matrix we get

$$
\begin{aligned}
\operatorname{det} \bar{G} & =\operatorname{det}\left(C \otimes \hat{g}-\left(c^{\top} \otimes g^{v h}\right)\left(c \otimes g^{h v}\right)\right) \\
& =\operatorname{det}\left(C \otimes \hat{g}-\left(c^{\top} c\right) \otimes\left(g^{v h} g^{h v}\right)\right) \\
& =\operatorname{det}\left(\left(C-c^{\top} c\right) \otimes \hat{g}+\left(c^{\top} c\right) \otimes\left(\hat{g}-g^{v h} g^{h v}\right)\right)
\end{aligned}
$$

Since

$$
\begin{aligned}
& \operatorname{det}\left(C-c^{\top} c\right)=\operatorname{det} \bar{C}>0 \\
& \operatorname{det} \hat{g}>0 \\
& \operatorname{det}\left(c^{\top} c\right) \geq 0 \\
& \operatorname{det}\left(\hat{g}-g^{v h} g^{h v}\right)=\operatorname{det} G>0
\end{aligned}
$$

it follows that matrices $\left(C-c^{\top} c\right) \otimes \hat{g}$ and $\left(c^{\top} c\right) \otimes\left(\hat{g}-g^{v h} g^{h v}\right)$ are positive definite. Hence theirs sum is positive definite.

If $\bar{C}=I$ and $g_{T M}$ is the Sasaki metric, then we get Sasaki-Mok metric.
Assume now $C=I$ and $g_{T M}$ is a natural Riemannian metric on $T M$ [8, 1] such that $g_{T M}\left(X^{h}, Y^{h}\right)=g(X, Y)$ and distributions $\mathcal{H}^{T M}, \mathcal{V}^{T M}$ are orthogonal. Hence, there are two smooth real functions $\alpha, \beta:[0, \infty) \rightarrow \mathbb{R}$ such that

$$
\begin{align*}
\bar{g}\left(X^{h}, Y^{h}\right)_{u}= & g(X, Y) \\
\bar{g}\left(X^{h}, Y^{v, i}\right)_{u}= & 0, \\
\bar{g}\left(X^{v, i}, Y^{v, j}\right)_{u}= & 0, \quad i \neq j  \tag{2.4}\\
\bar{g}\left(X^{v, i}, Y^{v, i}\right)_{u}= & \alpha\left(|F(u)|^{2}\right) g(X, Y) \\
& +\beta\left(|F(u)|^{2}\right) g(X, F(u)) g(Y, F(u)) .
\end{align*}
$$

The above Riemannian metric does not "see" the index $i$ of the distribution $\mathcal{V}^{i}$. Since all distributions $\mathcal{H}^{L(M)}, \mathcal{V}^{1}, \ldots, \mathcal{V}^{n}$ are orthogonal, it follows that we may put $F_{i}(u)=u_{i}$ in the last condition, that is consider a family of maps $F_{1}, \ldots, F_{n}$ rather than one map $F$. Then we obtain the positive definite bilinear form, hence the Riemannian metric, of the form

$$
\begin{align*}
\bar{g}\left(X^{h}, Y^{h}\right)_{u} & =g(X, Y), \\
\bar{g}\left(X^{h}, Y^{v, i}\right)_{u} & =0, \\
\bar{g}\left(X^{v, i}, Y^{v, j}\right)_{u} & =0, \quad i \neq j,  \tag{2.5}\\
\bar{g}\left(X^{v, i}, Y^{v, i}\right)_{u} & =\alpha\left(\left|u_{i}\right|^{2}\right) g(X, Y)+\beta\left(\left|u_{i}\right|^{2}\right) g\left(X, u_{i}\right) g\left(Y, u_{i}\right) .
\end{align*}
$$

Now, we define functions $\alpha_{i}, \alpha_{i}^{\prime}: L(M) \rightarrow \mathbb{R}$ etc. as follows

$$
\alpha_{i}(u)=\alpha\left(\left|u_{i}\right|^{2}\right), \quad \alpha_{i}^{\prime}(u)=\alpha^{\prime}\left(\left|u_{i}\right|^{2}\right), \quad \text { etc. }
$$

To make the formulas in the next section more concise, we will write $\alpha_{i}, \alpha_{i}^{\prime}$ etc. instead of $\alpha\left(\left|u_{i}\right|^{2}\right), \alpha^{\prime}\left(\left|u_{i}\right|^{2}\right)$ etc.

## 3. Geometry of $\bar{g}$

Let $(M, g)$ be a Riemannian manifold, $(L(M), \bar{g})$ its frame bundle equipped with the metric $\bar{g}$ of the form 2.5 . Let $\bar{\nabla}$ and $\bar{R}$ denote the Levi-Civita connection and the curvature tensor of $\bar{g}$, respectively.

We recall the identities concerning Lie bracket of horizontal and vertical vector fields [9]

$$
\begin{align*}
{\left[X^{h}, Y^{h}\right]_{u} } & =[X, Y]_{u}^{h}-\sum_{i}\left(R(X, Y) u_{i}\right)^{v, i} \\
{\left[X^{h}, Y^{v, i}\right]_{u} } & =\left(\nabla_{X} Y\right)_{u}^{v, i}  \tag{3.1}\\
{\left[X^{v, i}, Y^{v, j}\right]_{u} } & =0
\end{align*}
$$

Moreover, in the local coordinates, for $X=\sum_{i} \xi_{i} \frac{\partial}{\partial x_{i}}$ we have

$$
\begin{align*}
X^{h}\left(u_{i}^{j}\right) & =-\sum_{a, b} \Gamma_{a b}^{j} u_{i}^{a} \xi_{b}  \tag{3.2}\\
X^{v, k}\left(u_{i}^{j}\right) & =\xi_{j} \delta_{i k} \tag{3.3}
\end{align*}
$$

where $\Gamma_{a b}^{j}$ are Christoffel's symbols [9].
Proposition 3.1. Connection $\bar{\nabla}$ satisfies the following relations

$$
\begin{aligned}
\left(\bar{\nabla}_{X^{h}} Y^{h}\right)_{u}= & \left(\nabla_{X} Y\right)_{u}^{h}-\frac{1}{2} \sum_{i}\left(R(X, Y) u_{i}\right)_{u}^{v, i} \\
\left(\bar{\nabla}_{X^{h}} Y^{v, i}\right)_{u}= & \frac{\alpha_{i}}{2}\left(R\left(u_{i}, Y\right) X\right)_{u}^{h}+\left(\nabla_{X} Y\right)_{u}^{v, i} \\
\left(\bar{\nabla}_{X^{v, i}} Y^{h}\right)_{u}= & \frac{\alpha_{i}}{2}\left(R\left(u_{i}, X\right) Y\right)_{u}^{h} \\
\left(\bar{\nabla}_{X^{v, i}} Y^{v, j}\right)_{u}= & 0 \quad i \neq j \\
\left(\bar{\nabla}_{X^{v, i}} Y^{v, i}\right)_{u}= & \frac{\alpha_{i}^{\prime}}{\alpha_{i}}\left(g\left(X, u_{i}\right) Y_{u}^{v, i}+g\left(Y, u_{i}\right) X_{u}^{v, i}\right) \\
& +\left(\frac{\beta_{i}^{\prime} \alpha_{i}-2 \alpha_{i}^{\prime} \beta_{i}}{\alpha_{i}\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)} g\left(X, u_{i}\right) g\left(Y, u_{i}\right)+\frac{\beta_{i}-\alpha_{i}^{\prime}}{\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}} g(X, Y)\right) U_{u}^{i}
\end{aligned}
$$

where $U_{u}^{i}=u_{i}^{v, i}$.
Proof. Follows from the formula for the Levi-Civita connection

$$
\begin{aligned}
2 \bar{g}\left(\bar{\nabla}_{A} B, C\right)= & A \bar{g}(B, C)+B \bar{g}(A, C)-C \bar{g}(A, B) \\
& +\bar{g}([A, C], B)+\bar{g}([B, C], A)+\bar{g}([A, B], C)
\end{aligned}
$$

relations (3.1) and the following equalities

$$
\begin{aligned}
X_{u}^{v, i}\left(g\left(u_{i}, Y\right)\right) & =g(X, Y) \\
X_{u}^{v, i}\left(\left|u_{i}\right|^{2}\right) & =2 g\left(X, u_{i}\right) \\
X_{u}^{h}\left(g\left(u_{i}, Y\right)\right) & =g\left(u_{i}, \nabla_{X} Y\right) .
\end{aligned}
$$

Before we compute the curvature tensor, we will need some formulas concerning the Levi-Civita connection $\bar{\nabla}$ of certain vector fields.

Lemma 3.2. The following equalities hold

$$
\begin{aligned}
\left(\bar{\nabla}_{X^{h}} U^{i}\right)_{u} & =0, \\
\left(\bar{\nabla}_{X^{v, i}} U^{j}\right)_{u} & =0 \quad i \neq j \\
\left(\bar{\nabla}_{X^{v, i}} U^{i}\right)_{u} & =\frac{\alpha_{i}+\left|u_{i}\right|^{2} \alpha_{i}^{\prime}}{\alpha_{i}} X_{u}^{v, i}+\frac{\left|u_{i}\right|^{2}\left(\alpha_{i} \beta_{i}^{\prime}-\alpha_{i}^{\prime} \beta_{i}\right)+\alpha_{i} \beta_{i}}{\alpha_{i}\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)} g\left(X, u_{i}\right) U_{u}^{i} .
\end{aligned}
$$

and

$$
\left(\bar{\nabla}_{W}\left(R\left(u_{i}, X\right) Y\right)^{Q}\right)_{u}=\sum_{j} W\left(u_{i}^{j}\right)\left(R\left(u_{i}, X\right) Y\right)_{u}^{Q}+\sum_{j} u_{i}^{j}\left(\bar{\nabla}_{W}\left(R\left(\frac{\partial}{\partial x_{j}}, X\right) Y\right)^{Q}\right)_{u}
$$

for any $W \in T L(M)$, where $Q$ denotes the horizontal or vertical lift.
Proof. Follows by standard computations in local coordinates.
Proposition 3.3. The curvature tensor $\bar{R}$ at $u \in L(M)$ satisfies the following relations

$$
\begin{aligned}
\bar{R}\left(X^{h}, Y^{h}\right) Z^{h}= & (R(X, Y) Z)^{h}+\frac{1}{2} \sum_{i}\left(\left(\nabla_{Z} R\right)(X, Y) u_{i}\right)^{v, i} \\
& -\frac{1}{4} \sum_{i} \alpha_{i}\left(R\left(u_{i}, R(Y, Z) u_{i}\right) X-R\left(u_{i}, R(X, Z) u_{i}\right) Y\right. \\
& \left.-2 R\left(u_{i}, R(X, Y) u_{i}\right) Z\right)^{h}
\end{aligned}
$$

$$
\begin{aligned}
\bar{R}\left(X^{h}, Y^{h}\right) Z^{v, i}= & (R(X, Y) Z)^{v, i}+\frac{\alpha_{i}}{2}\left(\left(\nabla_{X} R\right)\left(u_{i}, Z\right) Y-\left(\nabla_{Y} R\right)\left(u_{i}, Z\right) X\right)^{h} \\
& -\frac{\alpha_{i}}{4} \sum_{j}\left(R\left(X, R\left(u_{i}, Z\right) Y\right) u_{j}-R\left(Y, R\left(u_{i}, Z\right) X\right) u_{j}\right)^{v, j} \\
& +\frac{\alpha_{i}^{\prime}}{\alpha_{i}} g\left(Z, u_{i}\right)\left(R(X, Y) u_{i}\right)^{v, i}-\frac{\beta_{i}-\alpha_{i}^{\prime}}{\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}} g\left(R(X, Y) Z, u_{i}\right) U^{i}, \\
\bar{R}\left(X^{h}, Y^{v, i}\right) Z^{h}= & \frac{\alpha_{i}}{2}\left(\left(\nabla_{X} R\right)\left(u_{i}, Y\right) Z\right)^{h}-\frac{1}{2}(R(Z, X) Y)^{v, i} \\
& +\frac{\alpha_{i}^{\prime}}{2 \alpha_{i}} g\left(Y, u_{i}\right)\left(R(X, Z) u_{i}\right)^{v, i}-\frac{\alpha_{i}}{4} \sum_{j}\left(R\left(X, R\left(u_{i}, Y\right) Z\right) u_{j}\right)^{v, j} \\
& -\frac{\beta_{i}-\alpha_{i}^{\prime}}{2\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)} g\left(R(X, Z) Y, u_{i}\right) U^{i}
\end{aligned}
$$

$$
\begin{aligned}
\bar{R}\left(X^{h}, Y^{v, i}\right) Z^{v, j}= & -\frac{\alpha_{i} \alpha_{j}}{4}\left(R\left(u_{i}, Y\right) R\left(u_{j}, Z\right) X\right)^{h} \\
\bar{R}\left(X^{h}, Y^{v, i}\right) Z^{v, i}= & \frac{\alpha_{i}^{\prime}}{2}\left(g\left(Z, u_{i}\right) R\left(u_{i}, Y\right) X-g\left(Y, u_{i}\right) R\left(u_{i}, Z\right) X\right)^{h} \\
& -\frac{\alpha_{i}^{2}}{4}\left(R\left(u_{i}, Y\right) R\left(u_{i}, Z\right) X\right)^{h}-\frac{\alpha_{i}}{2}(R(Y, Z) X)^{h} \\
\bar{R}\left(X^{v, i}, Y^{v, i}\right) Z^{h}= & \alpha_{i}(R(X, Y) Z)^{h} \\
& +\frac{\alpha_{i}^{2}}{4}\left(R\left(u_{i}, X\right) R\left(u_{i}, Y\right) Z-R\left(u_{i}, Y\right) R\left(u_{i}, X\right) Z\right)^{h} \\
& +\alpha_{i}^{\prime}\left(g\left(X, u_{i}\right)\left(R\left(u_{i}, Y\right) Z\right)^{h}-g\left(Y, u_{i}\right)\left(R\left(u_{i}, X\right) Z\right)^{h}\right) \\
\bar{R}\left(X^{v, i}, Y^{v, j}\right) Z^{h}= & \frac{\alpha_{i} \alpha_{j}}{4}\left(R\left(u_{i}, X\right) R\left(u_{j}, Y\right) Z-R\left(u_{j}, Y\right) R\left(u_{i}, X\right) Z\right)^{h} \\
\left.\bar{R}\left(X^{v, i}, Y^{v, i}\right) Z^{v, i}\right)= & C_{i}\left(g\left(X, u_{i}\right) g(Y, Z)-g\left(Y, u_{i}\right) g(X, Z)\right) U^{i} \\
& +\left(A_{i} g\left(Y, u_{i}\right) g\left(Z, u_{i}\right)+B_{i} g(Y, Z)\right) X^{v, i} \\
& -\left(A_{i} g\left(X, u_{i}\right) g\left(Z, u_{i}\right)+B_{i} g(X, Z)\right) Y^{v, i} \\
\bar{R}\left(X^{v, i}, Y^{v, j}\right) Z^{v, k}= & 0 \quad \text { if } \sharp\{i, j, k\}>1
\end{aligned}
$$

where

$$
\begin{aligned}
A_{i}= & \frac{3\left(\alpha_{i}^{\prime}\right)^{2}-2 \alpha_{i} \alpha_{i}^{\prime \prime}}{\alpha_{i}^{2}}+\frac{\left(\alpha_{i} \beta_{i}^{\prime}-2 \alpha_{i}^{\prime} \beta_{i}\right)\left(\alpha_{i}+\left|u_{i}\right|^{2} \alpha_{i}^{\prime}\right)}{\alpha_{i}^{2}\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)} \\
B_{i}= & \frac{\alpha_{i} \beta_{i}-2 \alpha_{i} \alpha_{i}^{\prime}-\left(\alpha_{i}^{\prime}\right)^{2}\left|u_{i}\right|^{2}}{\alpha_{i}\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)}, \\
C_{i}= & -\frac{2 \alpha_{i}^{\prime \prime}}{\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}} \\
& +\frac{3 \alpha_{i}\left(\alpha_{i}^{\prime}\right)^{2}+2\left(\alpha_{i}^{\prime}\right)^{2} \beta_{i}\left|u_{i}\right|^{2}+\alpha_{i}^{2} \beta_{i}^{\prime}-\alpha_{i} \beta_{i}^{2}+\alpha_{i} \alpha_{i}^{\prime} \beta_{i}^{\prime}\left|u_{i}\right|^{2}}{\left.\alpha_{i}\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)^{2}\right)}
\end{aligned}
$$

Proof. Follows from the characterization of the Levi-Civita connection $\bar{\nabla}$ and Lemma 3.2

Remark 3.4. Notice that

$$
A_{i} \alpha_{i}-B \beta_{i}=C_{i}\left(\alpha_{i}+\left|u_{i}\right|^{2} \beta_{i}\right)
$$

which is equivalent to the condition

$$
\bar{g}\left(\bar{R}\left(X^{v, i}, Y^{v, i}\right) Z^{v, i}, W^{v, i}\right)=\bar{g}\left(\bar{R}\left(Z^{v, i}, W^{v, i}\right) X^{v, i}, Y^{v, i}\right) .
$$

Corollary 3.5. Let $X, Y$ be two orthonormal vectors in the tangent space $T_{x} M$. Then the scalar curvature $\bar{K}$ of $(L(M), \bar{g})$ at $u \in L(M), \pi_{L(M)}(u)=x$, and $K$ of
$(M, g)$ at $x \in M$ are related as follows

$$
\begin{aligned}
\bar{K}\left(X^{h}, Y^{h}\right) & =K(X, Y)-\frac{3}{4} \sum_{i} \alpha_{i}\left|R(X, Y) u_{i}\right|^{2}, \\
\bar{K}\left(X^{h}, Y^{v, i}\right) & =\frac{\alpha_{i}^{2}}{4\left(\alpha_{i}+\beta_{i} g\left(Y, u_{i}\right)^{2}\right)}\left|R\left(u_{i}, Y\right) X\right|^{2}, \\
\bar{K}\left(X^{v, i}, Y^{v, i}\right) & =\frac{A_{i}\left(g\left(X, u_{i}\right)^{2}+g\left(Y, u_{i}\right)^{2}\right)+B_{i}}{\alpha_{i}+\beta_{i}\left(g\left(X, u_{i}\right)^{2}+g\left(Y, u_{i}\right)^{2}\right)}, \\
\bar{K}\left(X^{v, i}, Y^{v, j}\right) & =0 \quad i \neq j .
\end{aligned}
$$

Corollary 3.6. If $(M, g)$ is of constant sectional curvature $\kappa$, then

$$
\begin{aligned}
\bar{K}\left(X^{h}, Y^{h}\right) & =\kappa-\frac{3}{4} \kappa^{2} \sum_{i} \alpha_{i}\left(g\left(X, u_{i}\right)^{2}+g\left(Y, u_{i}\right)^{2}\right) \\
\bar{K}\left(X^{h}, Y^{v, i}\right) & =\frac{\kappa^{2} \alpha_{i}^{2} g\left(X, u_{i}\right)^{2}}{4\left(\alpha_{i}+\beta_{i} g\left(Y, u_{i}\right)\right)} \geq 0
\end{aligned}
$$

If, in addition, $\sum_{i} \alpha\left(t_{i}\right) t_{i}<\frac{4}{3 \kappa}$ for all $t_{i}>0$, then $\bar{K}\left(X^{h}, Y^{h}\right)>0$.
Proof of Corollary 3.5 and 3.6. The formula for $\bar{K}$ follows by Proposition 3.3 Assume now $(M, g)$ is of constant sectional curvature $\kappa$ and $\sum_{i} \alpha\left(t_{i}\right) t_{i}<\frac{4}{3 \kappa}$ for all $t_{i}>0$. Since $g\left(X, u_{i}\right)^{2}+g\left(Y, u_{i}\right)^{2} \leq\left|u_{i}\right|^{2}$, then

$$
\bar{K}\left(X^{h}, Y^{h}\right) \geq \kappa-\frac{3}{4} \kappa^{2} \sum_{i} \alpha_{i}\left|u_{i}\right|^{2}>0
$$

Corollary 3.7. The scalar curvature $\bar{s}$ of $(L(M), \bar{g})$ at $u \in L(M)$ is of the form

$$
\bar{s}=s-\frac{1}{4} \sum_{i, j, k} \alpha_{k}\left|R\left(e_{i}, e_{j}\right) u_{k}\right|^{2}+(n-1) \sum_{k} \frac{2\left|u_{k}\right|^{2} C_{k}+n B_{k}}{\alpha_{k}}
$$

where $s$ is the scalar curvature of $(M, g)$ at $x \in M$ and $e_{1}, \ldots, e_{n}$ is an orthonormal basis in $T_{x} M, \pi_{L(M)}(u)=x$.

Proof. Fix $u \in L(M)$ and let $e_{1}, \ldots, e_{n}$ be an orthonormal basis in $T_{x} M, \pi_{L(M)}(u)=$ $x$. Consider a basis of $T_{u} L(M)$ of the form (2.3). Put

$$
\bar{g}_{i j}^{k}=\bar{g}\left(e_{i}^{v, k}, e_{j}^{v, k}\right)=\alpha_{k} \delta_{i j}+\beta_{k} g\left(e_{i}, u_{k}\right) g\left(e_{j}, u_{k}\right)
$$

The inverse matrix $\left(\bar{g}_{k}^{i j}\right)$ to $\left(\bar{g}_{i j}^{k}\right)$ is the following

$$
\bar{g}_{k}^{i j}=\frac{1}{\alpha_{k}} \delta_{i j}-\frac{\beta_{k}}{\alpha_{k}\left(\alpha_{k}+\left|u_{k}\right|^{2} \beta_{k}\right)} g\left(e_{i}, u_{k}\right) g\left(e_{j}, u_{k}\right) .
$$

Hence

$$
\begin{aligned}
\bar{s}= & \sum_{i, j} \bar{g}\left(\bar{R}\left(e_{i}^{h}, e_{j}^{h}\right) e_{j}^{h}, e_{i}^{h}\right)+2 \sum_{i, j, l, k} \bar{g}_{k}^{j l} \bar{g}\left(\bar{R}\left(e_{i}^{h}, e_{j}^{v, k}\right) e_{l}^{v, k}, e_{i}^{h}\right) \\
& +\sum_{i, j, k, l, p} \bar{g}_{k}^{i p} \bar{g}_{k}^{j l} \bar{g}\left(\bar{R}\left(e_{i}^{v, k}, e_{j}^{v, k}\right) e_{l}^{v, k}, e_{p}^{v, k}\right)
\end{aligned}
$$

The formula for $\bar{s}$ follows now by Proposition 3.3 Remark 3.4 and the equality

$$
\left.\sum_{i, j}\left|R\left(e_{i}, e_{j}\right) u_{k}\right|^{2}=\sum_{i, j} \mid R\left(u_{k}, e_{j}\right) e_{i}\right)\left.\right|^{2}
$$

In the end, we show that, in the case of a Cheeger-Gromoll type metric over the manifold of constant sectional curvature, the sectional curvature of $L(M)$ is nonnegative.

Corollary 3.8. Assume

$$
\alpha(t)=\beta(t)=\frac{1}{1+t}, \quad t>0
$$

Then

$$
\bar{K}\left(X^{v, i}, Y^{v, i}\right)=\frac{-\left|u_{i}\right|^{2}\left(g\left(X, u_{i}\right)^{2}+g\left(Y, u_{i}\right)^{2}\right)+\left|u_{i}\right|^{4}+3\left|u_{i}\right|^{2}+3}{\left(1+\left|u_{i}\right|^{2}\right)^{2}\left(1+g\left(X, u_{i}\right)^{2}+g\left(Y, u_{i}\right)^{2}\right)} .
$$

In particular, if $(M, g)$ is of constant sectional curvature $0<\kappa<\frac{4}{3 n}$, then the sectional curvature $\bar{K}$ is nonnegative.

Proof. We have

$$
\sum_{i} \alpha\left(t_{i}\right) t_{i}=\sum_{i} \frac{t_{i}}{1+t_{i}}<\frac{4}{3 \kappa} \quad \text { for all } t_{i}>0
$$

if and only if $0<\kappa<\frac{4}{3 n}$. Hence, by Corollary $3.6 \bar{K}\left(X^{h}, Y^{h}\right) \geq 0$ for $X, Y \in T_{x} M$ unit and orthogonal. Moreover, $g\left(X, u_{i}\right)^{2}+\left(\overline{Y, u_{i}}\right)^{2} \leq\left|u_{i}\right|^{2}$. Thus

$$
\bar{K}\left(X^{v, i}, Y^{v, i}\right) \geq \frac{-\left|u_{i}\right|^{4}+\left|u_{i}\right|^{4}+3\left|u_{i}\right|^{2}+3}{\left|u_{i}\right|^{2}\left(1+\left|u_{i}\right|^{2}\right)^{2}}=\frac{3}{\left|u_{i}\right|^{2}\left(1+\left|u_{i}\right|^{2}\right)}>0 .
$$

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[^1]:    Department of Mathematics and Computer Science, University of Łódź,
    ul. Banacha 22, 90-238 Łódź, Poland
    E-mail: kamiln@math.uni.lodz.pl

