Miloš Zahradník A note on the nonexistence of the Feynman integral

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Fifth winter school

<u>A note on the nonexistence of the Feynman integral</u> Miloš Zahradník

There is the following well known difficulty in the theory of Feynman integral: no measure can be related on $\mathbb{R}^{\langle 0,1 \rangle}$ to the formal expression $e^{i \int_{0}^{s} [\mathbf{x}'(t)]^{2}} dt \not (\mathbf{x})$, contrary to the case when the formal expression $e^{-\int_{0}^{s} [\mathbf{x}'(t)]^{2}} dt \not (\mathbf{x})$ leads to the well defined Wiener measure. This was first pointed out by Gelfand and Cameron. The same difficulty arises in the case of the operator valued Feynman integral, introduced by Cameron and Storvick. <u>Definition</u>. A dynamical system $T = \{T_{g}^{t}, 0 \leq g \leq t \leq 1\}$ on $L^{p}(\mathbf{X}, \mu)$ is a family of bounded operators on L^{p} satisfying

(1) $T_t^u \circ T_g^t = T_g^u$, T_t^t = identity (2) $T_t^{(\cdot)}$, $T_{(\cdot)}^t$ are Borel measurable operatorvalued functions.

For any dynamical system T we can construct the "dynamical operatorvalued Feynman integral" $\overrightarrow{\mu_{T}}$, defined for each $0 = t_0 \leq t_1 \leq \ldots \leq t_n = 1$ and each rectangle $A = A_0 \times A_1 \times \cdots \times A_n \subset \mathbb{X}^{\{t_0, t_1, \ldots, t_m\}} \times \mathbb{X}^{(0,1)}$ with A_1 Borel by $\overrightarrow{\mu_{T}}(A) = I_{A_n} \circ T_{t_{n-1}}^{t_n} \circ \cdots T_{t_0}^{t_4} \circ I_{A_0}$

where $I_{A_{\underline{i}}}$ denotes the operator of multiplying by $\mathcal{X}_{A_{\underline{i}}}$. Examples: 1) The "Feynman" dynamical system defined by the semigroup of operators on $L^2(\mathbb{R})$ related to the Schrödinger equation $\frac{\partial}{\partial \varphi} = \varphi = i\Delta \varphi - U \cdot \varphi$ 120

2) The "Wiener" dynamical system, related to the equation $\frac{\partial}{\partial t} \varphi = \Delta \varphi$ It is the aim of this note to investigate the question, when $\mathcal{A}_{\mathbf{T}}$ extents to a vector measure (with values in $L(L^p, L^p) - the space of bounded operators on <math>L^p$). The results are the following: <u>Definition 1</u>. Let $\mathbf{T} \in (L^p, L^p)$. Consider L^p with its natural norm and lattice structure. If $\varphi \ge 0$, put $|\mathbf{T}| \ \varphi = \sup \qquad \sum |\mathbf{T} \ \varphi_n|$ $\qquad \qquad \sum \ \varphi_n = \varphi \\ 0 \le \ \varphi_n$ iff it exists in L^p . For an arbitrary $\ \varphi \in L^p$, put $|\mathbf{T}| \ \varphi = |\mathbf{T}| \ \varphi^+ - |\mathbf{T}| \ \varphi^-$ whenever it is defined.

Clearly T is a linear operator (the absolute value of T). As it will be shown, it often happens that $\mathcal{O}(|T| = \{0\})$. <u>Theorem 1</u>. Consider the space L (L^P, L^P) with its strong operator topology. If $T \in L(L^P, L^P)$, define $\overrightarrow{\mathcal{A}_T}$ (the "operator integral" on X x X) on Borel rectangles by

 $\mathcal{U}_{T} (A \times B) = I_{B} \circ T \circ I_{A} \quad .$ Then \mathcal{U}_{T} can be extended to a vector measure on Borel subsets of X x X iff |T| is a bounded operator. Moreover, then there is a Borel measurable function G with |G| = 1 such that

Now we give the extension of Theorem 1 for dynamical systems: <u>Definition 2</u>. Let T be a dynamical system. Let each $|T_s^t|$ be bounded and let for each s < t $\{|T_{t_n}^t| \circ \cdots \circ |T_s^{t_1}|, s \le t_1 \le \cdots \le t_n \le t\}$ be bounded in L (L^p, L^p) . We can define

 $|T|_{g}^{t} = \sup |T_{t_{n}}^{t}| \circ \dots \circ |T_{g}^{t_{1}}| \circ \text{ for each } \varphi \geq 0.$ It can be checked that $|T| \stackrel{\text{def}}{=} \{|T|_{g}^{t}\}$ (the absolute value of T) is a dynamical system. Consider also the "truncated dynamical systems" ${}_{g}^{t}$ defined by: ${}_{g}^{t}T_{g}^{t'} = T_{g}^{t'}$, whenever $s', t' \leq s$ and $s', t' \geq t$,

 $t_{s}t'_{s} = Id$ whenever $s \leq s, t' \geq t$.

Now, the main result says:

<u>Theorem 2</u>. All dynamical integrals \mathcal{U}_{t_T} extend to a vector measure on Borel subsets of $X^{(0,1)}$ iff |T| exists. Moreover, then there is a Borel measurable function G on $X^{(0,1)}$ with |G| = 1 such that $\mathcal{U}_T = G$. $\mathcal{U}_{|T|}$. <u>Examples</u>. Let T be an operator on L^p (m) (m-Lebesgue) measure invariant with respect to shipts.

Then |T| exists iff T can be expressed by a convolution with a finite measure.

If $T = \{T_s^t\}$ is a dynamical system defined by a semigroup, invariant with respect to shifts, then if |T| exists, then each $|T|_0^t$ can be expressed by a convolution with $e^{\ll t} \cdot u_t$ where u_t is an infinite divisible probability. Thus we see the striking difference between the Wiener and Feynman dynamical system.

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