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ON A CLASS OF TOPOLOGICAL SPACES CONTAINING ALL BICOMPACT AND ALL CONNECTED SPACES 1)

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When comparing a class \mathscr{B} of bicompact spaces and a class \mathscr{C} of connected spaces, it is conspicuous that in spite of all their outward dissimilarity they have some common (more precisely-analogous) properties that moreover belong to the basic topological qualities of these classes. For example:

1) A product of topological spaces is bicompact (connected) iff every factor is bicompact (resp. connected).

2) An image of a bicompact (connected) space under a continuous mapping is bicompact (resp. connected).

3) Let \mathcal{FB} (\mathcal{FC}) be a collection of all closed mappings having the property that the preimage of every point is bicompact (resp. connected). Then a space X which is a preimage of a space $\mathbf{y} \in \mathcal{B}$ ($\mathbf{y} \in \mathcal{C}$) under a mapping $f \in \mathcal{FB}$ ($f \in \mathcal{FC}$) is also bicompact (resp. connected).

The aim of this paper is to define and to begin the study of a class of spaces (we call them cb-spaces or "clustered" spaces), containing all bicompact and all connected spaces, which possesses some properties common for \mathcal{B} and \mathcal{C} . For example, a product of topological spaces is a cb-space iff the same holds for every factor, a continuous image of a cb-space is a cb-space. Although the third property does not hold for cb-spaces to the full extent (see Example 7) there is a certain analogy of it (see Theorem 4, and also Theorem 5).

¹⁾ The detailed version of this paper is to be published in Utchenije Zapisky of the Latvian State University Issue "Topological spaces and their mappings" No 4 (1978).

§ 1. DEFINITION AND BASIC PROPERTIES OF cb-SPACES

<u>Definition</u>. A topological space X is called "clustered" or a cb-space if its every cover consisting of clopen sets (i.e. closed and open) has a finite subcover.

Further a cover consisting of clopen sets will be called a "clopen cover".

It is easy to see that bicompact spaces and also connected spaces are clustered (see Examples 1.2).

Taking into consideration the fact that a complement of a clopen set is again a clopen set one can easily prove the following

<u>Theorem 1.</u> A topological space X is a cb-space iff every centered system of its clopen subsets has a non-void intersection.

From Zorn's lemma one obtains that every centered system of clopen sets is contained in a (unique) maximal centered system of clopen sets. Calling maximal centered systems of clopen sets clopen ultrafilters one can get the following corollary from the previous theorem:

<u>Corollary</u> A topological space X is a cb-space iff every clopen ultrafilter converges in X.

Theorem 2. A clopen subset of a cb-space is again a cb-space. The proof is obvious.

<u>Theorem 3.</u> An image of a cb-space under a continuous mapping is a cb-space.

The proof can be easily obtained directly from the definition .

Corollary. A quotient of a cb-space is a cb-space.

<u>Theorem 4.</u> Let f be a clopen mapping ¹⁾ of a space X onto a cb-space Y. If the preimage of every point $y \in Y$ under f is clustered then X itself is a cb-space.

¹⁾ A mapping $f: X \rightarrow Y$ is called clopen if it maps every clopen set onto a clopen set.

<u>Proof:</u> Consider a family $\mathcal{U} = \{U_{\alpha}\}$ of clopen subsets in the space X having a void intersection. To prove the theorem it is necessary and sufficient to show that \mathcal{U} is not centered. Clearly, without a loss of generality one may consider that \mathcal{U} is closed under finite intersections.

Let us examine the family of clopen sets $f(U_{\alpha})$ in the space Y. First we show that $\cap f(U_{\alpha}) = \emptyset$. Really, if there exists a point y_0 in $\cap f(U_{\alpha})$ then $f^{-1}(y_0)$ would have a non-void intersection with every U_{α} and hence the family $\{f^{-1}(y_0) \cap U_{\alpha}\}$ is centered. Since $f^{-1}(y_0)$ is a cb-space, the intersection $\bigcap (f^{-1}(y_0) \cap U_{\alpha})$ is nonvoid and hence $\cap U_{\alpha} \neq \emptyset$ which contradicts our conditions. This contradiction implies that $\cap f(U_{\alpha}) = \emptyset$ and as Y is a cb-space, the family $\{f(U_{\alpha})\}$ cannot be centered. Find indexes α, \ldots, α_n such that $\bigcap f(U_{\alpha i}) = \emptyset$, then obviously $\bigcap U_{\alpha i} = \emptyset$ and so the family $U = \{U_{\alpha}\}$ is not centered. The theorem is proved.

Using similar ideas it is easy to prove the following proposition:

<u>Theorem 5.</u> Let f be a mapping of a space X onto a bicompact space Y, the preimage of every point $y \in Y$ under f being clustered. Then X is also a cb-space.

<u>Theorem 6.</u> Let X be a completely regular space and βX its Stone-Čech compactification. The space X is clustered iff its every cover consisting of clopen in βX subsets has a finite subcover.

The proof follows from the well-known fact (see e.g. [1]) that the closure of a clopen subset $A \subset X$ in the extension is clopen in it.

<u>Theorem 7.</u> A product of topological spaces is a cb-space iff all factors are cb-spaces.

<u>Proof:</u> If the product $X = \prod X_{\alpha}$ is a cb-space, then so is every factor X_{α} , because X_{α} is the image of X under corresponding projection $\mathcal{T}_{\alpha}: X \longrightarrow X_{\alpha}$ (see Theorem 3).

Conversely, if every X_{α} is clustered then the product $X = \prod X_{\alpha}$ is also a cb-space. This fact may be proved by virtue of a number of auxiliary propositions some of which we suppose to be of interest by themselves.

Lemma 1. Let Y be a cb-space, X -any topological space and π_{χ} : X×Y→X, π_{χ} : X×Y→Y - the corresponding projections. If π_{χ}

448

is a clopen mapping, then the mapping $\pi_{\mathbf{v}}$ is also clopen.

Using Lemma 1 it is easy to prove

Lemma 2. If X is bicompact and Y is a cb-space, then the projections π_v and π_v are clopen mappings.

Lemma 2 implies

Proposition 1. A projection along a cb-space is a clopen mapping.

This proposition in its turn allows us to prove

<u>Proposition 2.</u> The closure of a projection of a clopen subset of the product is a clopen subset in the corresponding factor.

Lemma 3. Let $z, c \in \pi X_{\alpha}$, moreover $z \notin W$ nad $c \in W$ where W is a clopen subset in the product. Then there exists a factor X_{α} and a clopen set $U_{\alpha} \subset X_{\alpha}$ such that $z \in \pi_{\alpha}^{-1}(U_{\alpha})$ but $c \notin \pi_{\alpha}^{-1}(U_{\alpha})$.

It is convenient to prove this lemma first for two factors, then to extend it to the finite case and finally to use Proposition 2 to prove the general case.

With the aid of Lemma 3 and Proposition 1 one can prove the following

Lemma 4. Let X,Y be cb-spaces, W- a clopen subset of the product X × Y and z- a point that does not belong to W. Then there exist clopen sets $U \subset X$, $V \subset Y$ such that $(U \times V) \cap W = \phi$ but $z \in U \times V$.

By Lemma 4 and Proposition 1 we may prove the following

Lemma 5. The product of two cb-spaces is a cb-space.

<u>Corollary.</u> The product of a finite number of cb-spaces is also a cb-space.

Further, using this corollary, Lemma 3 and Theorem 2, it is not difficult to prove

Lemma 6. If X1,X2,...,Xn are cb-spaces and W is a clopen

subset of the product $X = \pi X_i$ then there exist clopen sets $U_1 \subset X_1$ $U_2 \subset X_2, \ldots, U_n \subset X_n$ such that $z \in \pi U_i$ and $(\pi U_i) \cap W = \phi$.

Now, using Proposition 2, one may generalize Lemma 6 :

<u>Proposition 3.</u> Let X_{α} be a cb-space for every index $\alpha \in A$, W- a clopen subset in the product $X = \prod X_{\alpha}$ and $z \notin W$. Then there exists a clopen set $V \subset X$ such that $z \in V$, $V \cap W = \phi$ and, moreover, V is of the form $V = \prod U_{\alpha}$ where every U_{α} is a clopen subset of the corresponding factor X_{α} and $U_{\alpha} = X_{\alpha}$ for all but a finite number of indexes α .

Now we pass directly to the proof of Theorem 7. Let X_{α} be a cbspace and \mathcal{F} -a clopen ultrafilter in the product $X = \prod X_{\alpha}$. For every α consider a family of subsets $\mathcal{F}_{\alpha} = \{\overline{\pi_{\alpha}(U)} : U \in \mathcal{F}\}$. Every $\pi_{\alpha}(U)$ is a clopen subset of the corresponding factor (see Proposition 2), hence \mathcal{F}_{α} is a centered system of clopen subsets in a cb-space X_{α} and so the intersection $\cap \{\overline{\pi_{\alpha}(U)} : U \in \mathcal{F}\}$ is non-void.Taking a point $x_{\alpha} \in \cap \{\overline{\pi_{\alpha}(U)} : U \in \mathcal{F}\}$ for every α , consider a point $z = (\mathbf{x}_{\alpha})$ in the product $\prod X_{\alpha}$; we shall show that $z \in \cap \{U : U \in \mathcal{F}\}$.

Really, if $z \notin \cap \{ U : U \in \mathcal{F} \}$, then there exists a set $W \in \mathcal{F}$ that does not contain z. Using Proposition 3 we can find clopen sets $U_{\alpha_1} \subset X_{\alpha_2}, U_{\alpha_2} \subset X_{\alpha_2}, \ldots, U_{\alpha_n} \subset X_{\alpha_n}$ such that $z \in V$ and $V \cap W = \phi$ where $V = \prod U_{\alpha}$ and moreover $U_{\alpha} = X_{\alpha}$ for all α distinct from $\alpha_1, \ldots, \alpha_n$. Consider now the sets $V_{\alpha_1} = (X_{\alpha_1} \setminus U_{\alpha_1}) \times \prod X_{\alpha}$. It is easy to verify that $V_{\alpha_1} \cup \ldots \cup V_{\alpha_n} \cup V = X$ and as \mathcal{F} is a clopen ultrafilter at least one of the sets $V_{\alpha_1}, \ldots, V_{\alpha_n}, V$ must belong to \mathcal{F} . On the other hand directly from the definition of the point z it is clear that no set V_{α_1} may belong to \mathcal{F} , besides V does not belong to \mathcal{F} either because $W \in \mathcal{F}$ while $V \cap W = \phi$. This contradiction proves that z must belong to every $U \in \mathcal{F}$ and hence the clopen ultrafilter \mathcal{F} converges. Now, using the corollary of Theorem 1 we conclude that the product $X = \prod X_{\alpha}$. is a cb-space.

In such a way Theorem 7 is proved.

§ 2. EXAMPLES

Example 1. All bicompact spaces are, obviously, clustered.

Example 2. All connected spaces are clustered.

Really, the only non void clopen subset of a connected space X is the whole X itself.

More generally, it is easy to notice that a space that can be represented as a finite union of its connected subspaces is also clustered.

Example 3. From Theorem 7 it follows that a product of a bicompact space and a connected space is clustered.

<u>Example 4.</u> Consider a subspace L of a unit interval [0,1] defined by the equality $L = [0,1] \setminus \{\frac{1}{n}: n=1,2,...\}$. The space L is neither bicompact nor connected, but it is a cb-space.

Example 5. Modify the previous example taking for base on the set $[0,1]\setminus\{\frac{1}{n}: n = 1,2,...\}$ all sets open in L and also the sets of the form $V = \{0\} \cup (U(\frac{1}{n}, \frac{1}{n} + \varepsilon_n))$ where $0 < \varepsilon_n < \frac{4}{n^2}$ for every n. The space obtained in this way will be denoted by L'. It is easy to check that L' is a cb-space but it is neither bicompact nor connected. Moreover, the space L' is not first countable.

Example 6. According to Theorem 2 the property "to be clustered" is inherited by clopen sets. On the other hand, it is easy to notice, that closed sets do not inherit this property: the space N of natural numbers, being a closed subspace of the real line R, is not a cb-space.

It is natural, however, to ask a question about the heredity of the property "to be clustered" in the following refined form. Let X be a cb-space and Y its closed subspace. Can one affirm that every cover of Y by clopen in X sets has a finite subcover? The following example gives a negative answer to this question, too.

Consider a subspace X of the plane, defined by the equality $X = UX_n \cup \{b\}$ where every X_n is a set of points with the first coordinate equal to $\frac{1}{n}$ and the second belonging to the interval [0,1] and b is the point (0,1). It is not difficult to notice, that X is a cb-space -every clopen set, containing the point b must contain also almost all of X_n . Consider now the closed subspace $Y \in X$ defined by the equality $Y = \{(1,0), (\frac{1}{2}, 0), \dots, (\frac{1}{n}, 0), \dots\}$.

It is clear that the family $\{X_n\}$ is a clopen cover of Y, but one cannot find a finite subcover in it.

One can also construct examples which show that the property to be clustered is not inherited by open subspaces, either. Example 7. There exists a not clustered space X, which can be perfectly mapped onto a cb-space (even onto a connected space).

For such a space X one can take a subspace of the plane, defined by the equality $X = UX_n$ where $X_n = (n, [0,1])$ for all $n = 0, \pm 1, \pm 2, \ldots$. Obviously, the space X is not clustered. On the other hand, let a mapping f from X onto R be defined by the formula f(n,x) = n + xfor every point $(n,x) \in X$. It is clear that the mapping f is perfect (the preimage of every point $r \in R$ consists of either one or two points).

The same example shows us also that a space X which is not clustered may have for its quotient a connected space even in the case when all the equivalence classes are finite.

LITERATURE

[1] R.Engelking: Outline of General Topology.