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In: Jaroslav Kurzweil (ed.): Equadiff 7, Proceedings of the 7th Czechoslovak Conference on Differential Equations and Their Applications held in Prague, 1989. BSB B.G. Teubner Verlagsgesellschaft, Leipzig, 1990. Teubner-Texte zur Mathematik, Bd. 118. pp. 135--138.

Persistent URL: http://dml.cz/dmlcz/702390

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SUBHARMONIC **BIFURCATION** IN EQUIVARIANT SYSTEMS

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1. <u>INTRODUCTION</u>. We know from equivariant bifurcation theory (see e.g. [4] or [6]) that the presence of symmetry can considerably change the typical bifurcation behaviour of a system. In this note we discuss a problem - namely subharmonic bifurcation - where the presence of symmetry not only leads to different answers, but forces us even to ask different cuestions. Consider the differential equation

$$\mathbf{x} = \mathbf{f}(\mathbf{x}, \lambda) , \qquad (1)$$

with $x \in \mathbb{R}^n$, $\lambda \in \mathbb{R}^k$ (the parameter space), and $f : \mathbb{R}^n \times \mathbb{R}^k \to \mathbb{R}^n$ smooth. Suppose that (1) has for $\lambda=0$ a periodic solution $x_0(t)$, with minimal period $T_0>0$. The problem of subharmonic bifurcation is then the following : describe, for some given $q \ge 2$ and for all λ near zero, all periodic solutions of (1) with minimal period near qT_0 and with orbit nearby $\kappa_0 := \{x_0(t) \mid t \in \mathbb{R}\}$. Such solutions can be found in all neighborhoods of κ_0 only if $x_0(t)$ has some Floquet multiplier μ with $\mu^q = 1$ and $\mu^{q'} \ne 1$ for q' < q. Generically period-doubling (i.e. the case q=2) can happen in one-parameter problems (k=1), while subharmonic bifurcation with $q\ge 3$ requires two parameters (k=2) and leads to so-called Arnol'd tongues; these are thin horn-like regions in parameter space corresponding to parameter values for which (1) has a subharmonic solution. The standard method to study subharmonic bifurcation consists in finding q-periodic points of a Poincaré map associated to $x_0(t)$ (see [1]). Now suppose that our system (1) is symmetric, i.e. there exists a compact group

Now suppose that our system (1) is symmetric, i.e. there exists a compact group $\Gamma \subset L(\mathbb{R}^n)$ such that

 $f(\gamma x, \lambda) = \gamma f(x, \lambda)$, $\forall \gamma \in \Gamma$; (2)

we also say that (1) is Γ -equivariant. Without loss of generality we may assume that $\Gamma \subset O(n)$; moreover, Γ forms a Lie group, and we will denote by $L(\Gamma)$ its Lie algebra, i.e. the tangent space to Γ at the identity. An immediate consequence of (2) is that instead of just a periodic orbit κ_0 we now have a compact invariant manifold

$$M_0 := \{\gamma x_0(t) \mid t \in \mathbb{R}, \gamma \in \Gamma\}, \qquad (3)$$

foliated with periodic orbits of $(1)_{\lambda=0}$; this manifold is invariant under both the flow and the group action. It is then clear that the questions we should ask are the following :

- (i) can we continue the manifold M_0 , i.e. does there exist a family of compact manifolds M_{λ} , depending in some sense smoothly on λ , coinciding with M_0 for $\lambda=0$, and such that M_{λ} is invariant under the group action of Γ and under the flow of (1),?
- (ii) are there bifurcations of such manifolds?
- (iii) if there are bifurcations, how does the dimension of the manifolds and the flow on them change?

The following (intuitive) example shows that this is not the same as asking for the continuation and the bifurcations of the periodic orbit κ_0 .

Suppose $\Gamma \cong SO(2)$ and $f(\mathbf{x}, \lambda) = f_0(\mathbf{x}) + \lambda f_t(\mathbf{x})$, where f_0 and f_t are Γ -equivariant, and such that $f_t(\mathbf{x})$ is for each $\mathbf{x} \in \mathbb{R}^n$ tangent to the group orbit $\Gamma \mathbf{x}$. Suppose f_0 has a periodic orbit κ_0 such that M_0 is a 2-torus. Then M_0 is still invariant for $\lambda \neq 0$, but the orbits of f_{λ} on M_0 will either not be periodic at all, or periodic with a very large period (if λ is small). We see that although we can continue the manifold M_0 , we cannot continue the periodic orbit κ_0 .

2. <u>A POINCARE MAP</u>. We will now combine some ideas of Chossat and Golubitsky [2] with a construction introduced by Fiedler [3] to obtain a Poincaré map which forms the basic tool for studying the bifurcation problem described above. This Poincaré map will reflect the symmetry of the periodic orbit κ_0 , which we can describe as follows (see [3]).

We call

$$H_{0} := \{ \gamma \in \Gamma | \gamma(\kappa_{0}) = \kappa_{0} \}$$

$$\tag{4}$$

the orbital symmetry of κ_0 , and

$$K_0 := \{ \gamma \in \Gamma \mid \gamma \overline{x_0} = \overline{x_0} \}$$
(5)

the spatial symmetry of κ_0 . In (5) $\overline{x_0}$ is any point of κ_0 ; the definition is independent of the choice of $\overline{x_0} \in \kappa_0$. It is easy to see that K_0 is a normal subgroup of H_0 , and that H_0/K_0 is cyclic, i.e. we have either $H_0/K_0 \cong S^1$ or $H_0/K_0 \cong \mathbb{Z}_m$ for some m≥1. If $H_0/K_0 \cong S^1$ then we say that κ_0 corresponds to a *notating wave* solution; in that case M_0 consists of just one single group orbit, i.e. $M_0 = \Gamma \overline{x_0}$, and we say that $\overline{x_0}$ is a relative equilibrium. For more information on this case we refer to recent work of Krupa [5] (see also [7]). Here we will restrict to the case where $H_0/K_0 \cong \mathbb{Z}_m$ for some m≥1; we put $\overline{x_0} := x_0(0)$, and we fix $\delta \in H_0$ such that $x_0(t+T_0/m) = \delta x_0(t)$. We have then $K_0 = \operatorname{Fix}(\overline{x_0})$, $\delta \kappa_0 \delta^{-1} = K_0$ and $\delta^m \in K_0$. The tangent space at $\overline{x_0}$ to M_0 is given by

$$T_{\overline{x}_{0}}M_{0} = \operatorname{span}\{\dot{x}_{0}(0)\} \oplus \{\eta \overline{x}_{0} \mid \eta \in L(\Gamma)\}.$$
(6)

We define $Y_0 := (T_{\overline{x}_0}M_0)^{\perp}$ and $S_0 := \{\overline{x}_0 + y_0 \mid y_0 \in Y_0\}$. Remark that $T_{\overline{x}_0}M_0$, Y_0 and S_0 are invariant under K_0 . When we start at a point $x = \overline{x}_0 + y_0 \in S_0$ $(y_0 \in Y_0)$

sufficiently close to $\overline{x_0}$ then the flow $\phi(t;x,\lambda)$ of (1) will in general not intersect S_0 after some time near T_0 , but it will intersect S_0 modulo a symmetry operator, i.e. it will intersect ΓS_0 . This is the basic idea behind the K_0 -equivariant Poincaré map Π : $Y_0 \times \mathbb{R}^k \to Y_0$ which we construct as follows. The group Γ acts on $L(\Gamma)$ via the adjoint action $(\gamma, \eta) \leftrightarrow \gamma \eta \gamma^{-1}$; using this action we

see that $L(K_0)$ is K_0 -invariant, and hence there exists a K_0 -invariant subspace U of $L(\Gamma)$ such that $L(\Gamma) = L(K_0) \oplus U$. A simple application of the implicit function theorem then shows that for each sufficiently small $(y_0, \lambda) \in Y_0 \times \mathbb{R}^k$ there exists a unique $(\tau, \eta) = (\tilde{\tau}(y_0, \lambda), \tilde{\eta}(y_0, \lambda)) \in \mathbb{R} \times U$ near $(T_0, 0)$ such that $e^{-\eta} \phi(\tau; \overline{x_0} + y_0, \lambda) \in S_0$. We define then

$$\Pi(\mathbf{y}_{0},\boldsymbol{\lambda}) := e^{-\overline{\eta}(\mathbf{y}_{0},\boldsymbol{\lambda})} \phi(\widetilde{\tau}(\mathbf{y}_{0},\boldsymbol{\lambda}),\mathbf{y}_{0},\boldsymbol{\lambda}) - \overline{\mathbf{x}}_{0} ; \qquad (7)$$

It is easy to check that for each $\sigma \in K_{\Omega}$ we have

$$\tilde{\tau}(\sigma y_0, \lambda) = \tilde{\tau}(y_0, \lambda) , \tilde{\eta}(\sigma y_0, \lambda) = \sigma \tilde{\eta}(y_0, \lambda) \sigma^{-1}$$

and $\Pi(\sigma y_0, \lambda) = \sigma \Pi(y_0, \lambda) ,$ (8)

i.e. If is K_0 -equivariant. We have $\Pi(0,0) = 0$, and the eigenvalues of $D_1 \Pi(0,0)$ will be the Floquet multipliers of $x_0(t)$ which are not forced to be 1 by the flow and the symmetry. For example, if the multiplicity of 1 as a multiplier of $x_0(t)$ equals dim $T_{\overline{x}_0} M_0 = 1 + \dim U$, then 1 will not be an eigenvalue of $D_1 \Pi(0,0)$ and Π will have for each sufficiently small λ a unique K_0 -invariant fixed point $\overline{y}_0(\lambda)$, corresponding to a continuation of M_0 .

When m>l then II has a more detailed structure which not only reflects the spatial symmetry K_0 but also the orbital symmetry H_0 of κ_0 . To see this we set $Y_j := \delta^j(Y_0)$ and $S_j := \delta^j(S_0)$ for $j = 0, 1, \ldots, m$. Each of the Y_j and S_j is K_0 -invariant, since $\delta K_0 \delta^{-1} = K_0$, while $Y_m = Y_0$ and $S_m = S_0$, since $\delta^m \in K_0$. In a similar way as above one defines then K_0 -equivariant mappings $\hat{\Pi}_j : Y_j \times \mathbb{R}^k \to Y_{j+1}$ (j=0,1,...,m-1), corresponding to "partial" Poincaré maps. One can then easily check (see [3]) that $\hat{\Pi}_{j+1} = \delta \hat{\Pi}_i \delta^{-1}$, and when we define $\Pi_0 : Y_0 \times \mathbb{R}^k \to Y_0$ by $\Pi_0 := \delta^{-1} \hat{\Pi}_0$, then

$$\Pi = \delta^{m} \Pi_{0}^{m} .$$
⁽⁹⁾

The mapping Π_0 is not K_0 -equivariant in the strict sense, but satisfies

$$\Pi_{0}(\sigma y_{0}, \lambda) = (\delta^{-1}\sigma\delta)\Pi_{0}(y_{0}, \lambda) , \quad \forall \sigma \in K_{0} .$$
(10)

That means : Π_0 is equivariant with respect to two different actions of K_0 ; it is however important to notice that the orbits of both actions coincide. The bifurcation problem described in the introduction now reduces to the following : study the bifurcations from {0} of compact manifolds in Y_0 which are invariant under Π (or Π_0) and under the group action of K_0 . Subharmonic bifurcation means in this context the bifurcation from {0} of K_0 -orbits which are invariant under some q-th iterate of Π . For example, if M_0 is a torus and q=2, then such bifurcation would correspond to a "torus-doubling". In general the flow on the bifurcating invariant manifolds will not be periodic, but quasi-periodic; therefore we should rather talk about quasi-subharmonic bifurcation.

In certain cases one can obtain sufficient conditions for such bifurcations by considering points with certain isotropy properties (see [2]). For example, if m=1 and the multiplier 1 of κ_0 has minimal multiplicity (given by 1 + dim U), then $\Pi=\Pi_0$ (we take $\delta=Id$), and we may without loss of generality assume that $\Pi(0,\lambda)=0$ for all λ . Modulo some generically satisfied transversality conditions one has then the following :

- (i) if -1 is a K_0 -simple multiplier of κ_0 (see [4] for the definition), with eigenspace Z, and if k=1, then there corresponds a quasi-period-doubling to each isotropy subgroup Σ of K_0 such that dim $Z^{\Sigma} = 1$;
- (ii) let $\mu \in \mathbb{C}$ be a K₀-simple multiplier of κ_0 such that $\mu^q=1$ for some $q \ge 3$; on the corresponding (complex) eigenspace Z we define an action of K₀× \mathbb{Z}_q by

$$(\sigma,j).z = \mu^{J}\sigma.z$$
, $\forall (\sigma,j) \in K_{0} \times \mathbb{Z}_{\sigma}$; (11)

(we take $\mathbb{Z}_q := \mathbb{Z}/q\mathbb{Z}$); if k=2 then there corresponds a quasi-q-harmonic bifurcation to each isotropy subgroup Σ of $K_0 \times \mathbb{Z}_q$ such that $\dim_{\mathbb{C}} \mathbb{Z}^{\Sigma} = 1$; to each such bifurcation there corresponds an Arnol'd tongue in parameter space.

We will give more details and examples in a forthcoming paper.

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