Sayed Saber The $L^2\ \bar\partial\text{-}{\rm Cauchy\ problem\ on\ weakly\ }q\text{-pseudoconvex\ domains\ in\ Stein\ manifolds}$

Czechoslovak Mathematical Journal, Vol. 65 (2015), No. 3, 739-745

Persistent URL: http://dml.cz/dmlcz/144440

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THE $L^2 \overline{\partial}$ -CAUCHY PROBLEM ON WEAKLY q-PSEUDOCONVEX DOMAINS IN STEIN MANIFOLDS

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(Received June 24, 2014)

Abstract. Let X be a Stein manifold of complex dimension $n \ge 2$ and $\Omega \in X$ be a relatively compact domain with C^2 smooth boundary in X. Assume that Ω is a weakly *q*-pseudoconvex domain in X. The purpose of this paper is to establish sufficient conditions for the closed range of $\overline{\partial}$ on Ω . Moreover, we study the $\overline{\partial}$ -problem on Ω . Specifically, we use the modified weight function method to study the weighted $\overline{\partial}$ -problem with exact support in Ω . Our method relies on the L^2 -estimates by Hörmander (1965) and by Kohn (1973).

Keywords: $\overline{\partial}$ operator; $\overline{\partial}$ -Neumann operator; q-convex domain; Stein manifold MSC 2010: 32F10, 32W05

1. INTRODUCTION

The solution of the $\overline{\partial}$ -Neumann problem has many important applications in the theory of several complex variables and in partial differential equations, particulary in the study of the $\overline{\partial}$ -problem with exact support. On domains with certain geometric conditions on the boundary, the question of existence of a solution to the $\overline{\partial}$ -Neumann problem was settled through the works of Hörmander [10] and Kohn [11], [12]. In fact, Hörmander's results in [10] imply that there exists a bounded operator N on $L^2_{r,s}(\Omega)$, which inverts the complex Laplacian under the assumption that Ω is a bounded, pseudoconvex domain.

Following Hörmander [10], the $\overline{\partial}$ -problem can be solved in L^2 if $\overline{\partial}$ satisfies Z(q). As shown in Theorem 1.9.9 in [18], q-pseudoconvexity implies that for $L^2_{0,s+1}$ -forms fin the kernel of $\overline{\partial}$, there exists an $L^2_{0,s}$ -form u solving the $\overline{\partial}$ -problem $\overline{\partial}u = f$. It has been proved recently, by several authors including Harrington-Raich [8], that Nexists on q-forms in a q-pseudoconvex domain. Establishing the existence of the $\overline{\partial}$ -Neumann operator leads to a particular solution to the $\overline{\partial}$ -problem with support condition. Here, we are interested in the existence of such an L^2 -solution u for given data f. More precisely, we prove the following result:

Theorem 1.1. Let $\Omega \subseteq X$ be a weakly q-pseudoconvex domain with C^2 boundary $b\Omega$ in a Stein manifold X of complex dimension $n \ge 2$. For any $q \le s \le n$ and for $f \in L^2_{r,s}(\Omega)$, supp $f \subset \overline{\Omega}$, satisfying $\overline{\partial} f = 0$ in the distribution sense in X, there exists $u \in L^2_{r,s-1}(\Omega)$, supp $u \subset \overline{\Omega}$ such that $\overline{\partial} u = f$ in the distribution sense in X.

The $\overline{\partial}$ -problem with exact support was considered by Derridj [6], [7] using Carleman type estimates for smooth domains with plurisubharmonic defining functions. Shaw [17] has obtained a solution to this problem in a pseudoconvex domain Ω with C^1 boundary in \mathbb{C}^n . If Ω is locally Stein in the complex projective space, Cao-Shaw-Wang [2] obtained a solution to this problem in Ω .

Also, in the setting of strictly q-convex (or concave) domains, the $\overline{\partial}$ -problem with exact support has been studied by Sambou in his thesis, where he proves some Dolbeault isomorphism between the tangential Cauchy-Riemann cohomology groups of smooth forms and currents on hypersurfaces (see [16]). Abdelkader and Saber [1] studied this problem on strictly q-convex domains in a complex manifold. Saber [15] (respectively [14]) studied this problem on a weakly q-pseudoconvex domain with C^1 -smooth boundary (respectively with Lipschitz boundary) in \mathbb{C}^n .

2. NOTATION AND DEFINITIONS

Let X be a complex manifold of complex dimension n with a Hermitian metric g. Let $\Omega \in X$ be an open submanifold with smooth boundary $b\Omega$ and defining function ϱ . Denote by L_1, L_2, \ldots, L_n a C^{∞} special boundary coordinate chart in a small neighborhood U of some point $z_0 \in b\Omega$, i.e., $L_i \in T^{1,0}$ on $U \cap \overline{\Omega}$ with L_i tangential for $1 \leq i \leq n-1$ and $\langle L_i, L_j \rangle = \delta_{ij}$, where δ_{ij} is the Kronecker symbol. Denote $\overline{L}_1, \overline{L}_2, \ldots, \overline{L}_n$ the conjugate of L_1, L_2, \ldots, L_n , respectively; these form an orthonormal basis of $T^{1,0}$ on U. The dual basis of (1,0) forms are $\omega^1, \ldots, \omega^n = \sqrt{2}\partial \varrho$. The Levi form associated to ϱ is defined by

$$\varrho_{jk} = \langle L_j \wedge \overline{L}_k, \partial \overline{\partial} \varrho \rangle, \quad j, k = 1, 2, \dots, n-1.$$

Let $(\partial^2 \varrho(z)/\partial z_j \overline{\partial} z_k)_{j,k=1}^{n-1}$ be the matrix of the Levi form $\partial \overline{\partial} \varrho(z)$ in the complex tangential direction at z. Let $\lambda_1(z) \leq \ldots \leq \lambda_{n-1}(z)$ be the eigenvalues of $(\varrho_{jk}(z))_{j,k=1}^{n-1}$.

A complex-valued differential form u of type (r, s) on X can be expressed as $u = \sum_{I,J} u_{I,J} dz^I \wedge d\overline{z}^J$, where I and J are strictly increasing multi-indices with lengths r and s, respectively. Let $C_{r,s}^{\infty}(X)$ be the space of complex-valued differential

forms of class C^{∞} and of type (r, s) on X. For $u, v \in C^{\infty}_{r,s}(X)$, we define a local inner product (u, v) induced by the Hermitian metric by $(u, v) = \sum_{I \in I} u_{I,J} \overline{v}_{I,J}$.

The Hodge star operator \star is a linear map $\star: C^{\infty}_{r,s}(X) \to C^{\infty}_{n-s,n-r}(X)$ which satisfies $\overline{\star u} = \star \overline{u}$ (that is, \star is a real operator) and $\star \star u = (-1)^{r+s}u$; for the proof cf. [13], Theorem 2.1. Let $C^{\infty}_{0}(\Omega)$ be the space of C^{∞} -functions with compact support in Ω . Let $C^{\infty}_{r,s}(\overline{\Omega}) = \{u|_{\overline{\Omega}}; u \in C^{\infty}_{r,s}(X)\}$ be the subspace of $C^{\infty}_{r,s}(\Omega)$ whose elements can be extended smoothly up to the boundary $b\Omega$. Let $L^{2}_{r,s}(\Omega)$ be the space of (r, s)forms on Ω with square-integrable coefficients. If φ is a smooth function in Ω , the weighted L^{2} -inner product and norms are defined by

$$\langle u, v \rangle_{\varphi} = \int_{\Omega} (u, v) \mathrm{e}^{-\varphi} \, \mathrm{d}V \quad \mathrm{and} \quad \|u\|_{\varphi}^2 = \langle u, u \rangle_{\varphi},$$

where dV is the volume element. We write

$$d\varphi = \sum_{j=1}^{n} L_j(\varphi)\omega_j + \sum_{j=1}^{n} \bar{L}_j(\varphi)\overline{\omega}_j.$$

Then one defines

$$\partial \varphi = \sum_{j=1}^{n} L_j(\varphi) \omega_j$$
 and $\overline{\partial} \varphi = \sum_{j=1}^{n} \overline{L}_j(\varphi) \overline{\omega}_j.$

We denote by φ_{jk} the coefficients in $\partial \overline{\partial} \varphi = \sum_{jk} \varphi_{jk} \omega_j \wedge \overline{\omega}_k$, that is,

$$\varphi_{jk} = \langle L_j \wedge \overline{L}_k, \partial \overline{\partial} \varphi \rangle, \quad j, k = 1, 2, \dots, n.$$

The Cauchy-Riemann operator $\overline{\partial}: C^{\infty}_{r,s-1}(\Omega) \to C^{\infty}_{r,s}(\Omega)$ satisfies

(2.1)
$$\overline{\partial}u = \sum_{I,J} \sum_{k=1}^{n} \overline{L}_{k} u_{I\overline{J}} \overline{\omega}^{k} \wedge \omega^{I} \wedge \overline{\omega}^{J} + \dots,$$

where the dots refer to terms of order zero in u. Let $\mathcal{D}^{r,s}(U)$ be the space of (r,s)-forms u on U such that

(2.2)
$$u_{I,J} = 0 \text{ on } b\Omega \text{ when } n \in J.$$

Then, for forms $u \in \mathcal{D}^{r,s}(U)$, we have

(2.3)
$$\overline{\partial}_{\varphi}^{\star} u = (-1)^{r-1} \sum_{I,K} \sum_{j=1}^{n} \delta_{j}^{\varphi} u_{IjK} \omega^{I} \wedge \overline{\omega}^{K} + \dots,$$

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where $\delta_j^{\varphi} = e^{\varphi} L_j(e^{-\varphi})$ and the dots refer to terms of order zero in u. Let $\overline{\partial} : \operatorname{dom} \overline{\partial} \subset L^2_{r,s}(\Omega) \to L^2_{r,s+1}(\Omega)$ be the maximal closure of the Cauchy-Riemann operator and $\overline{\partial}_{\varphi}^*$ be its Hilbert space adjoint of $\overline{\partial}$. For $1 \leq s \leq n$, we denote by $\Box_{\varphi} = \overline{\partial}\overline{\partial}_{\varphi}^* + \overline{\partial}_{\varphi}^*\overline{\partial} : \operatorname{dom} \Box_{\varphi} \to L^2_{r,s}(\Omega)$ the Laplace-Beltrami operator, where $\operatorname{dom} \Box_{\varphi} = \{u \in \operatorname{dom} \overline{\partial} \cap \operatorname{dom} \overline{\partial}_{\varphi}^*; \overline{\partial} u \in \operatorname{dom} \overline{\partial}_{\varphi}^* \text{ and } \overline{\partial}_{\varphi}^* u \in \operatorname{dom} \overline{\partial}\}$. Thus

$$\mathcal{H}_{\varphi}(\Omega) = \{ u \in \operatorname{dom}(\Box_{\varphi}); \ \overline{\partial}u = \overline{\partial}_{\varphi}^* u = 0 \}.$$

Then $\mathcal{H}_{\varphi}(\Omega)$ is a closed subspace of dom (\Box_{φ}) since \Box_{φ} is a closed operator. One defines the $\overline{\partial}$ -Neumann operator $N_{\varphi} \colon L^2_{r,s}(\Omega) \to L^2_{r,s}(\Omega)$ as the inverse of the restriction of \Box_{φ} to $(\mathcal{H}_{\varphi}(\Omega))^{\perp}$.

Definition 2.1. We say that $u \in L^2_{r,s}(\Omega)$ is supported in $\overline{\Omega}$ (supp $u \subset \overline{\Omega}$) or u vanishes to infinite order at the boundary of Ω if u vanishes on $b\Omega$.

Definition 2.2 (Ho [9]). We say that Ω is weakly q-pseudoconvex domain $(q \ge 1)$ if at every point $x_0 \in b\Omega$ we have

$$\sum_{|K|} \sum_{j,k} \frac{\partial^2 \varrho}{\partial z_j \partial \overline{z}_k} u_{jK} \overline{u}_{kK} \ge 0 \quad \text{for every } (0,q) \text{-form } u = \sum_{|J|=q} u_J \, \mathrm{d}\overline{z}^J$$

such that
$$\sum_{j=1}^n (\partial \varrho / \partial z_j) u_{jK} = 0 \text{ for all } |K| = q - 1.$$

Definition 2.3. A complex manifold X is said to be a Stein manifold if there exists an exhaustion function $\mu \in C^2(X, \mathbb{R})$ such that $i\partial \overline{\partial} \mu > 0$ on X.

Remark 2.4. If we take $\varphi_t = t\mu$, $t \ge 0$ and use the notation $\|\cdot\|_t = \|\cdot\|_{\varphi_t}$, $\langle,\rangle_t = \langle,\rangle_{\varphi_t}$ and $\overline{\partial}_t^{\star} = \overline{\partial}_{\varphi_t}^{\star}$, $\Box_{\varphi_t} = \Box^t$, $N_{\varphi_t} = N^t$ and $\mathcal{H}_{\varphi_t}(\Omega) = \mathcal{H}_t(\Omega)$, it is known that dom $\overline{\partial}_t^{\star} = \text{dom } \overline{\partial}^{\star}$ (e.g., [3], Chapter 4). In that case $\langle f, g \rangle_t$ denotes $\langle f, g \rangle_{\varphi_t}$, that is, we use subscripts t instead of φ_t . The inner product $\langle f, g \rangle_t$ and the norm $\|f\|_t^2$, in $L^2_{p,q}(\Omega)$, are denoted by

$$\langle f,g \rangle_t = \int_{\Omega} f \wedge \star_t \overline{g} \quad \text{and} \quad \|f\|_t^2 = \langle f,f \rangle_t, \quad \text{where } \star_t = e^{-\varphi_t} \star = \star e^{-\varphi_t}.$$

Lemma 2.5. Let $\Omega \in X$ be a smooth domain in a Stein manifold X and ρ be its defining function. The following two conditions are equivalent:

- (i) Ω is weakly q-pseudoconvex.
- (ii) For any z ∈ bΩ the sum of any q eigenvalues ρ_{i1},..., ρ_{iq}, with distinct subscripts, of the Levi-form at z satisfies ∑^q_{i=1} ρ_{ij} ≥ 0.

3. Closed range for $\overline{\partial}$

The purpose of this section is to establish sufficient conditions for the closed range of $\overline{\partial}$ on not necessarily pseudoconvex domains (and their boundaries) in Stein manifolds.

Theorem 3.1 (cf. Zampieri [18]). Let $\Omega \in X$ be the same as in Theorem 1. If $\varphi_t = t\mu, t > 0$, for any (r, s)-form $u \in \text{dom }\overline{\partial} \cap \text{dom }\overline{\partial}_t^*, q \leq s \leq n$, we have

(3.1)
$$\|\overline{\partial}u\|_t^2 + \|\overline{\partial}_t^*u\|_t^2 \ge C_0 t \|u\|_t^2.$$

From (3.1), we get $\sqrt{t} ||u||_t \lesssim ||\Box^t u||_t$; thus \Box^t has closed range and there is well defined a continues inverse operator N_t . Moreover, $\overline{\partial}N_t$ and $\overline{\partial}^*N_t$ are also continuous. Finally, for $\overline{\partial}f = 0$ in degree $\ge q+1$, the form $u := \overline{\partial}^*N_t f$ is the $L^2(\Omega, \varphi_t)$ -canonical solution of the equation $\overline{\partial}u = f$, that is, the one orthogonal to ker $\overline{\partial}$. More precisely, we have the following theorem:

Theorem 3.2 (cf. Chen-Shaw [3], Demailly [4], [5]). Let $\Omega \in X$ be the same as in Theorem 1.1. For t sufficiently large, and for any $q \leq s \leq n$, we have the following:

- (1) $\mathcal{H}_t(\Omega)$ is finite dimensional,
- (2) the Laplace-Beltrami operator \Box^t has closed range in $L^2_{r,s}(\Omega)$,
- (3) the $\overline{\partial}$ -Neumann operator $N^t \colon L^2_{r,s}(\Omega) \to L^2_{r,s}(\Omega)$ exists and is bounded,
- (4) Ran $N^t \subset \operatorname{dom} \Box^t$, $N^t \Box^t = I$ on dom \Box^t ,
- (5) for $f \in L^2_{r,s}(\Omega)$, we have $f = \overline{\partial}\overline{\partial}^{\star}_t N^t f \oplus \overline{\partial}^{\star}_t \overline{\partial} N^t f$,
- $(6) \ \overline{\partial}N^t = N^t\overline{\partial}, \, q \leqslant s \leqslant n-1 \ \text{and} \ \overline{\partial}_t^{\star}N^t = N^t\overline{\partial}_t^{\star}, \, q+1 \leqslant s \leqslant n,$
- (7) the operator $\overline{\partial}$ has closed range in $L^2_{r,s}(\Omega)$ and $L^2_{r,s+1}(\Omega)$,
- (8) the operator $\overline{\partial}_t^{\star}$ has closed range in $L^2_{r,s}(\Omega)$ and $L^2_{r,s-1}(\Omega)$,
- (9) the canonical solution operators to $\overline{\partial}$ given by $\overline{\partial}_t^{\star} N^t \colon L^2_{r,s}(\Omega) \to L^2_{r,s-1}(\Omega)$ and $N^t \overline{\partial}_t^{\star} \colon L^2_{r,s+1}(\Omega) \to L^2_{r,s}(\Omega)$ are continuous,
- (10) the canonical solution operators to $\overline{\partial}_t^{\star}$ given by $\overline{\partial}N^t \colon L^2_{r,s}(\Omega) \to L^2_{r,s+1}(\Omega)$ and $N^t\overline{\partial} \colon L^2_{r,s-1}(\Omega) \to L^2_{r,s}(\Omega)$ are continuous,
- (11) for any $f \in L^2_{r,s}(\Omega)$, where $q \leq s \leq n$, such that $\overline{\partial} f = 0$ in Ω , there exists $u \in L^2_{r,s-1}(\Omega)$ satisfying $\overline{\partial} u = f$ with $||u||_t \leq ||f||_t$.

4. Proof of Theorem 1.1

Following Theorem 3.2, N^t exists for forms in $L^2_{n-r,n-s}(\Omega)$. Thus, we can define $u \in L^2_{r,s-1}(\Omega)$ by

(4.1)
$$u = -\star_{(t)} \overline{\overline{\partial}} N^t_{n-r,n-s} \star_{(-t)} \overline{\overline{f}}.$$

Thus supp $u \subset \overline{\Omega}$. Thus, u vanishes on $b\Omega$. Now, we extend u to X by defining u = 0 in $X \setminus \Omega$. We want to prove that the extended form u satisfies the equation $\overline{\partial}u = f$ in the distribution sense in X.

For $\eta \in L^2_{n-r,n-s-1}(\Omega) \cap \operatorname{dom} \overline{\partial}$, we have

$$\begin{split} \langle \overline{\partial}\eta, \star_{-t}f \rangle_{(t)\Omega} &= \int_{\Omega} \overline{\partial}\eta \wedge \star_t (\star_{-t}f) = (-1)^{r+s} \int_{\Omega} \overline{\partial}\eta \wedge f = (-1)^{(r+s)(r+s-1)} \int_{\Omega} f \wedge \overline{\partial}\eta \\ &= \int_{\Omega} f \wedge \overline{\partial}\eta = (-1)^{r+s} \langle f, \star_{-t} \overline{\partial}\eta \rangle_{(t)\Omega} = (-1)^{r+s} \langle f, \star_{-t} \overline{\partial}\eta \rangle_{(t)X}, \end{split}$$

because supp $f \subset \overline{\Omega}$. Since $\overline{\partial}_t^{\star} = e^{\varphi_t} \vartheta e^{-\varphi_t} = -\star_{-t} \overline{\partial} \star_t$ and $\vartheta|_{\Omega} = \overline{\partial}^{\star}|_{\Omega}$, when ϑ acts in the distribution sense (see [10]), we obtain

$$\langle \overline{\partial}\eta, \star_{-t}f \rangle_{(t)\Omega} = \langle f, \vartheta \star_{-t}\eta \rangle_{(t)X} = \langle \overline{\partial}f, \star_{-t}\eta \rangle_{(t)X} = 0.$$

It follows that $\overline{\partial}_t^{\star}(\star_{-t}f) = 0$ on Ω . Using Theorem 3.2, we have

(4.2)
$$\overline{\partial}_t^* N^t(\star_{(-t)} f) = N^t \overline{\partial}_t^*(\star_{(-t)} f) = 0.$$

Thus, from (4.1), and (4.2), we obtain

$$\overline{\partial}u = -\overline{\partial \star_t \overline{\partial}N^t_{n-r,n-s} \star_{-t} \overline{f}} = (-1)^{r+s+1} \overline{\star_t \star_{-t} \partial \star_t \overline{\partial}N^t_{n-r,n-s} \star_{-t} \overline{f}}$$
$$= (-1)^{r+s} \overline{\star_t \overline{\partial}^t_t \overline{\partial}N^t_{n-r,n-s} \star_{-t} \overline{f}} = (-1)^{r+s} \overline{\star_t (\overline{\partial}^t_t \overline{\partial} + \overline{\partial}\overline{\partial}^t_t) N^t_{n-r,n-s} \star_{-t} \overline{f}}$$
$$= (-1)^{r+s} \overline{\star_t \star_{-t} \overline{f}} = f$$

in the distribution sense in Ω . Since u = 0 in $X \setminus \Omega$, then for $v \in L^2_{r,s}(X) \cap \operatorname{dom} \overline{\partial}_t^*$, we obtain

$$\begin{split} \langle u, \overline{\partial}_t^{\star} v \rangle_{(t)X} &= \langle u, \overline{\partial}_t^{\star} v \rangle_{(t)\Omega} = \langle \star \overline{\partial}_t^{\star} v, \star_{-t} u \rangle_{(t)\Omega} = (-1)^{r+s} \langle \overline{\partial} \star_t v, \star_{-t} u \rangle_{(t)\Omega} \\ &= (-1)^{r+s} \langle \star v, \overline{\partial}^{\star} \star_{-t} u \rangle_{(t)\Omega} = \langle \star v, \star_{-t} \overline{\partial} u \rangle_{(t)\Omega} = \langle f, v \rangle_{(t)\Omega} = \langle f, v \rangle_{(t)X}, \end{split}$$

where the third equality holds since $\star_{-t} u \in \text{dom }\overline{\partial}_t^{\star}$. Thus $\overline{\partial} u = f$ in the distribution sense in X.

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Acknowledgement. I would like to thank Prof. Miroslav Engliš and the referee for their helpful comments and suggestions improving on an earlier version of this paper.

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